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Time and Frequency Division
National Institute of Standards and Technology
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NIST

Report of Calibration: Cal_Id:1015-2023

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Abstract

This report is a record of the calibration results of three receivers: NRC4, NRCC, and NRC6 at NRC, Canada, performed via the NIST traveling receiver NB05 during the trip from NIST, Boulder to Canada and back. Three sets of data were collected between MJD60101 and MJD60162 (June 06, 2023, and August 08, 20223) by simultaneous operation of co-located GNSS receivers and the traveling receiver NB05. The purpose of this campaign was to measure the internal delay of the local(visited) receivers and thereby calibrate the links comprising NIST and the visited laboratories for time transfer applications using L1, L2, C1 GPS signals, and E1, E5a Galileo signals. The calibration campaign was initiated by NIST in consultation with the visited laboratories as per the guidelines set by BIPM [1].

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1 DESCRIPTION OF THE TRAVELING GNSS RECEIVER

The NIST Traveling System consists of Septentrio PolaRx5TR GNSS receiver unit (NB05), a Septentrio PolaNt-x MF.v2 antenna, an antenna cable (LMR 400), a laptop, a time interval counter (TIC) and two auxiliary cables (RG223 with BNC connectors) to be used for measuring the REF DLY for the traveling receiver. An HP53132A time interval counter is provided for measuring REF DLY. For more information, please refer to the NIST traveling receiver operator’s manual.

2 COMPUTING DELAYS IN THE MEASUREMENT SETUP

The difference in the total delay for a pair of co-located receivers is the sum of the delays incurred in the antenna cable(CABDLY) and the internal delay(INTDLY), minus the time offset at the latching point of the receiver as referenced to a fixed point, usually UTC(k)(REFDLY). The internal delay is comprised of both code- and frequency-dependent delays in the antenna and the receiver. After accounting for the baseline geometry, the difference in pseudoranges between a pair of receivers, say for P1, is given by

$$\text{RAWDIF}(P1)_{A-B} = \Delta\text{CABDLY}_{A-B} + \Delta\text{INTDLY}_{A-B} - \Delta\text{REFDLY}_{A-B}, \quad (1)$$

where $\text{RAWDIF}(P1)_{A-B}$ is the raw difference of pseudorange measurements of two receivers. Similarly for C1 and P2, $\text{RAWDIF}(C1/P2)_{A-B}$ is given by using the corresponding set of delays on the right-hand side of Eq.(1). The notation for the receivers A and B corresponds to the traveling- and station-receiver. $\Delta\text{CABDLY}_{A-B}$ and $\Delta\text{REFDLY}_{A-B}$ for NB05(A) and labv/NIST(B) are given in Table 1, referenced from Annexes—at the end of this report. We will refer to the visited laboratory receiver as labv. NISX and NB05 are NIST station- and traveling-receivers respectively. In this calibration campaign, we calibrate a total of three receivers in the visited laboratories. The procedure for measuring NB05 REF DLY (both X_P and X_O) is outlined in the operating manual. The visited laboratories are responsible for the REF DLY and CABDLY values for their station receivers.

Table 1: REF DLY and CABDLY and their differences between traveling and station receivers

Pair	MJD	REF _{DLY} (NB05)	REF _{DLY} (labv)	CAB _{DLY} (NB05)	CAB _{DLY} (labv)	Δ REF _{DLY} (ns)	Δ CAB _{DLY} (ns)
NB05-NISX	60101-60107	469.7	121.6	328.6	275.5	348.07	53.1
NB05-NRC4	60133-60137	64.1	228.81	328.6	269.26	-164.7	59.34
NB05-NRCC		64.1	58.65	328.6	314.94	5.45	13.66
NB05-NRC6	60145-60149	54.2	49.99	328.6	37.63	4.17	290.97
NB05-NISX	60157-60162	469.7	121.6	328.6	275.5	348.07	53.1

3 COMPUTING RAW DIFFERENCE OF PSUEDORANGES

The RINEX files for a pair of co-located receivers during the data acquisition period, MJD column in Table 1, are processed using *dchrinex* software provided by the BIPM that solves for the baseline between the phase centers of the two antennas from L1 and L2 phase differences [3, 4]. Subsequently, the P1 and P2 pseudorange differences are formed after accounting for the baseline. The results with the average values of RAWDIF are given in Table 2. The values for Δ INTDLY between a given pair of receivers are computed using Eq.(1) and are given in Table 3. NB05 and NISX are operated in auto compensation OFF mode.

Table 2: Computed raw differences: P1, P2, C1, E1, and E5.

Pair	RAWDIF(P1)	RAWDIF(P2)	RAWDIF(C1)	RAWDIF(E1)	RAWDIF(E5)
			(ns)		
NB05-NISX	-292.54	-296.346	-292.657	-292.635	-297.19
NB05-NRC4	193.637	183.547	194.384	194.506	186.876
NB05-NRCC	6.581	5.242	6.535	6.613	5.023
NB05-NRC6	285.071	280.632	284.873	284.989	283.734
NB05-NISX	-292.59	-296.703	-292.725	-292.681	-297.245

Table 3: INTDLY difference: traveling and station receivers.

Pair	Δ INTDLY(P1)	Δ INTDLY(P2)	Δ INTDLY(C1)	Δ INTDLY(E1)	Δ INTDLY(E5)
			(ns)		
NB05-NISX	2.43	-1.376	2.313	2.335	-2.22
NB05-NRC4	-30.413	-40.503	-29.666	-29.544	-37.174
NB05-NRCC	-1.629	-2.968	-1.675	-1.597	-3.187
NB05-NRC6	-1.729	-6.168	-1.927	-1.811	-3.066
NB05-NISX	2.38	-1.733	2.245	2.289	-2.275

4 INTDLY AND UNCERTAINTY ESTIMATES

Systematic and statistical uncertainties are assigned as given in Table 4. Misclosure is inferred from Table 2 and RAWDIF uncertainties for labv are from time deviation (TDEV), see attached plots at the end of this report. All other uncertainties are fixed values. The combined uncertainty given in Table 5 is obtained by combining uncorrelated (assumed) uncertainties in quadrature. The most recent G1 calibration results for NISX delays should be available from BIPM.

Table 4: Uncertainty assigned for each station

quantity	unc type	NRC4 (ns)	NRCC (ns)	NRC6 (ns)
RAWDIF (P1) _{NB05-labv}	u_a	0.015	0.009	0.036
RAWDIF (P2) _{NB05-labv}	u_a	0.015	0.02	0.025
RAWDIF (C1) _{NB05-labv}	u_a	0.018	0.011	0.02
RAWDIF (E1) _{NB05-labv}	u_a	0.027	0.054	0.069
RAWDIF (E5) _{NB05-labv}	u_a	0.032	0.059	0.049
NB05 antenna position	$u_{b,11}$		0.05	
labv antenna position	$u_{b,12}$		0.05	
NB05 multipath	$u_{b,13}$		0.20	
labv multipath	$u_{b,14}$		0.20	
REFDLY _{NB05}	$u_{b,21}$		0.15	
REFDLY _{labv}	$u_{b,22}$		0.15	
CABDLY _{NB05}	$u_{b,31}$		0.15	
CABDLY _{labv}	$u_{b,32}$		0.15	
Misclosure(P1)	$u_{b,1}$		0.025	
Misclosure(P2)	$u_{b,1}$		0.1785	
Misclosure(C1)	$u_{b,1}$		0.034	
Misclosure(E1)	$u_{b,1}$		0.023	
Misclosure(E5)	$u_{b,1}$		0.0275	

Table 5: INTDLY difference: station receivers.

Pair	INTDLY(P1)	INTDLY(P2)	INTDLY(C1) (ns)	INTDLY(E1)	INTDLY(E5)
NRC4(PR _x 4)-NISX	32.81(45)	38.94(45)	31.94(45)	31.85(45)	34.92(45)
NRCC(PR _x 5)-NISX	4.03(45)	1.41(45)	3.95(45)	3.90(46)	0.93(46)
NRC6(PR _x 5)-NISX	4.13(45)	4.61(45)	4.20(45)	4.12(46)	0.81(46)

5 SECONDARY INFORMATION

1. RAWDIF and TDev plots: Attached separately.
2. AnnexA: Attached separately.

References

- [1] <ftp://ftp2.bipm.org/pub/tai/publication/gnss-calibration/guidelines/>
- [2] <ftp://ftp2.bipm.org/pub/tai/publication/gnss-calibration/group1/1001-2018/1001-2020-phase3-report.pdf>
- [3] <ftp://ftp2.bipm.org/pub/tai/publication/gnss-calibration/doc-soft/>
- [4] http://www.bipm.org/wg/CCTF/WGGNSS/Allowed/BIPM_guidelines.V3/Annex-3_Computation-procedure-Rinex.V2.pdf

Annex A - Information Sheet

Laboratory:	NIST, Boulder, USA	
Date and hour of the beginning of measurements:	DOY150-225, 2023	
Date and hour of the end of measurements:		
Information on the system		
	Local:	Traveling:
4-character BIPM code	NISX	NB05
Receiver maker and type: Receiver serial number:	PolaRxTR 5 S/N	PolaRxTR 5 S/N 3025300
1 PPS trigger level /V:	1	1
Antenna cable maker and type: Phase stabilized cable (Y/N):	Andrew FSJ-50A N	LMR 400 N
Length outside the building /m:	65	50
Antenna maker and type: Antenna serial number:	Novatel 702	Septentrio PolaNt-x MFv2
Temperature (if stabilized) /°C		
Measured delays /ns		
	Local:	Traveling:
Delay from local UTC to receiver 1 PPS-in (X_P)	66.7	327.8+85.8 = 413.6
Delay from 1 PPS-in to internal Reference (if different): (X_O)	54.9	56.07
Antenna cable delay: (X_C)	275.5	328.6
Splitter delay (if any):	N/A	N/A
Additional cable delay (if any):	N/A	N/A
Data used for the generation of CGGTTS files		
• INT DLY (or X_R+X_S) (GPS) [†] /ns:	28.16 (P1), 26.31(P2)	
• INT DLY (or X_R+X_S) (Galileo) /ns:	30.54 (E1), 31.15 (E5a)	
• CAB DLY (or X_C) /ns:	275.5	
• REF DLY (or X_P+X_O) /ns:	120	
• Coordinates reference frame:	WGS84	
X /m:	-1288398.60	
Y /m:	-4721697.05	
Z /m	4078625.45	
General information		
• Rise time of the local UTC pulse:	3 ns	
• Is the laboratory air conditioned:	yes	
Set temperature value and uncertainty:		
Set humidity value and uncertainty:		

[†] Based on Cal_Id 1001-2020

Annex A - Information Sheet

Laboratory:	National Research Council Canada (NRC)	
Date and hour of the beginning of measurements	2023-07-08 00:00:00	
Date and hour of the end of measurements	2023-07-12 23:59:30	
Information on the system		
	Local	Traveling
4-character BIPM code	NRC4	nb05
Receiver maker and type Receiver serial number	Septentrio, PolaRx4TRpro 31022286	Septentrio, PolaRx5TR 4701275
1 PPS trigger level /V	1.0 V	1.0 V
Antenna cable maker and type Phase stabilized cable (Y/N)	Andrea, HeliAx LDF 2-50 Y	LMR-400 Y
Length outside the building /m:	~1.5 m	~ 20 m
Antenna maker, type, and serial number	ASH701945E_M SNOW GR52002205	PolaNt-x MF.v2, AT1675-486 5251
Temperature (if stabilized) /°C		
Measured delays /ns		
	Local	Traveling
Delay from local UTC to receiver 1 PPS-in (X_P)	84.40 ns	16.30 ns
Delay from 1 PPS-in to internal Reference (if different) (X_O)	144.41 ns	47.80 ns
Antenna cable delay (X_C)	269.26 ns	328.84 ns
Splitter delay (if any)	unknown	No
Additional cable delay (if any)	Surge arrestor included in cable delay	No
Data used for the generation of CGGTTS files		
INT DLY (or X_R+X_S) (GPS) /ns		
CAB DLY (or X_C) /ns		
REF DLY (or X_P+X_O) /ns		
Coordinates reference frame		
X /m		
Y /m		
Z /m		
General information		
Rise time of the local UTC pulse	2.70 ns	
Is the laboratory air conditioned ? (Y/N)	Y	
Set temperature value and uncertainty	24.8 ± 0.5 °C	
Set humidity value and uncertainty		

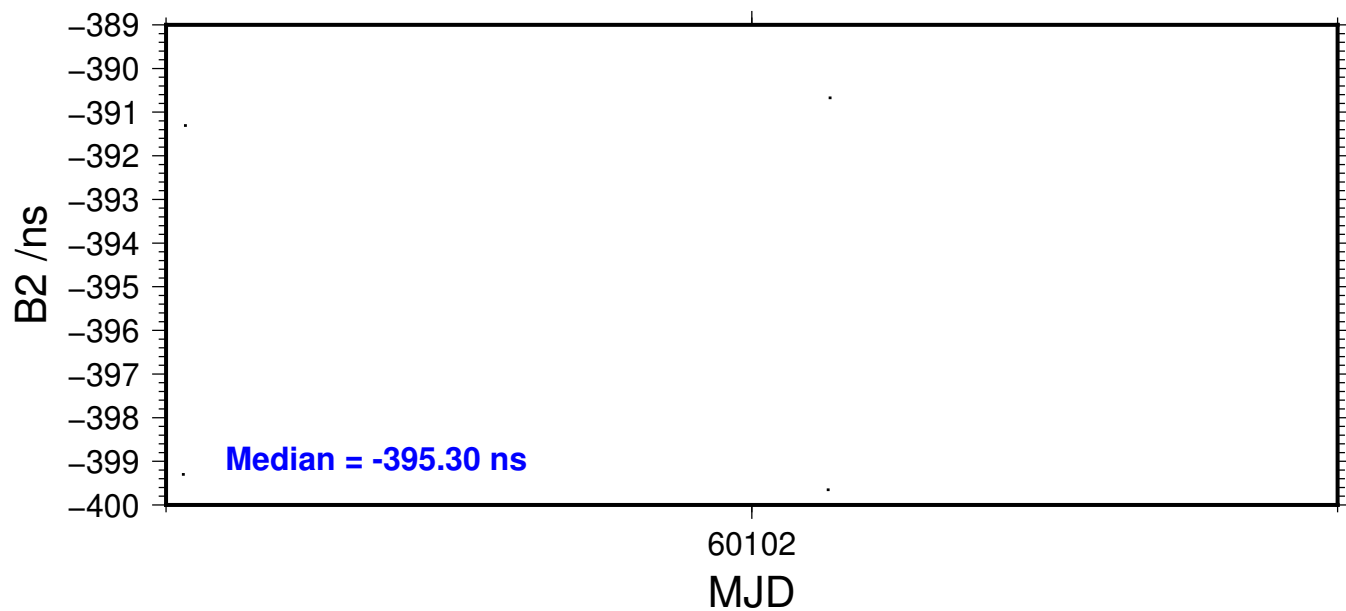
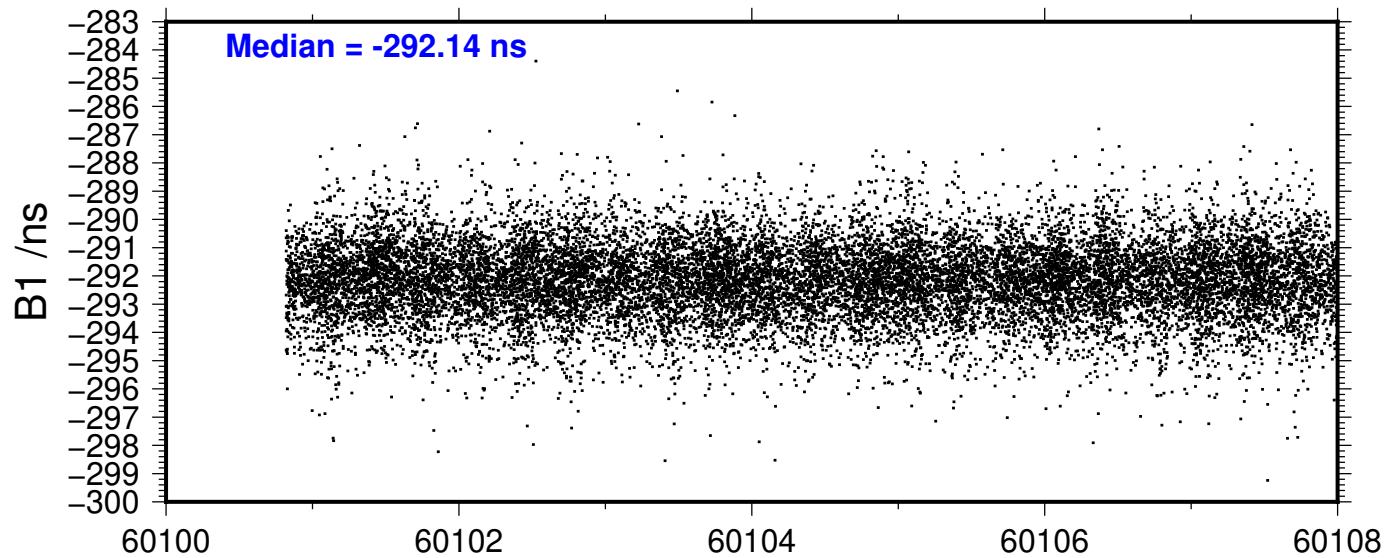
Annex A - Information Sheet

