

	Figure 1	Figure 2	Delay between 1PPS output
			and 1PPS input
Befor operation	28.17 ns	265.41 ns	237.24 ns
After operation	137.31 ns	374.66 ns	237.35 ns

Table 1:Result of measurement described in Annex B3

NIM.serial - RxControl	talo					<u>- ×</u>
He cogging view sectings floors in	Help 829 🐂 📾 🔍 829 🚟 H 🖌 V					
Paritian information (WGS84)						
$\phi = N 039^{\circ} 57' 49.1354''$						
λ = E 116° 24'47.9525″						
h = 57.011m						
Satellite status (Track 8 PVI R×	Control Data Logger				×	
GPS SBAS	Global Timing SEE MEA FTP	GGTTS				
G01 G02 G03 G04	Receiver:	SEPT POLARX2 v3.2.0 SN:3	135			
G11 G12 G13 G14	Number of Channels:	16				
G21 G22 G23 G24 1	Comments:	RxControl Auto-Generated	File			
G31 G32	-Laboratory and Referenc	e				
	Laboratory:	NIM				
	Reference:	UTC (NIM)				
	⊤Delav/Time calibration-		Revision Date	1		
	Int Delay P1 XR+XS:	209.2		Aug-2009		
	Int Delay P2 XR+XS:	209.2	Antenna True Po	sition		
	Ant Cab Dalarri	152 1	Set True Ante	enna Position		
	Clash Cab Delay.	2/21				
	CIOCK CAD DELAY AFTAU.	242.1				
	Leap Second:					
	c	lose Stop Logging	🕐 Help			
<u> </u>			2.1			
Time DOP (PL/RAI	M) Information		CD11 OW			
02:09:36.0 (JTC) TDOP = 0.95	2 mask 15 5 Uptime 15d		00:42			
1564/180591.0 HDOP = 0.96	6 COM2		409 Bps			
+0.000ms -0.000 µ s/s VDOP = 1.55	5 Base					
Cmd SBF MHEA SBAS	DICO SEvat				5	
					MPR EXT_R	EF PPS_IN
第开始 6 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	。定时上传程序 · BWindows	任务管理器 🕀 NIM.seria	l - RxControl	NIM.serial - Status	🌾 💽 🔮 🗘 🐯 대 🚅 🔳	10:09
	Fig	ure 2 N	VIM PolarX2	2 receiver delay	setup	

NIM PolarX2 receiver has two serial port. One port is used to collect data and generate CGGTTS file. During TAIPPP calibration period, this port still works. Figure 2 shows screenshot of actual setup. I don't wether it would effect the calibration result or not, so provide to you.



Figure 3 BIPM GTR50 set-up figure

	Х	Y	Z
GTR50	-2177653.54	4384314.12	4074929.45
PolarX2	-2177661.82	4384311.73	4074929.43