Laboratory:	National Research Council Canada (NRC)	
Date and hour of the beginning of measurements	2023-07-08 00:00:00	
Date and hour of the end of measurements	2023-07-12 23:59:30	
Information on the system		
	Local	Traveling
4-character BIPM code	NRCC	nb05
Receiver maker and type Receiver serial number	Septentrio, PolaRx5TR 4701362	Septentrio, PolaRx5TR 4701275
1 PPS trigger level /V	1.0 V	1.0 V
Antenna cable maker and type Phase stabilized cable (Y/N)	Andrea Helix, LDF2-50 3/8" Y	LMR-400 Y
Length outside the building /m:	~8 m	~ 20 m
Antenna maker, type, and serial number	PolaNt Choke Ring B3/E6 5645	PolaNt-x MF.v2, AT1675-486 5251
Temperature (if stabilized) /°C		
Measured delays /ns		
	Local	Traveling
Delay from local UTC to receiver 1 PPS-in (X_P)	19.04 ns	16.30 ns
Delay from 1 PPS-in to internal Reference (if different) (X_O)	39.61 ns	47.80 ns
Antenna cable delay (X_C)	305.44 ns	328.84 ns
Splitter delay (if any)	9.50 ns	No
Additional cable delay (if any)	-	No
Data used for the generation of CGGTTS files		
INT DLY (or X_R+X_S) (GPS) /ns		
CAB DLY (or X_C) /ns		
REF DLY (or X_P+X_O) /ns		
Coordinates reference frame		
X /m		
Y /m		
Z /m		
General information		
Rise time of the local UTC pulse	2.45 ns	
Is the laboratory air conditioned ? (Y/N)	Y	
Set temperature value and uncertainty	24.8 ± 0.5 °C	
Set humidity value and uncertainty		

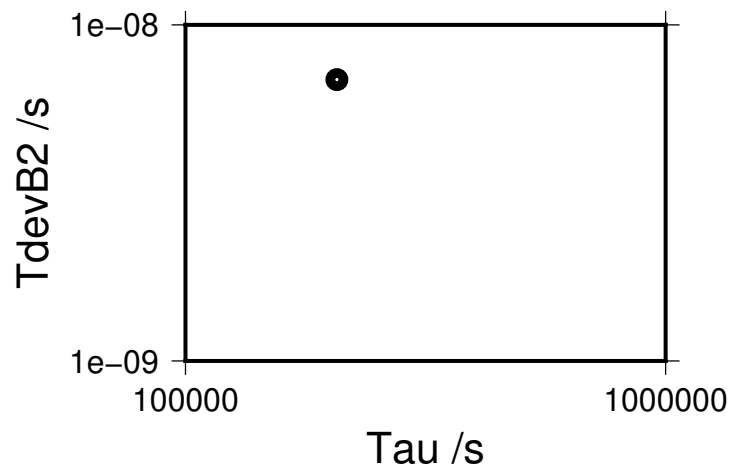
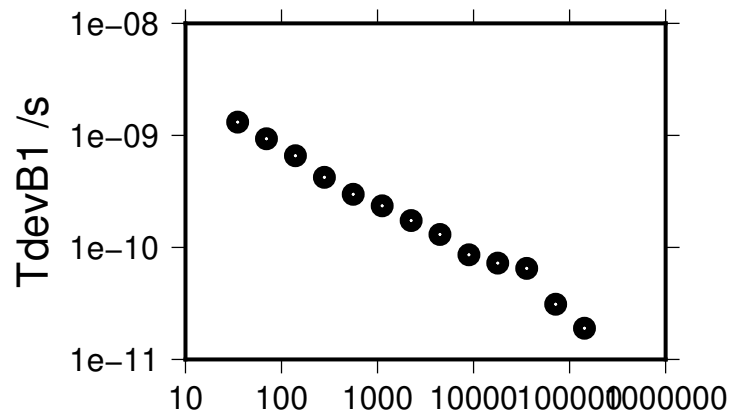
Annex A - Information Sheet

Laboratory:	National Research Council Canada (NRC)	
Date and hour of the beginning of measurements	2023-07-20 00:00:00	
Date and hour of the end of measurements	2023-07-24 23:59:30	
Information on the system		
	Local	Traveling
4-character BIPM code	NRC6	nb05
Receiver maker and type Receiver serial number	Septentrio, PolaRx5TR 47011574	Septentrio, PolaRx5TR 4701275
1 PPS trigger level /V	1.0 V	1.0 V
Antenna cable maker and type Phase stabilized cable (Y/N)	Andrea Helix, LDF2-50 3/8" Y	LMR-400 Y
Length outside the building /m:	~2 m	~15 m
Antenna maker, type, and serial number	PolaNt Choke Ring B3/E6 6064	PolaNt-x MF.v2, AT1675-486 5251
Temperature (if stabilized) /°C		
Measured delays /ns		
	Local	Traveling
Delay from local UTC to receiver 1 PPS-in (X_P)	2.86 ns	4.85 ns
Delay from 1 PPS-in to internal Reference (if different) (X_O)	47.13 ns	49.31 ns
Antenna cable delay (X_C)	37.63 ns	328.84 ns
Splitter delay (if any)	Splitter is not counted.	No
Additional cable delay (if any)	Surge arrestor is not counted.	No
Data used for the generation of CGGTTS files		
INT DLY (or X_R+X_S) (GPS) /ns		
CAB DLY (or X_C) /ns		
REF DLY (or X_P+X_O) /ns		
Coordinates reference frame		
X /m		
Y /m		
Z /m		
General information		
Rise time of the local UTC pulse	2.0 ns	
Is the laboratory air conditioned ? (Y/N)	Y	
Set temperature value and uncertainty	19.6 ± 2.5 °C	
Set humidity value and uncertainty		

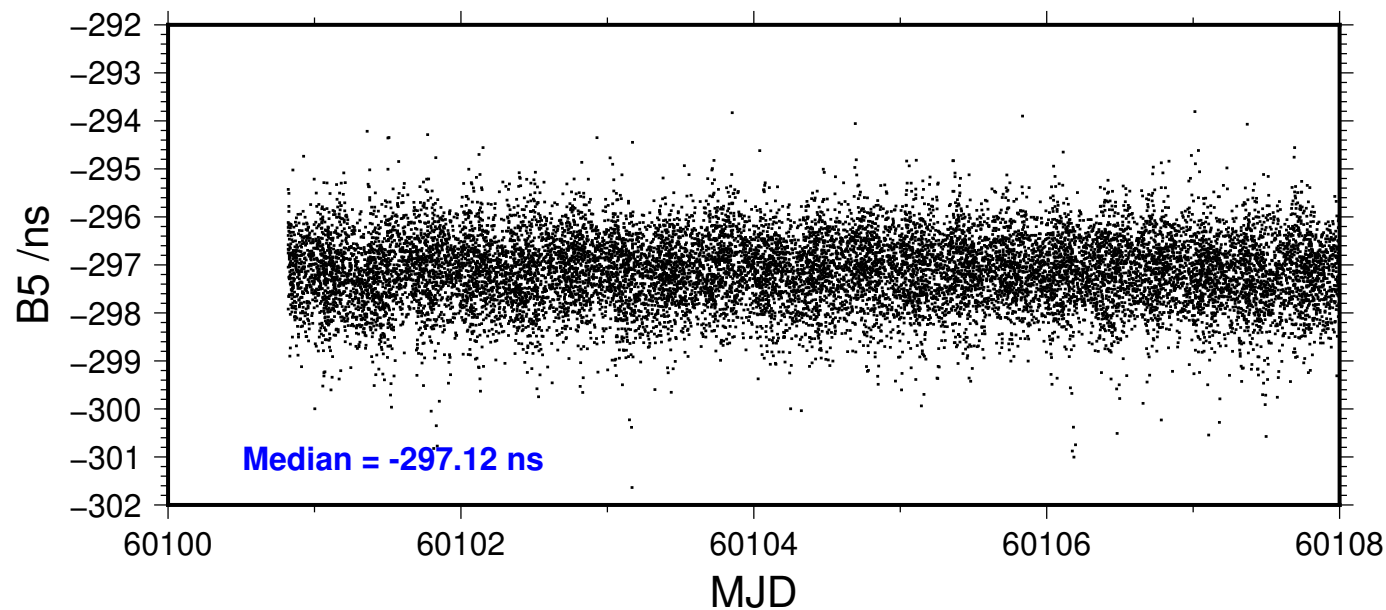
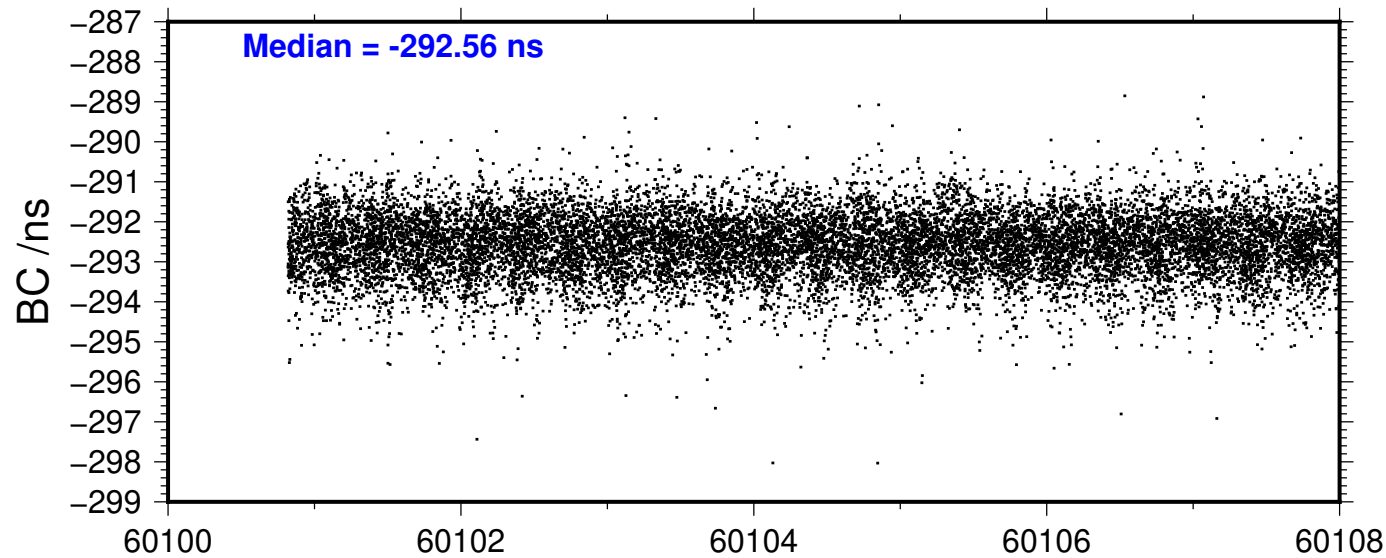
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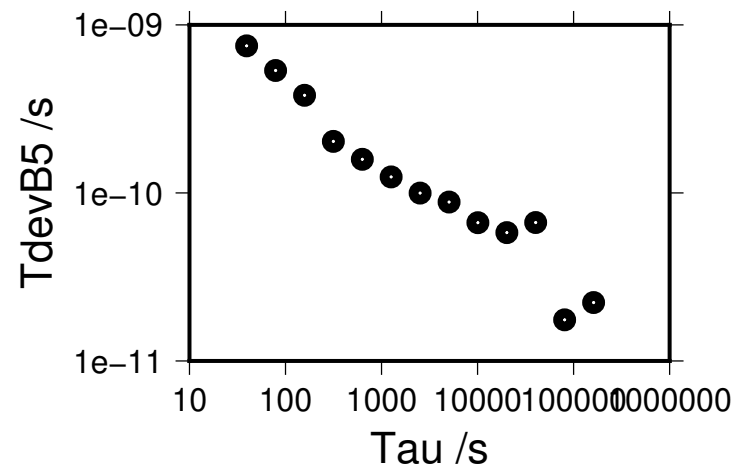
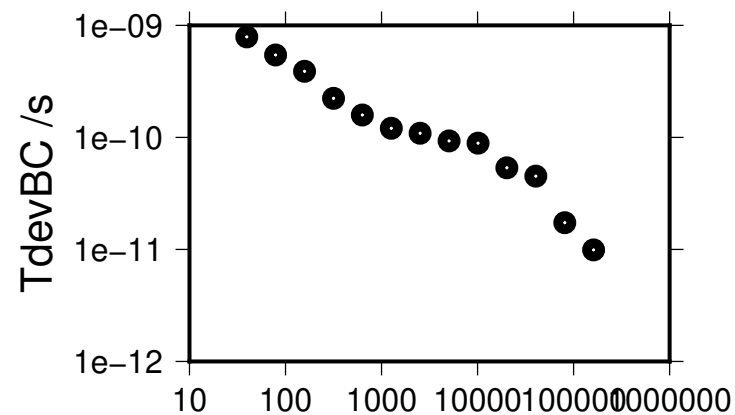
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- 35764 s: B1= 65 ps
- 17882 s: B1= 73 ps
- 8941 s: B1= 86 ps
- 4470 s: B1= 131 ps
- 2235 s: B1= 174 ps
- 1118 s: B1= 235 ps
- 559 s: B1= 298 ps
- 279 s: B1= 422 ps
- 140 s: B1= 659 ps
- 70 s: B1= 934 ps
- 35 s: B1= 1316 ps
- 206700 s: B2= 6875 ps



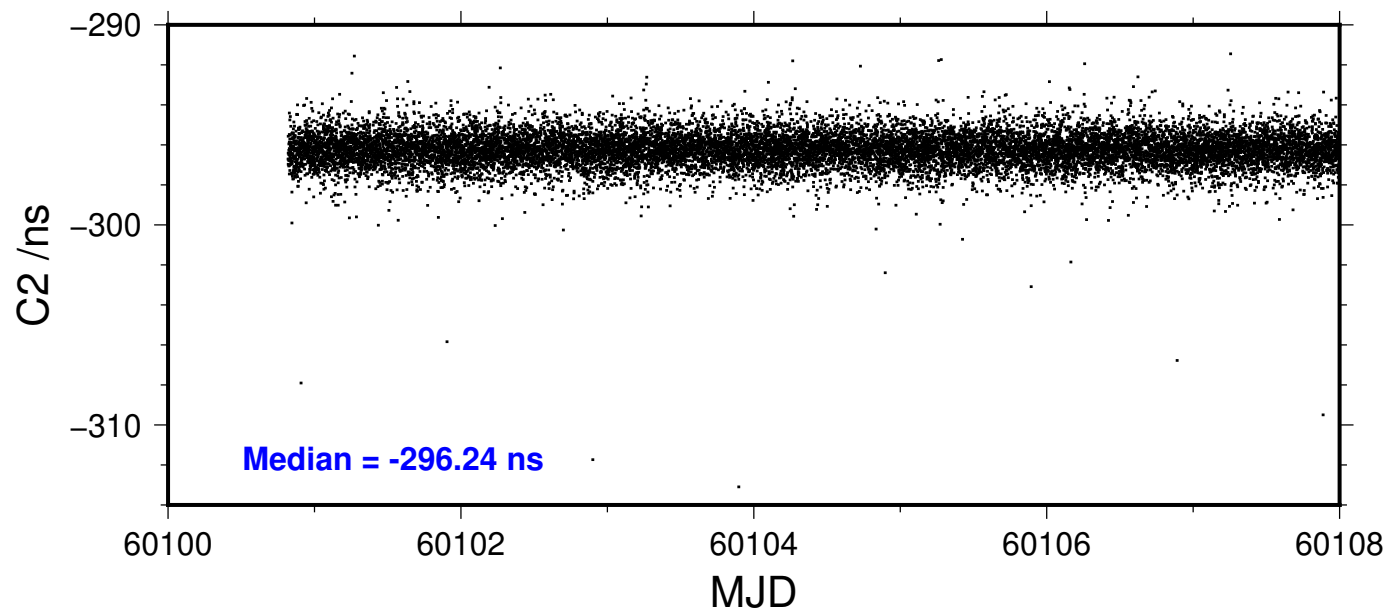
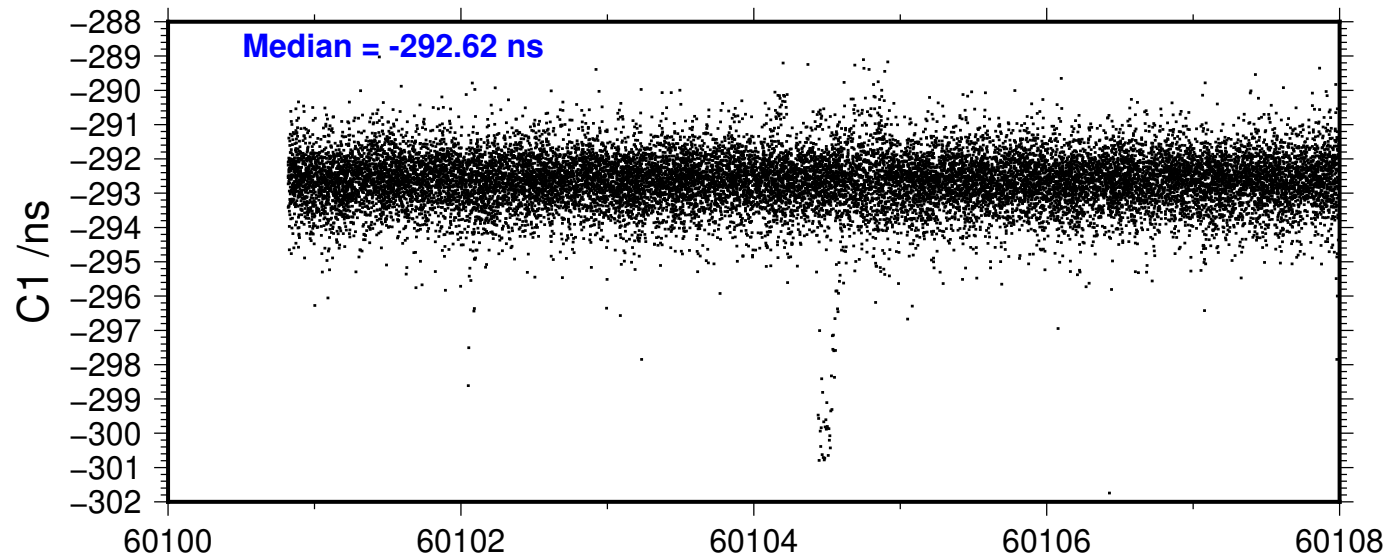
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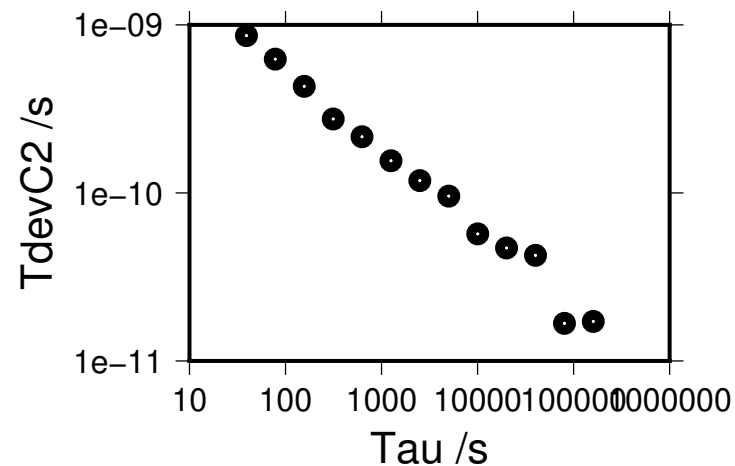
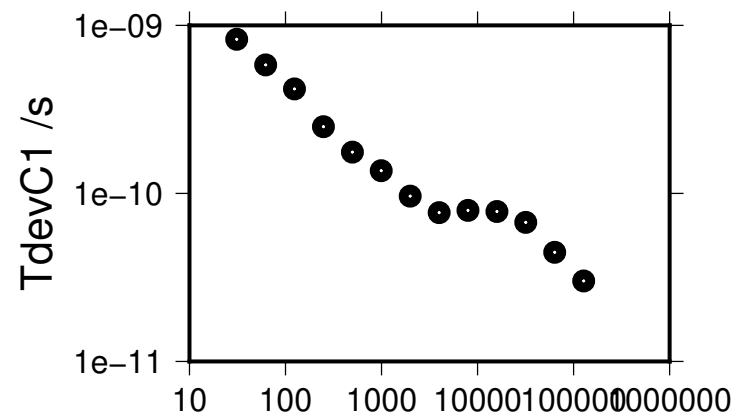
161635 s: BC=	10 ps	161388 s: B5=	22 ps
80817 s: BC=	17 ps	80694 s: B5=	18 ps
40409 s: BC=	45 ps	40347 s: B5=	67 ps
20204 s: BC=	54 ps	20174 s: B5=	58 ps
10102 s: BC=	89 ps	10087 s: B5=	66 ps
5051 s: BC=	93 ps	5043 s: B5=	88 ps
2526 s: BC=	109 ps	2522 s: B5=	100 ps
1263 s: BC=	121 ps	1261 s: B5=	125 ps
631 s: BC=	158 ps	630 s: B5=	159 ps
316 s: BC=	223 ps	315 s: B5=	203 ps
158 s: BC=	389 ps	158 s: B5=	381 ps
79 s: BC=	544 ps	79 s: B5=	535 ps
39 s: BC=	789 ps	39 s: B5=	751 ps



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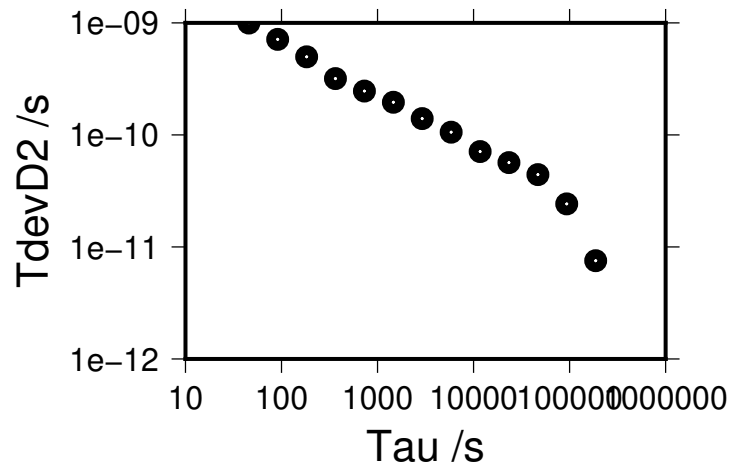
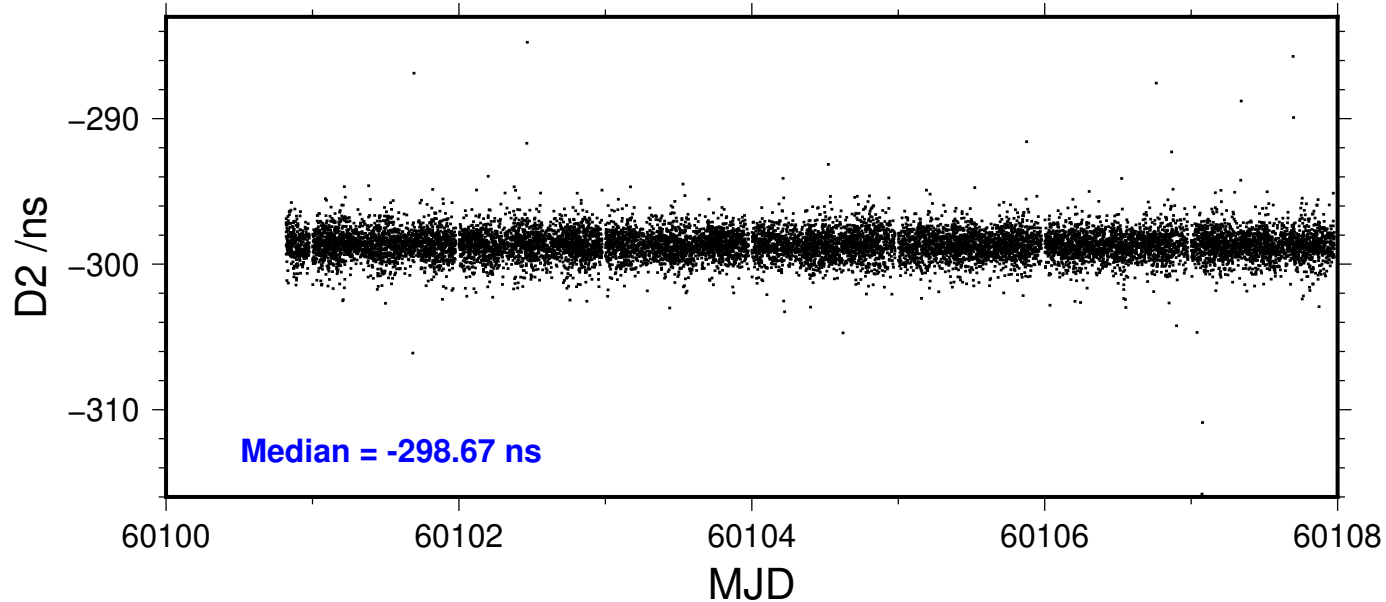
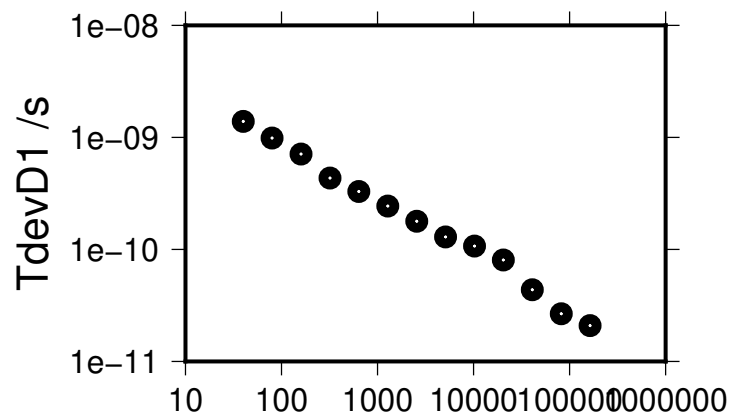
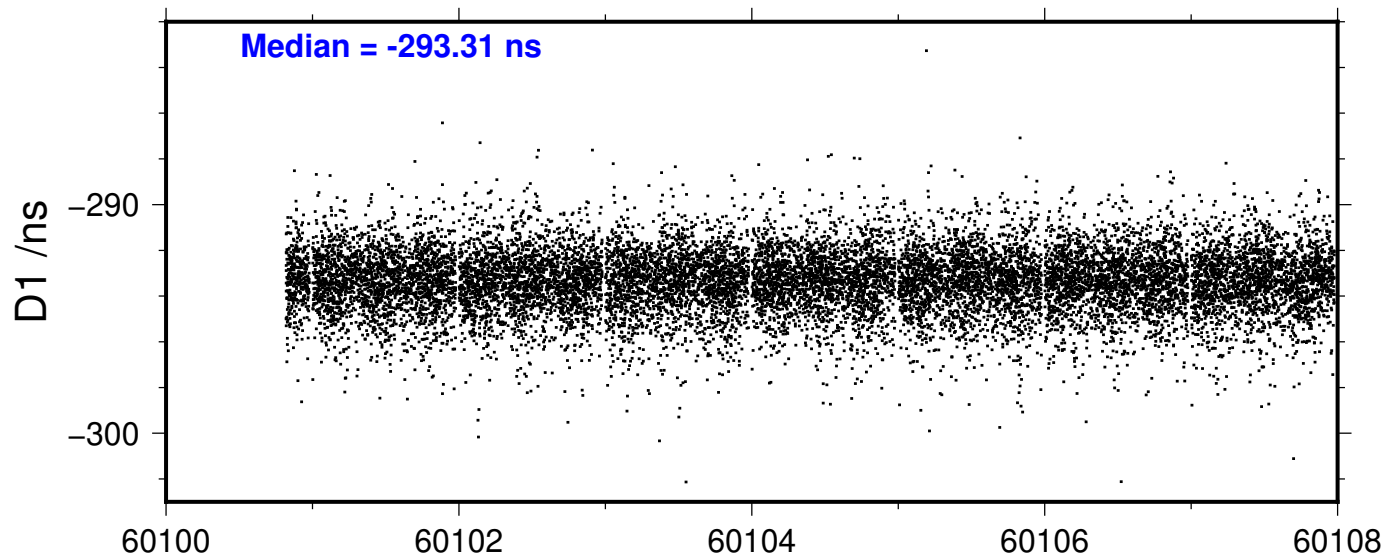


127175 s: C1= 30 ps	160450 s: C2= 17 ps
63587 s: C1= 45 ps	80225 s: C2= 17 ps
31794 s: C1= 67 ps	40113 s: C2= 43 ps
15897 s: C1= 78 ps	20056 s: C2= 47 ps
7948 s: C1= 79 ps	10028 s: C2= 57 ps
3974 s: C1= 77 ps	5014 s: C2= 96 ps
1987 s: C1= 96 ps	2507 s: C2= 118 ps
994 s: C1= 137 ps	1254 s: C2= 155 ps
497 s: C1= 176 ps	627 s: C2= 216 ps
248 s: C1= 249 ps	313 s: C2= 275 ps
124 s: C1= 419 ps	157 s: C2= 431 ps
62 s: C1= 582 ps	78 s: C2= 626 ps
31 s: C1= 826 ps	39 s: C2= 863 ps

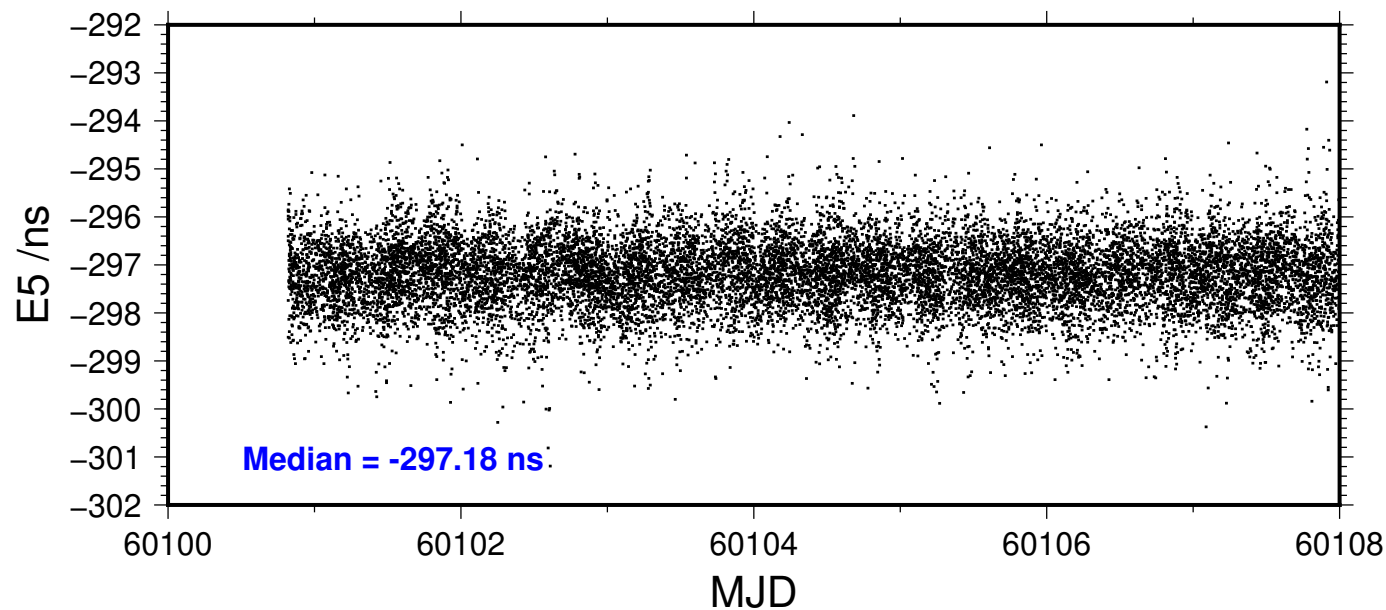
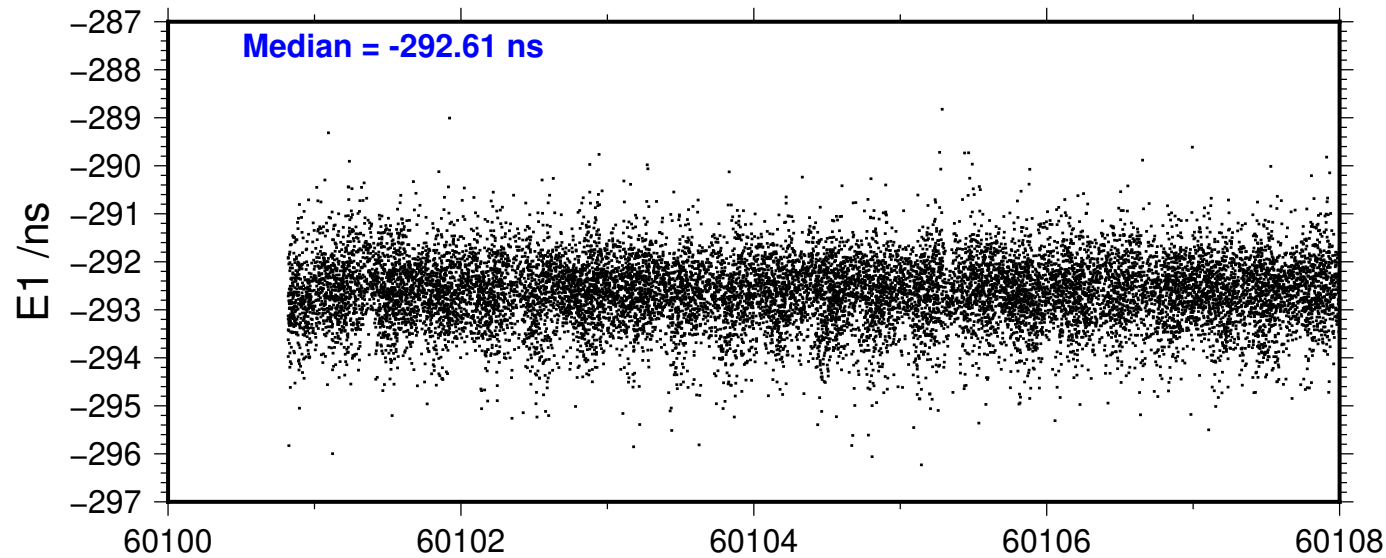


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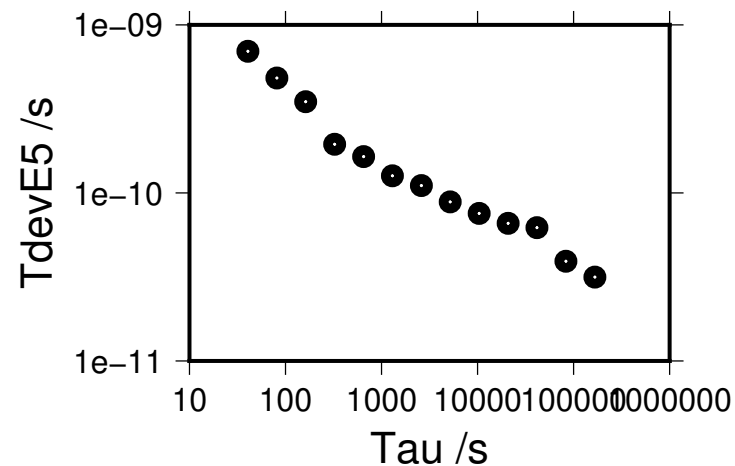
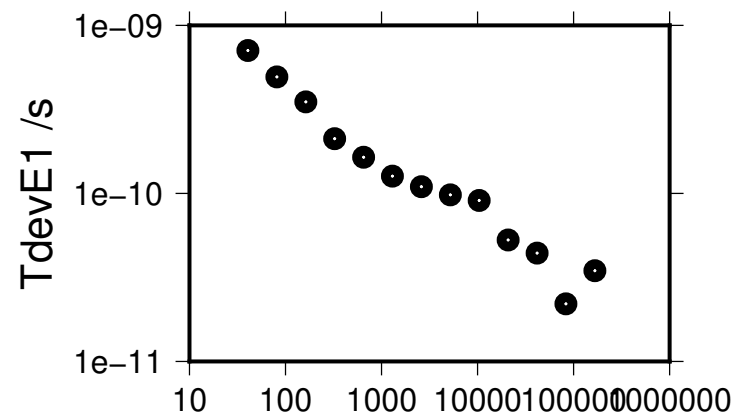
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81796 s: D1= 27 ps	93462 s: D2= 24 ps
40898 s: D1= 44 ps	46731 s: D2= 44 ps
20449 s: D1= 80 ps	23366 s: D2= 57 ps
10224 s: D1= 107 ps	11683 s: D2= 71 ps
5112 s: D1= 129 ps	5841 s: D2= 106 ps
2556 s: D1= 179 ps	2921 s: D2= 140 ps
1278 s: D1= 244 ps	1460 s: D2= 196 ps
639 s: D1= 329 ps	730 s: D2= 247 ps
320 s: D1= 433 ps	365 s: D2= 318 ps
160 s: D1= 711 ps	183 s: D2= 498 ps
80 s: D1= 986 ps	91 s: D2= 714 ps
40 s: D1= 1392 ps	46 s: D2= 996 ps



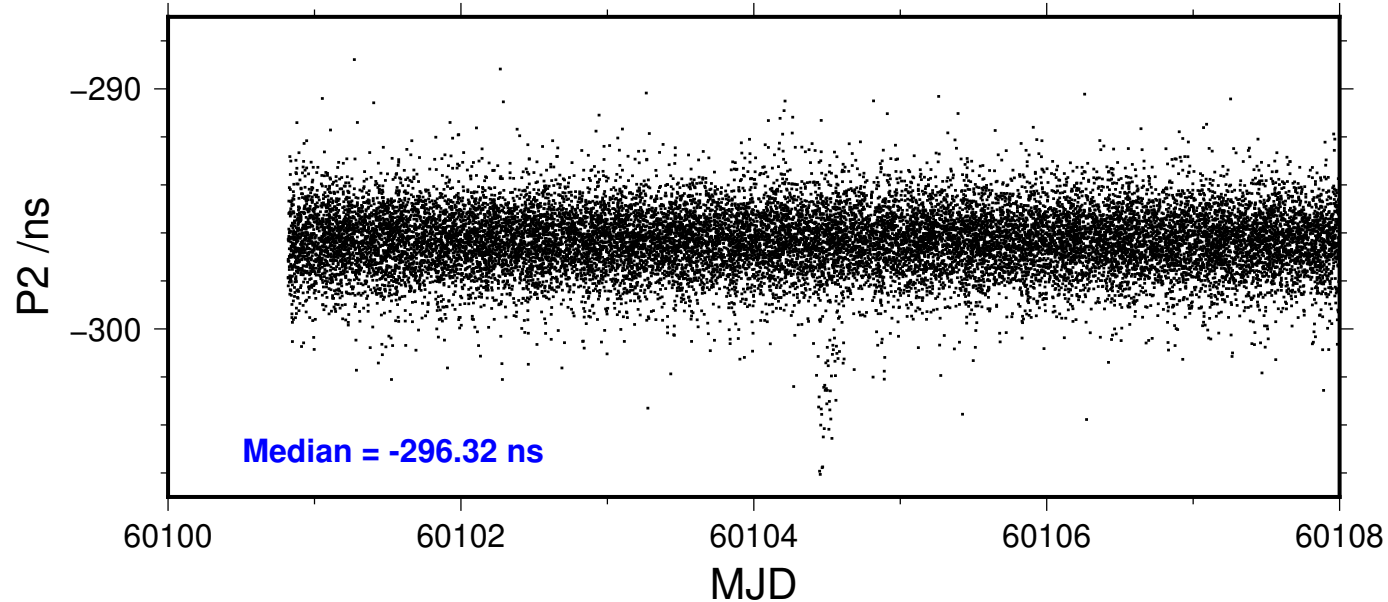
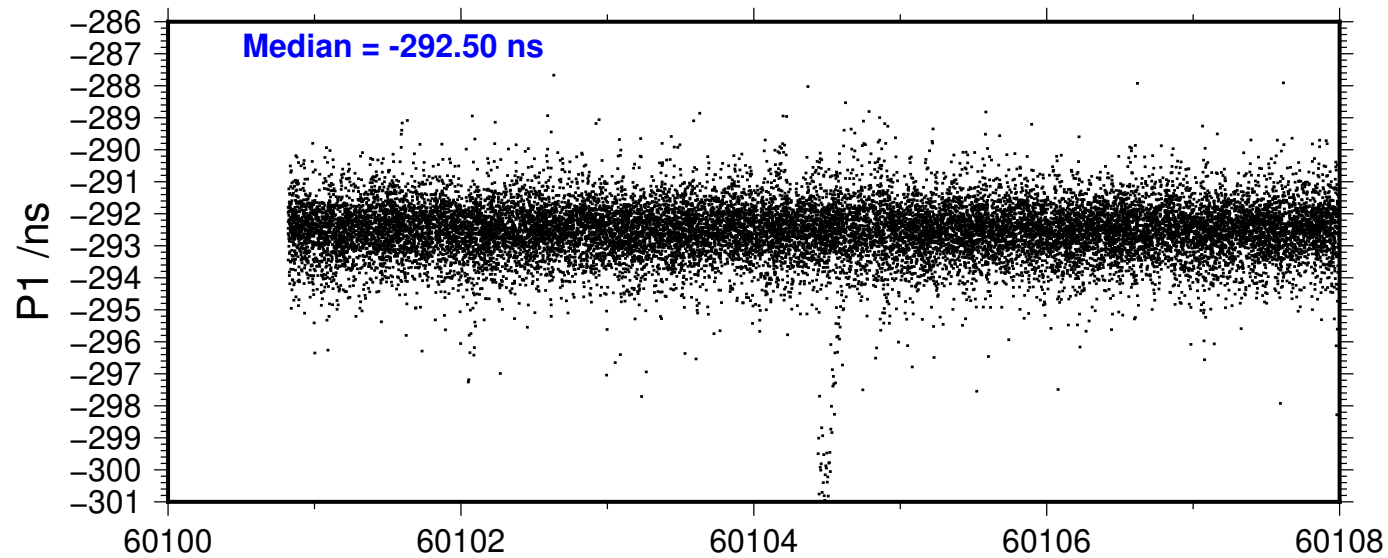
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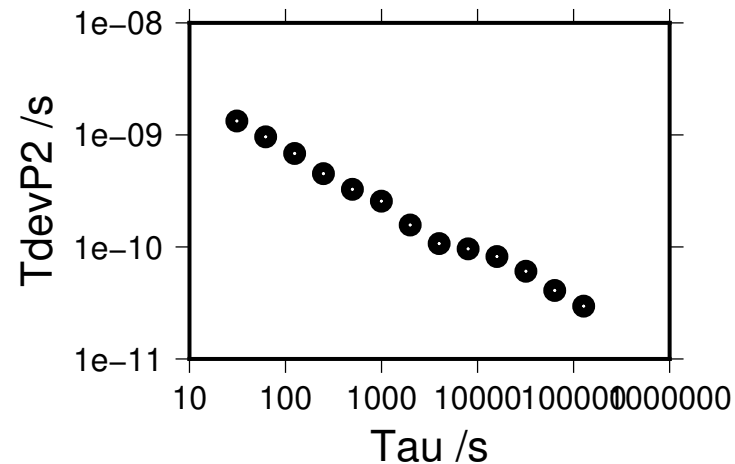
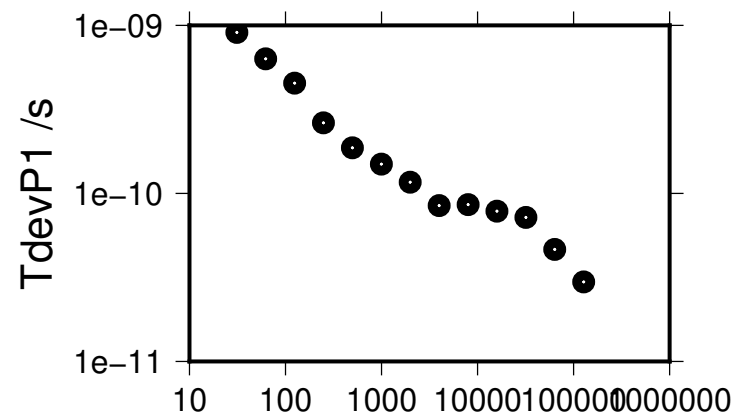
166433 s: E1= 35 ps	166280 s: E5= 32 ps
83216 s: E1= 22 ps	83140 s: E5= 39 ps
41608 s: E1= 44 ps	41570 s: E5= 62 ps
20804 s: E1= 53 ps	20785 s: E5= 66 ps
10402 s: E1= 91 ps	10393 s: E5= 76 ps
5201 s: E1= 98 ps	5196 s: E5= 88 ps
2601 s: E1= 110 ps	2598 s: E5= 111 ps
1300 s: E1= 127 ps	1299 s: E5= 127 ps
650 s: E1= 164 ps	650 s: E5= 165 ps
325 s: E1= 212 ps	325 s: E5= 195 ps
163 s: E1= 351 ps	162 s: E5= 349 ps
81 s: E1= 494 ps	81 s: E5= 483 ps
41 s: E1= 708 ps	41 s: E5= 696 ps



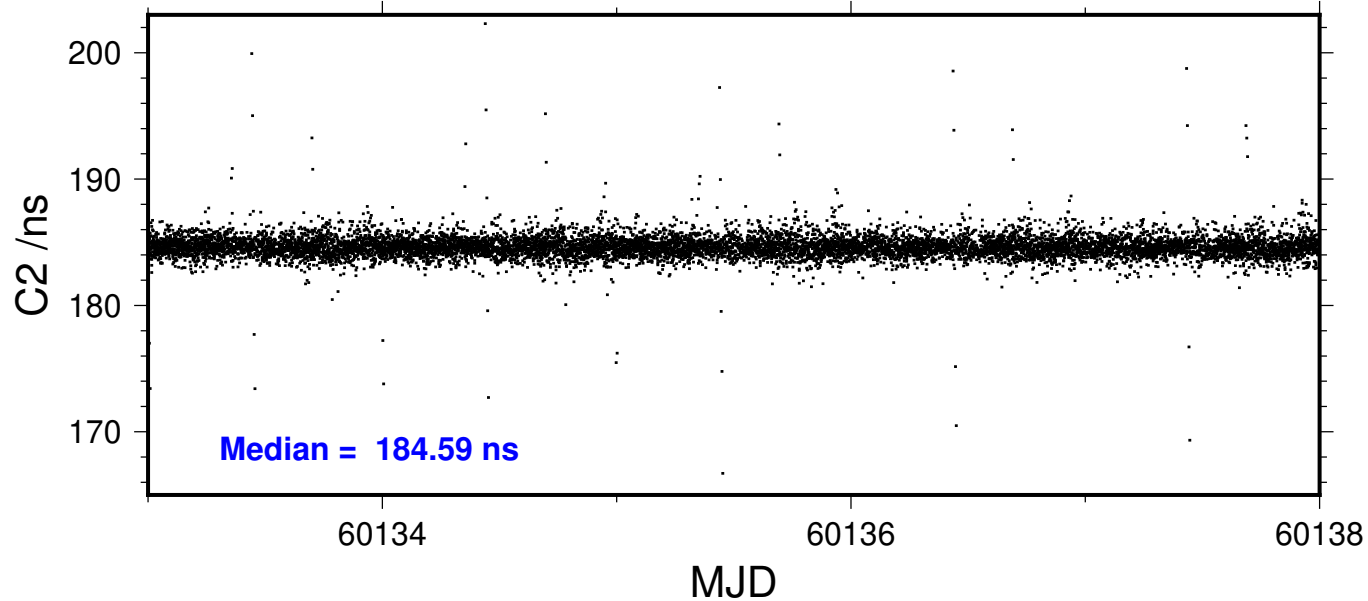
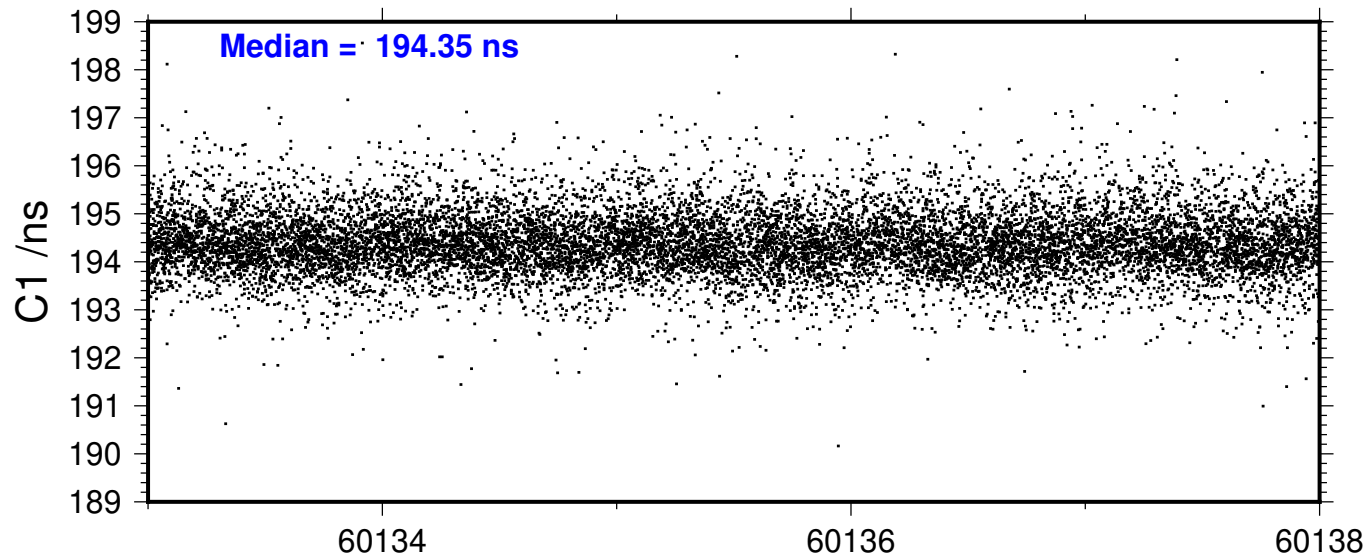
2023-06-13 NB05NIST23156_8



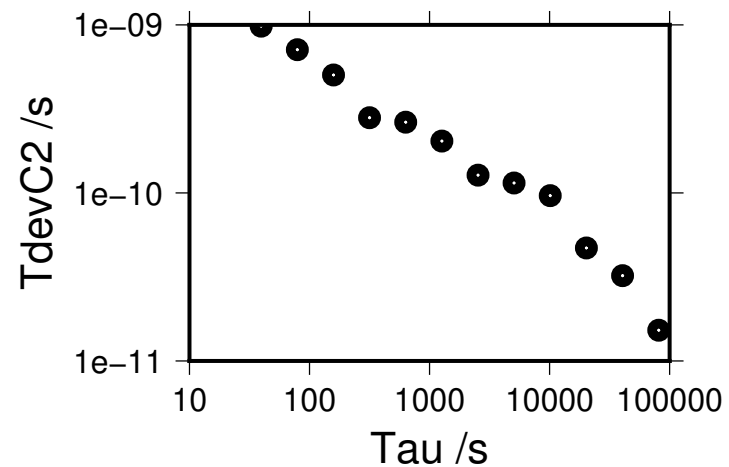
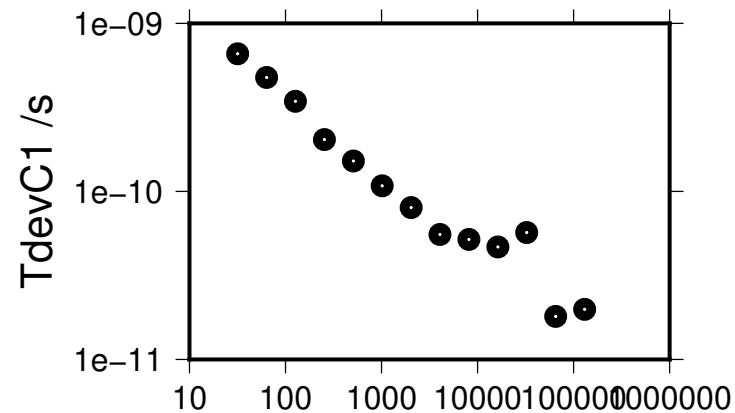
127359 s: P1= 30 ps	127359 s: P2= 30 ps
63680 s: P1= 46 ps	63680 s: P2= 41 ps
31840 s: P1= 72 ps	31840 s: P2= 61 ps
15920 s: P1= 78 ps	15920 s: P2= 82 ps
7960 s: P1= 86 ps	7960 s: P2= 96 ps
3980 s: P1= 85 ps	3980 s: P2= 107 ps
1990 s: P1= 117 ps	1990 s: P2= 157 ps
995 s: P1= 149 ps	995 s: P2= 256 ps
498 s: P1= 187 ps	498 s: P2= 327 ps
249 s: P1= 263 ps	249 s: P2= 451 ps
124 s: P1= 454 ps	124 s: P2= 683 ps
62 s: P1= 632 ps	62 s: P2= 963 ps
31 s: P1= 908 ps	31 s: P2= 1330 ps



2024-02-08 NB05NRC423189_5

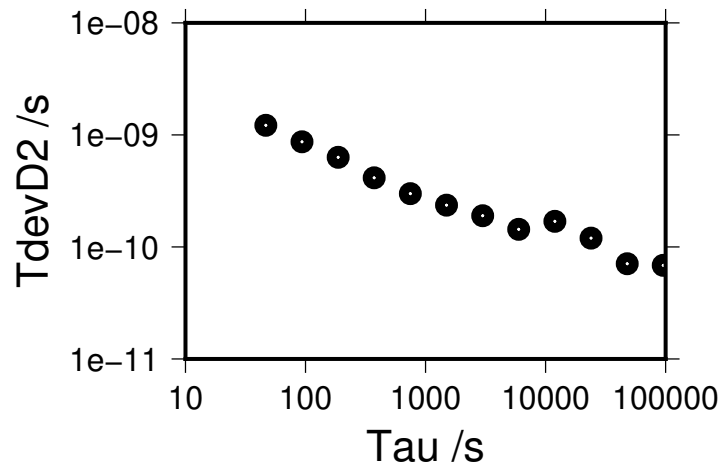
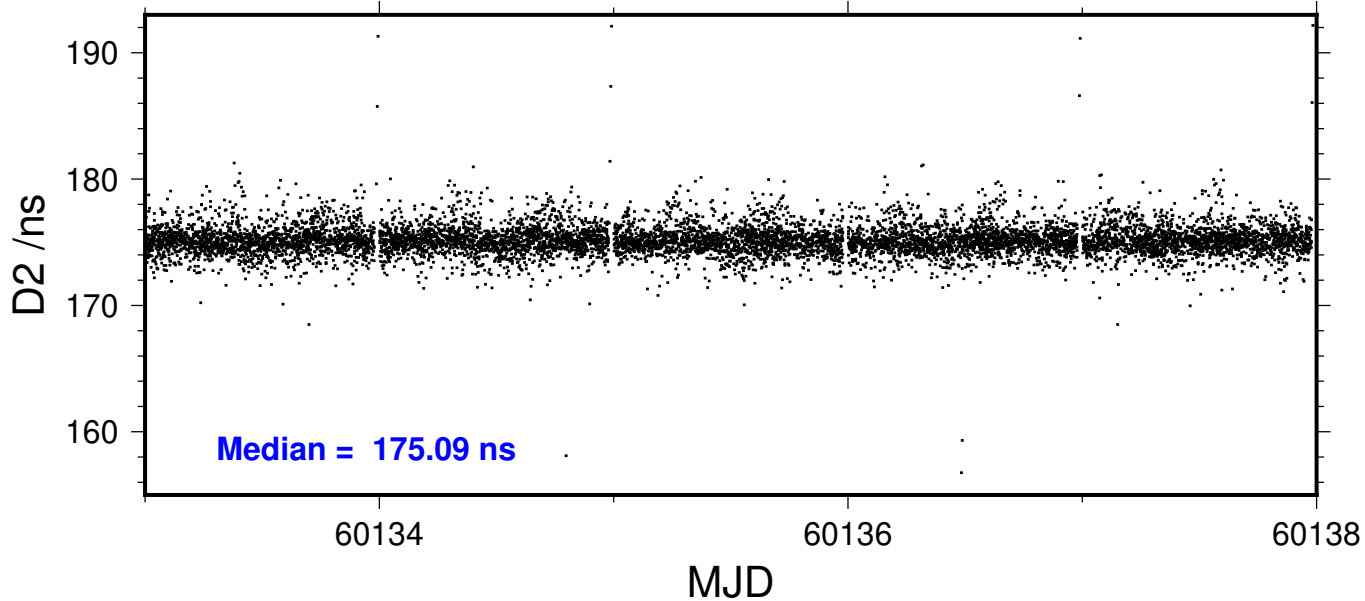
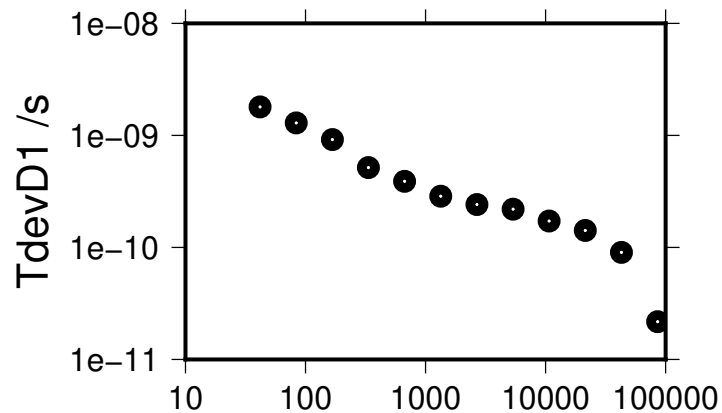
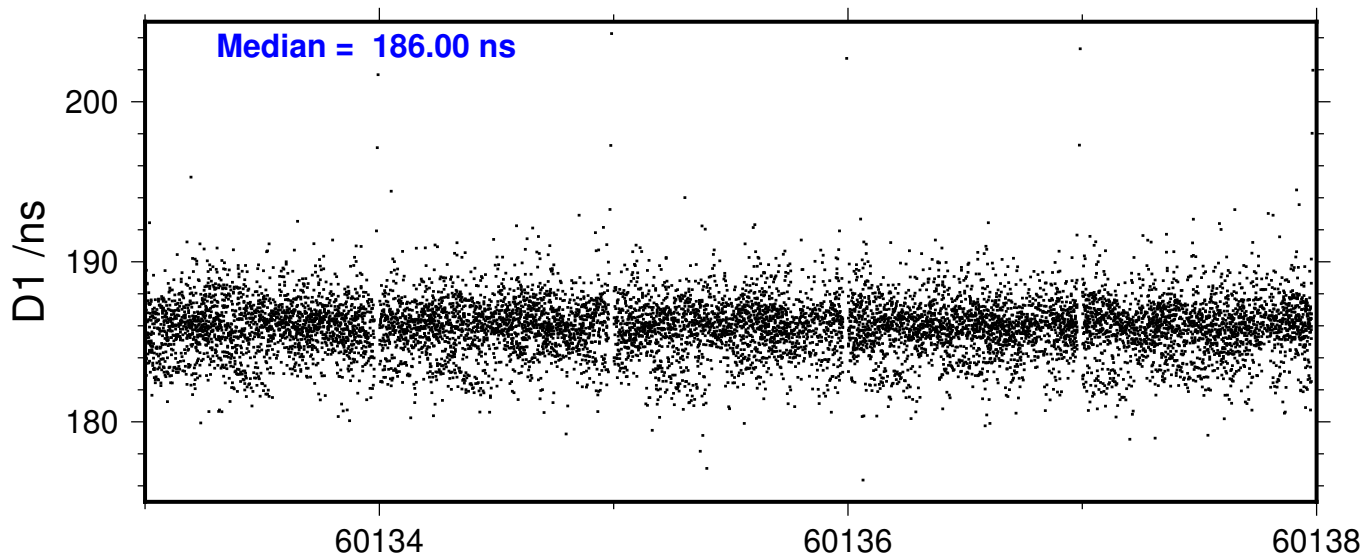


130075 s: C1= 20 ps	81038 s: C2= 15 ps
65038 s: C1= 18 ps	40519 s: C2= 32 ps
32519 s: C1= 57 ps	20259 s: C2= 47 ps
16259 s: C1= 47 ps	10130 s: C2= 96 ps
8130 s: C1= 52 ps	5065 s: C2= 114 ps
4065 s: C1= 55 ps	2532 s: C2= 128 ps
2032 s: C1= 80 ps	1266 s: C2= 203 ps
1016 s: C1= 108 ps	633 s: C2= 264 ps
508 s: C1= 152 ps	317 s: C2= 280 ps
254 s: C1= 203 ps	158 s: C2= 503 ps
127 s: C1= 343 ps	79 s: C2= 713 ps
64 s: C1= 477 ps	40 s: C2= 983 ps

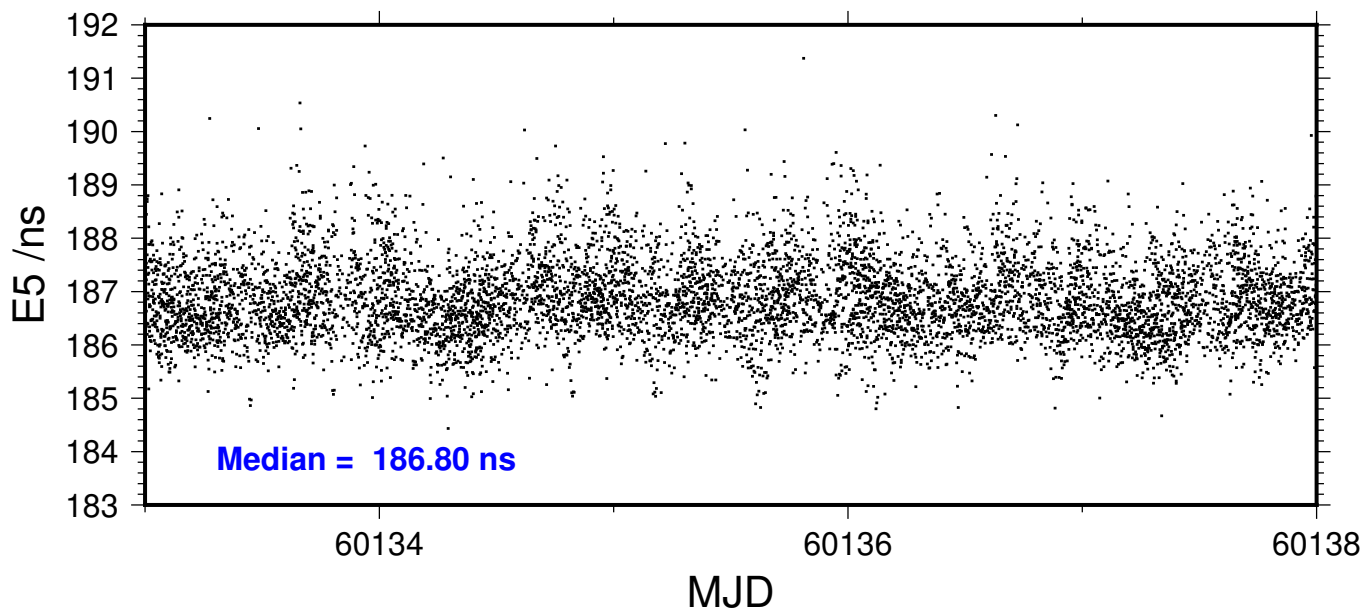
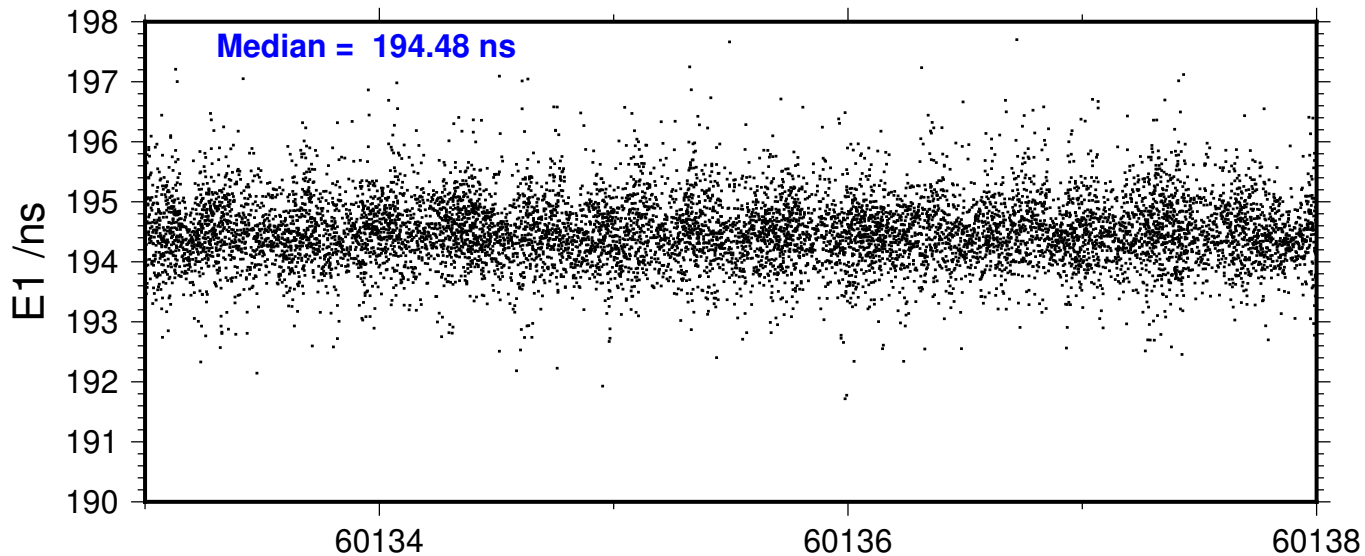


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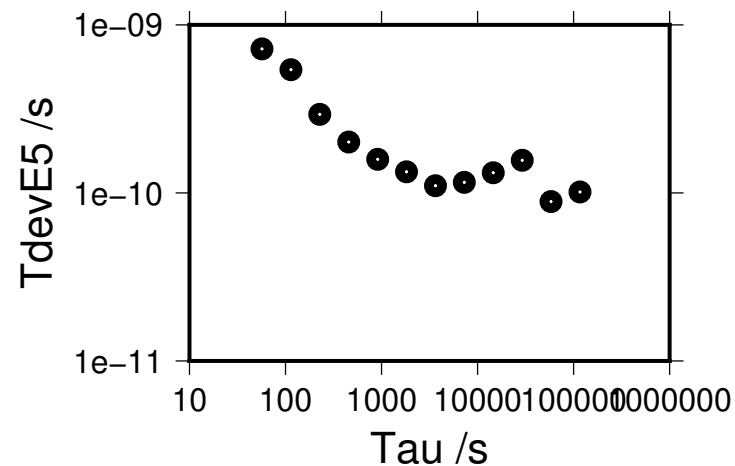
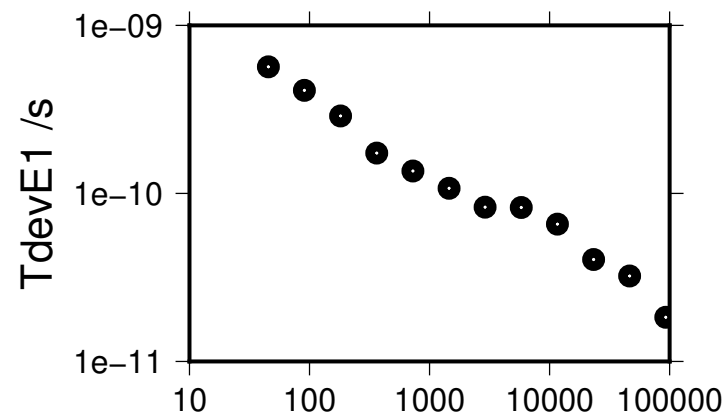
85679 s: D1= 22 ps	95643 s: D2= 68 ps
42840 s: D1= 90 ps	47821 s: D2= 71 ps
21420 s: D1= 142 ps	23911 s: D2= 120 ps
10710 s: D1= 172 ps	11955 s: D2= 169 ps
5355 s: D1= 219 ps	5978 s: D2= 143 ps
2677 s: D1= 242 ps	2989 s: D2= 190 ps
1339 s: D1= 286 ps	1494 s: D2= 236 ps
669 s: D1= 389 ps	747 s: D2= 299 ps
335 s: D1= 516 ps	374 s: D2= 415 ps
167 s: D1= 918 ps	187 s: D2= 631 ps
84 s: D1= 1292 ps	93 s: D2= 869 ps
42 s: D1= 1797 ps	47 s: D2= 1219 ps



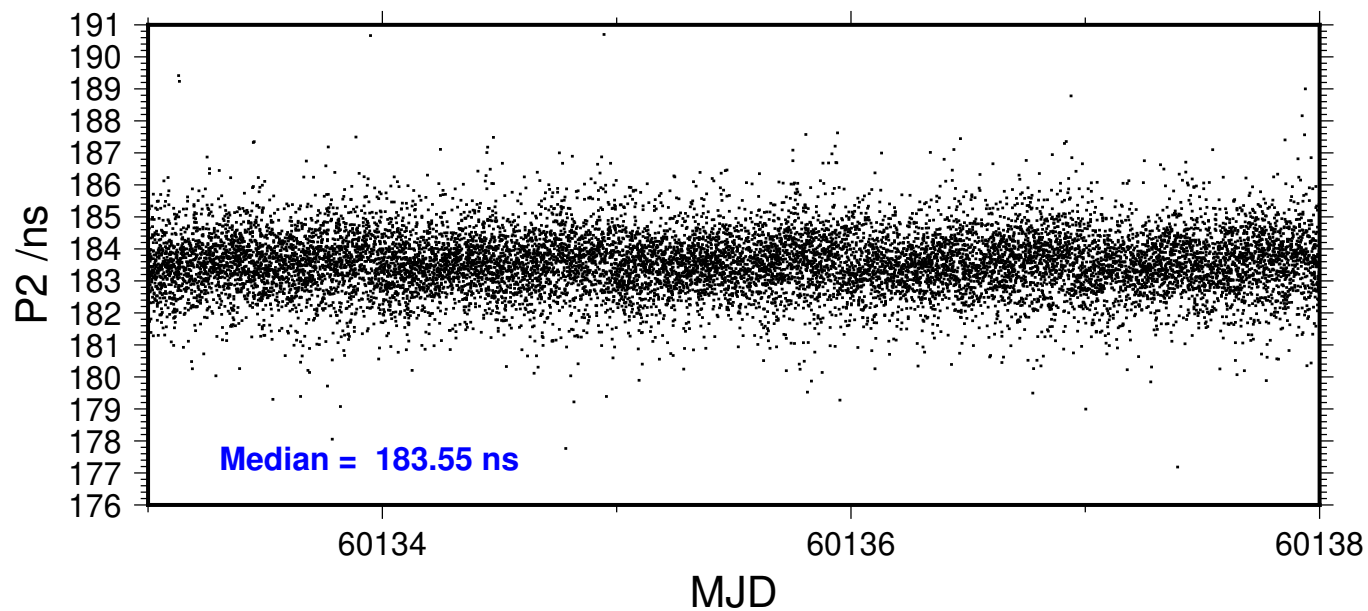
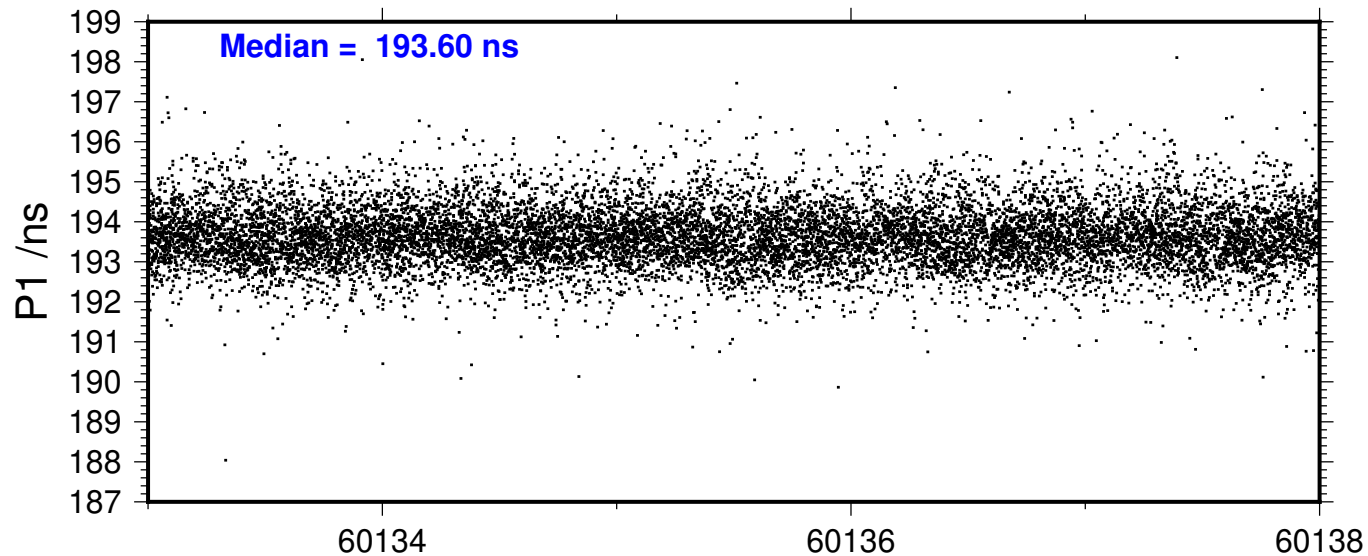
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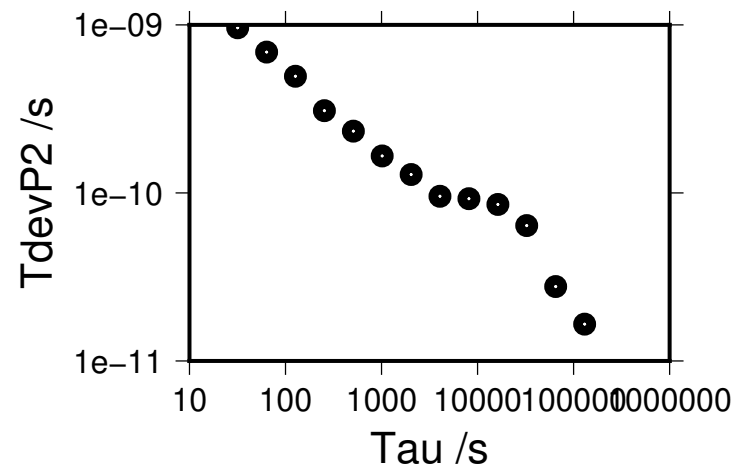
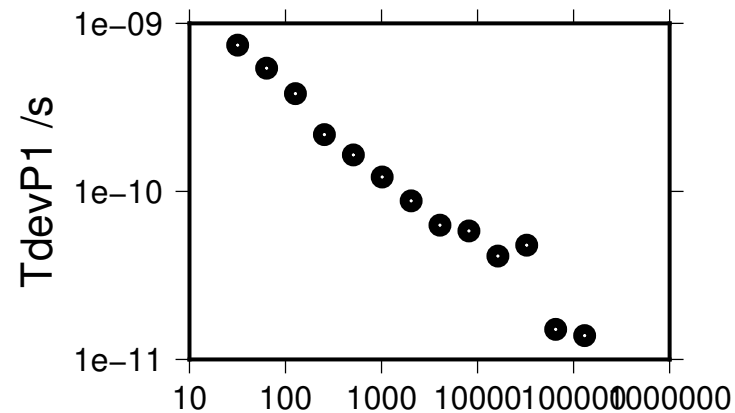
92948 s: E1= 18 ps	116531 s: E5= 101 ps
46474 s: E1= 32 ps	58266 s: E5= 89 ps
23237 s: E1= 40 ps	29133 s: E5= 156 ps
11618 s: E1= 66 ps	14566 s: E5= 132 ps
5809 s: E1= 83 ps	7283 s: E5= 116 ps
2905 s: E1= 83 ps	3642 s: E5= 110 ps
1452 s: E1= 107 ps	1821 s: E5= 134 ps
726 s: E1= 136 ps	910 s: E5= 158 ps
363 s: E1= 174 ps	455 s: E5= 201 ps
182 s: E1= 289 ps	228 s: E5= 294 ps
91 s: E1= 410 ps	114 s: E5= 542 ps
45 s: E1= 567 ps	57 s: E5= 720 ps



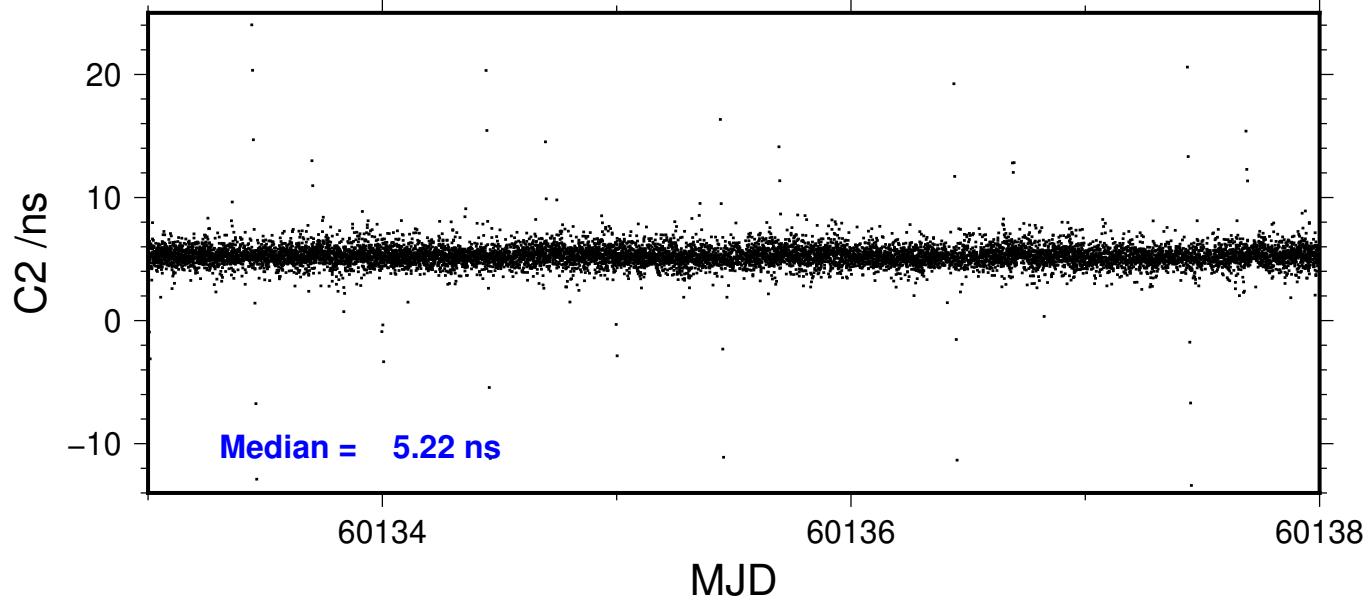
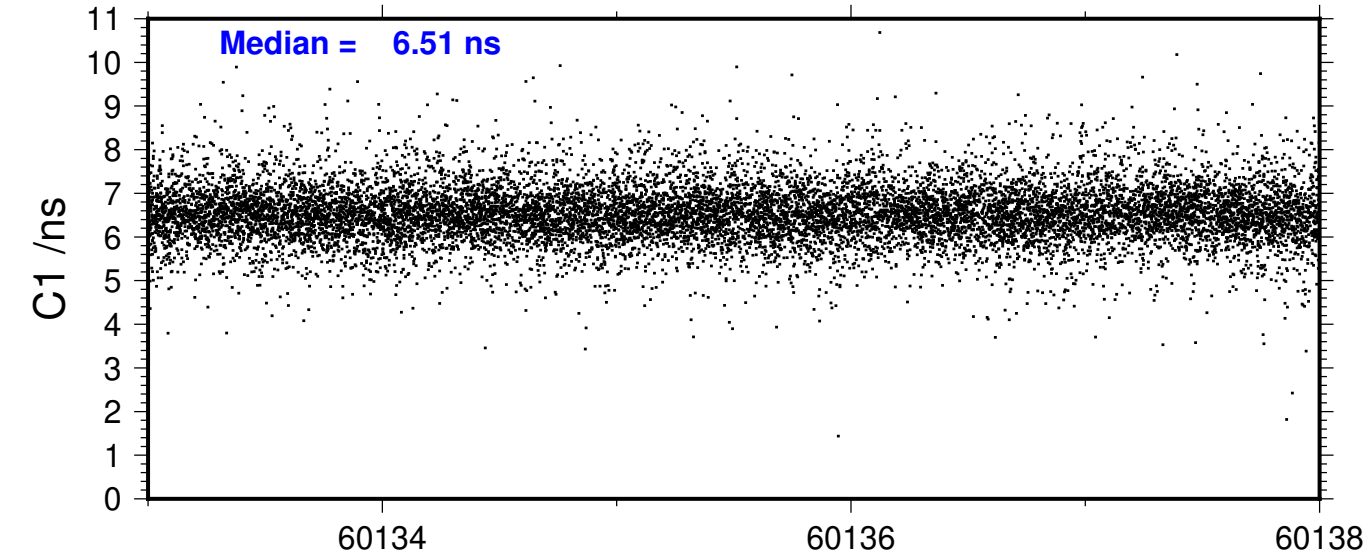
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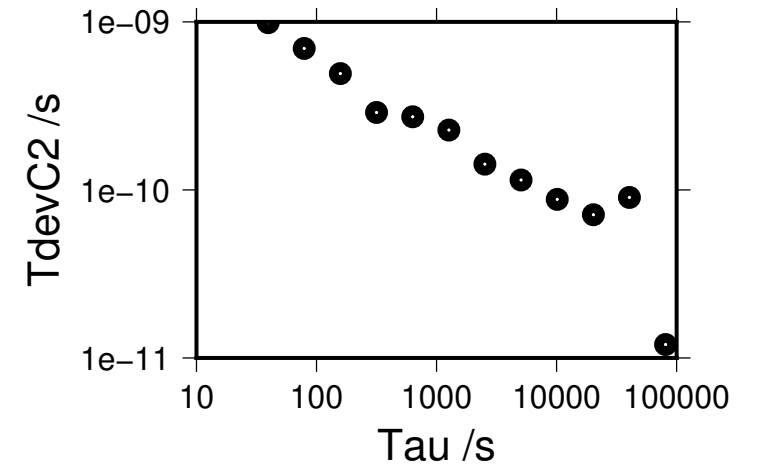
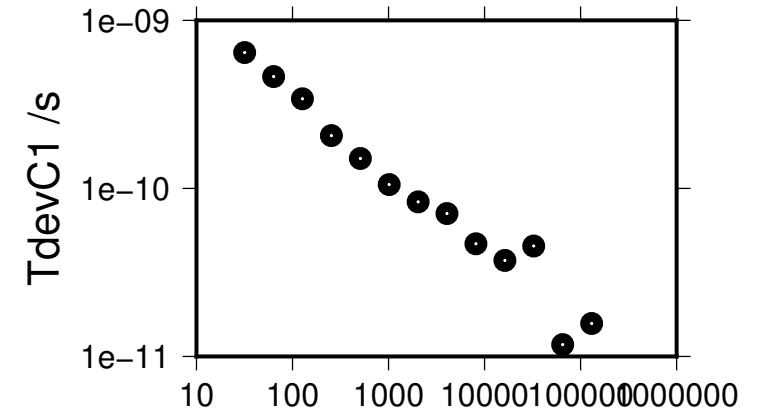
130075 s: P1= 14 ps	130075 s: P2= 17 ps
65038 s: P1= 15 ps	65038 s: P2= 28 ps
32519 s: P1= 48 ps	32519 s: P2= 64 ps
16259 s: P1= 41 ps	16259 s: P2= 85 ps
8130 s: P1= 58 ps	8130 s: P2= 92 ps
4065 s: P1= 63 ps	4065 s: P2= 95 ps
2032 s: P1= 88 ps	2032 s: P2= 129 ps
1016 s: P1= 122 ps	1016 s: P2= 166 ps
508 s: P1= 165 ps	508 s: P2= 233 ps
254 s: P1= 218 ps	254 s: P2= 309 ps
127 s: P1= 382 ps	127 s: P2= 495 ps
64 s: P1= 542 ps	64 s: P2= 688 ps
32 s: P1= 742 ps	32 s: P2= 962 ps



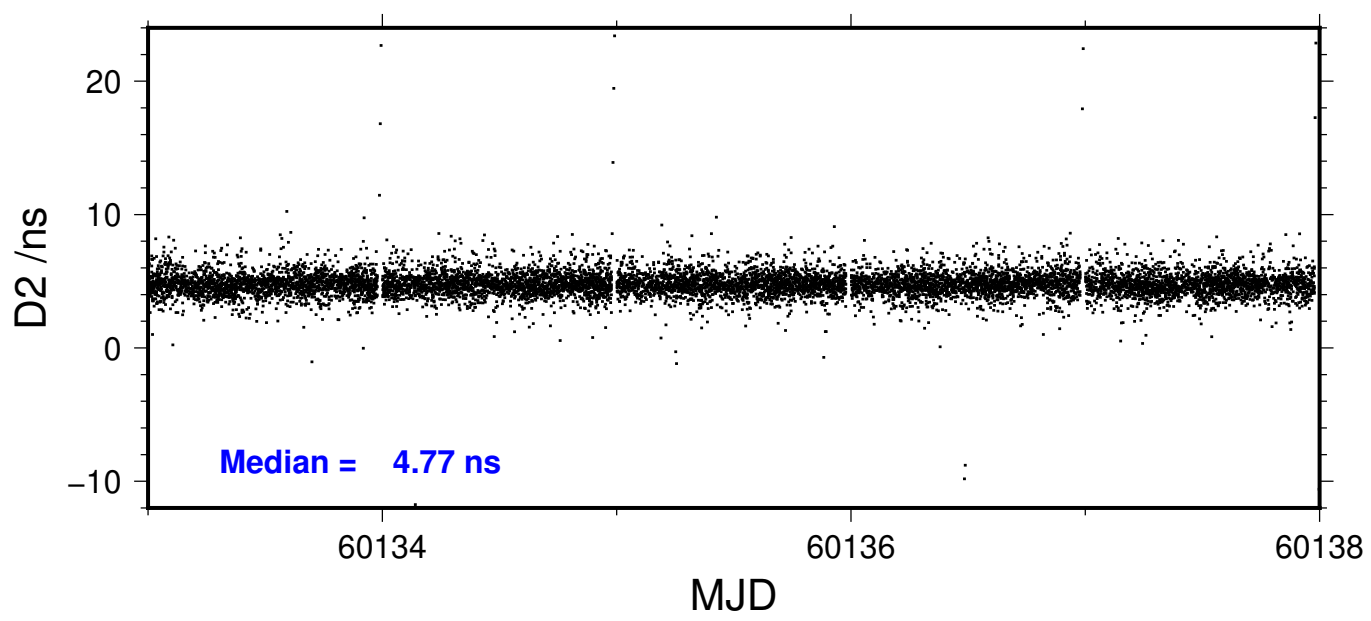
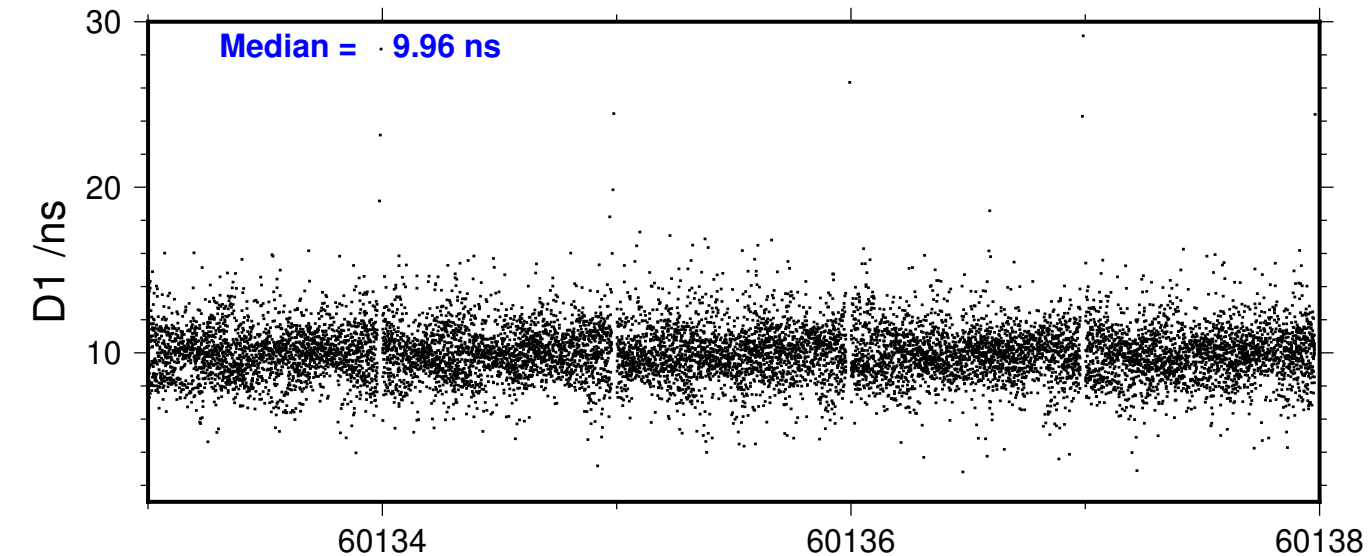
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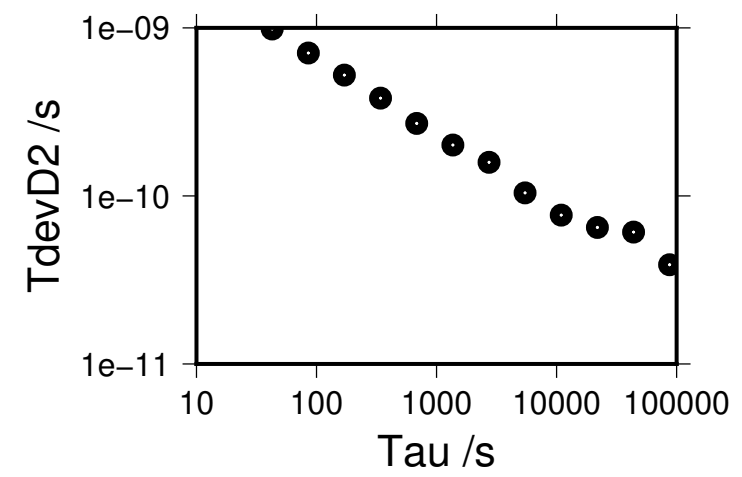
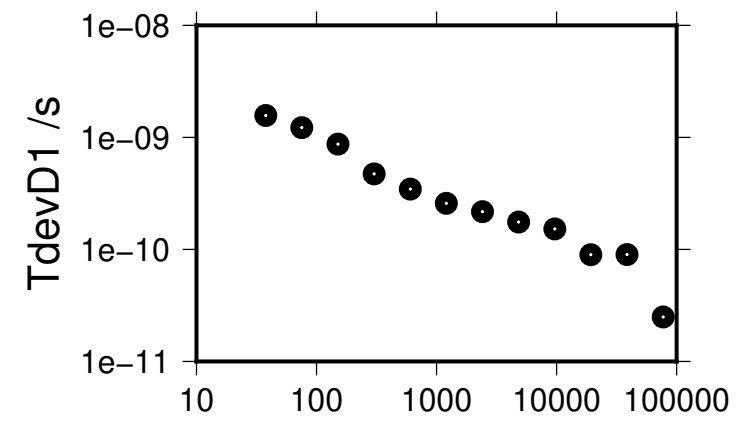
130075 s: C1= 16 ps	80956 s: C2= 12 ps
65038 s: C1= 12 ps	40478 s: C2= 90 ps
32519 s: C1= 45 ps	20239 s: C2= 71 ps
16259 s: C1= 37 ps	10120 s: C2= 88 ps
8130 s: C1= 47 ps	5060 s: C2= 115 ps
4065 s: C1= 71 ps	2530 s: C2= 142 ps
2032 s: C1= 83 ps	1265 s: C2= 227 ps
1016 s: C1= 105 ps	632 s: C2= 272 ps
508 s: C1= 151 ps	316 s: C2= 289 ps
254 s: C1= 206 ps	158 s: C2= 492 ps
127 s: C1= 342 ps	79 s: C2= 695 ps
64 s: C1= 463 ps	40 s: C2= 988 ps



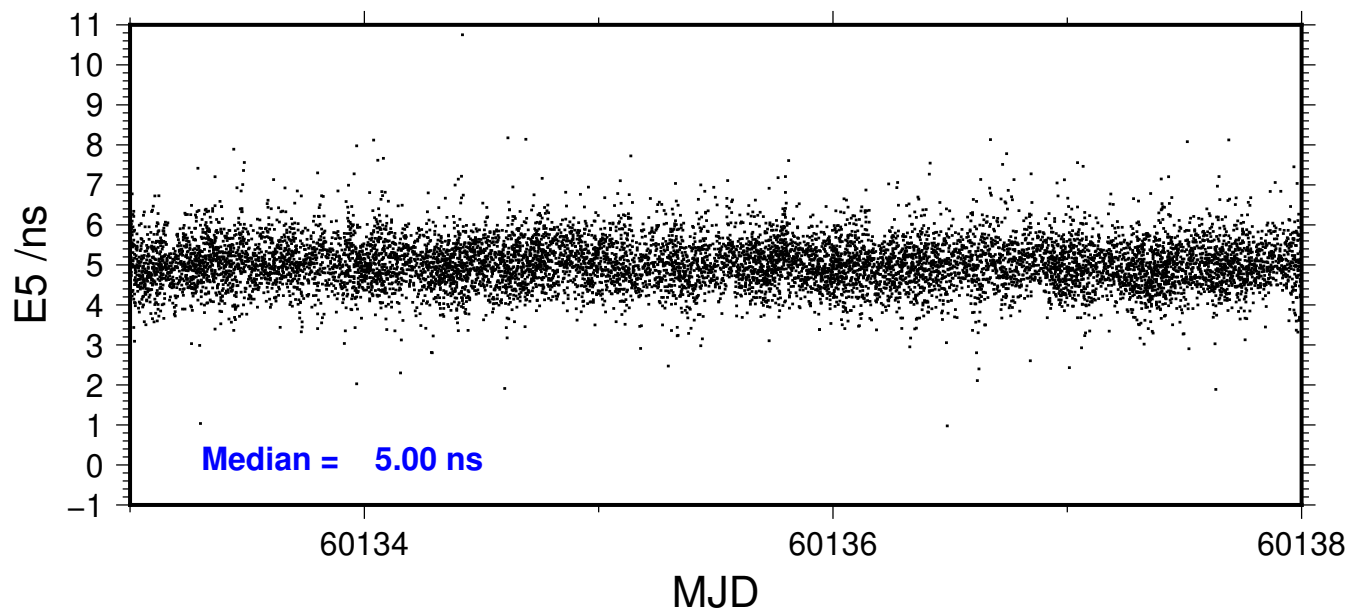
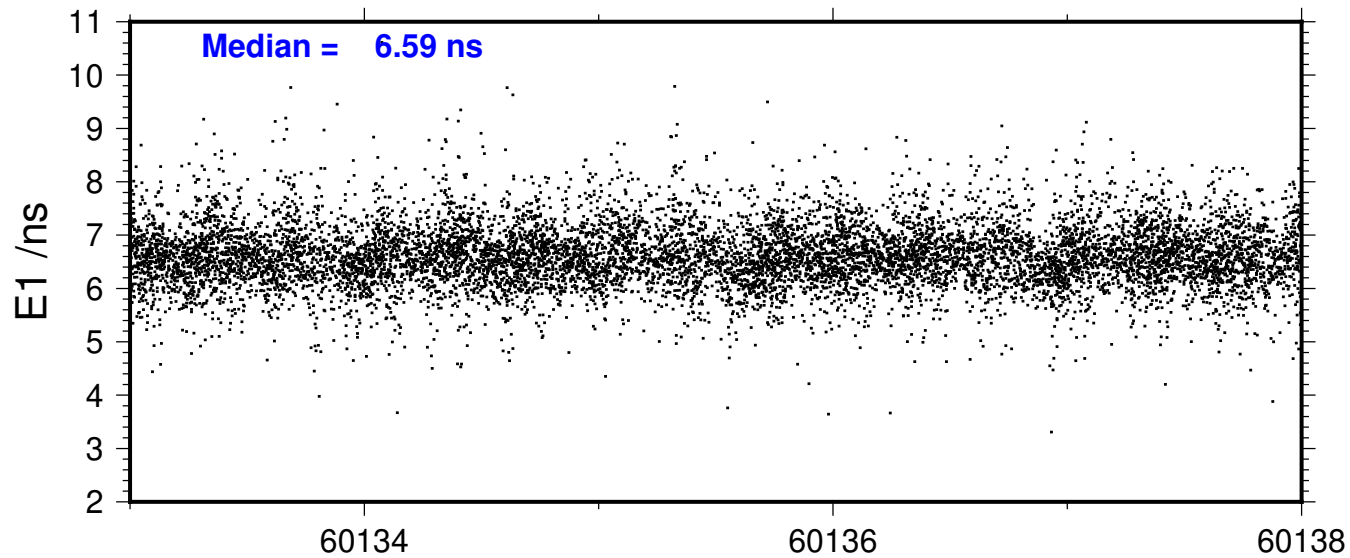
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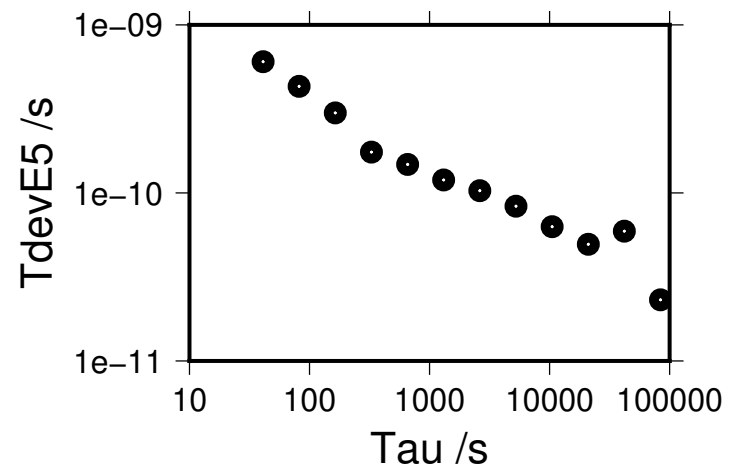
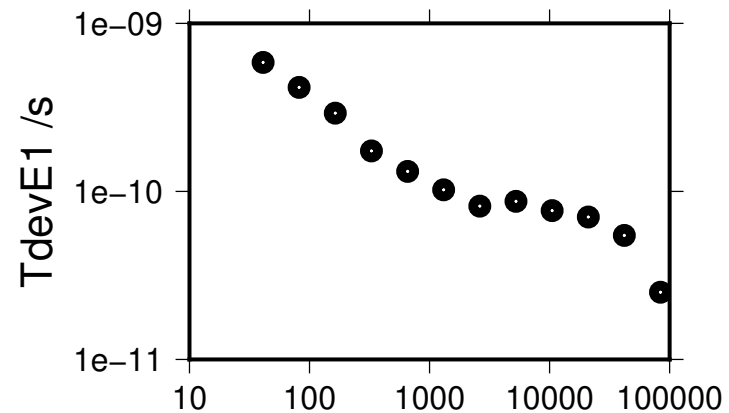
77277 s: D1= 25 ps	87468 s: D2= 39 ps
38638 s: D1= 90 ps	43734 s: D2= 61 ps
19319 s: D1= 90 ps	21867 s: D2= 65 ps
9660 s: D1= 153 ps	10933 s: D2= 77 ps
4830 s: D1= 175 ps	5467 s: D2= 104 ps
2415 s: D1= 217 ps	2733 s: D2= 159 ps
1207 s: D1= 258 ps	1367 s: D2= 201 ps
604 s: D1= 345 ps	683 s: D2= 270 ps
302 s: D1= 473 ps	342 s: D2= 382 ps
151 s: D1= 872 ps	171 s: D2= 524 ps
75 s: D1= 1221 ps	85 s: D2= 709 ps
38 s: D1= 1570 ps	43 s: D2= 985 ps



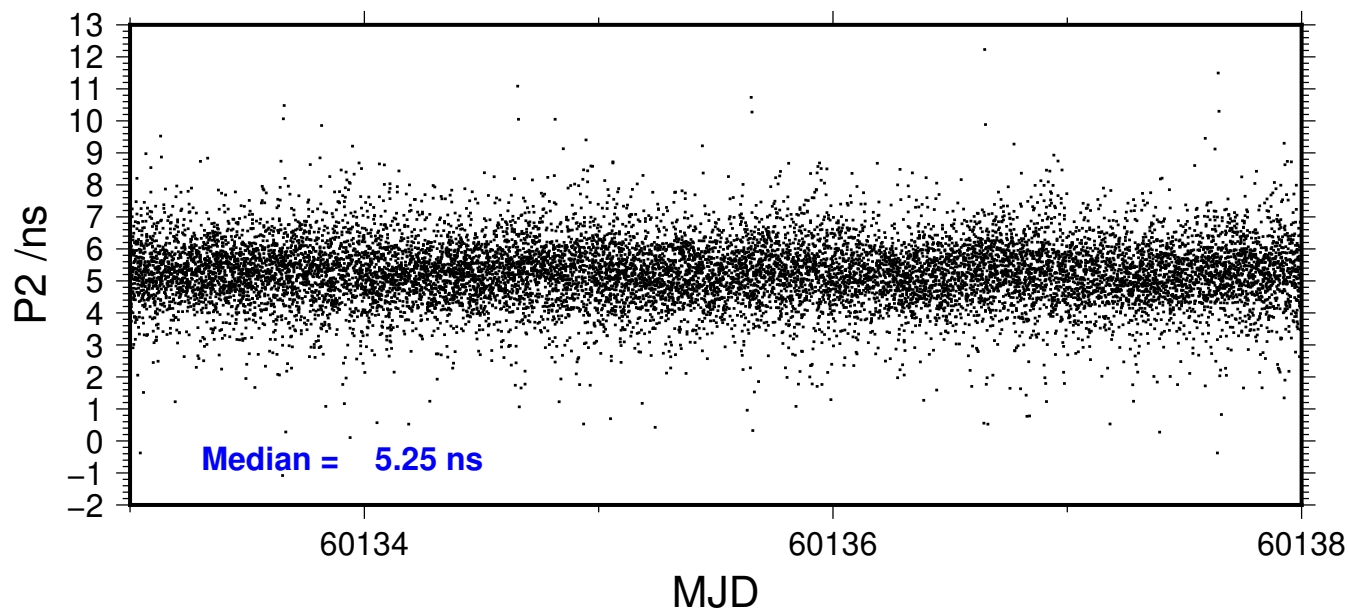
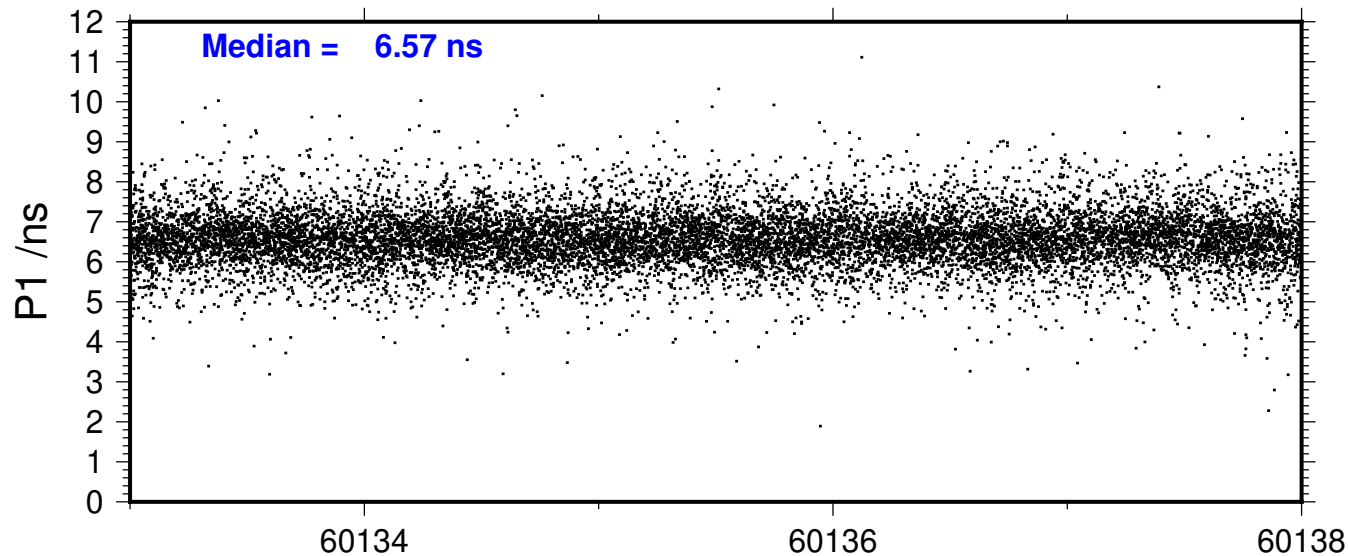
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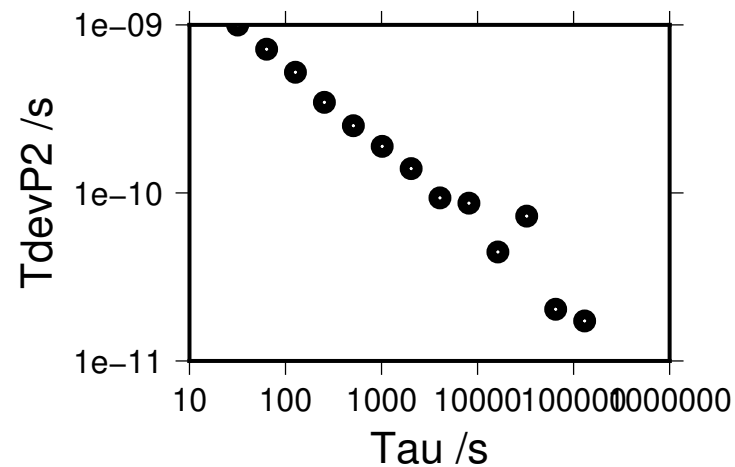
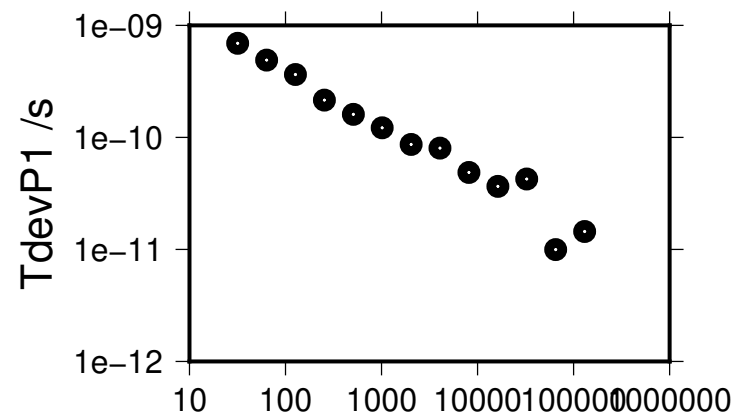
83978 s: E1= 25 ps	83962 s: E5= 23 ps
41989 s: E1= 55 ps	41981 s: E5= 59 ps
20995 s: E1= 70 ps	20991 s: E5= 49 ps
10497 s: E1= 77 ps	10495 s: E5= 63 ps
5249 s: E1= 87 ps	5248 s: E5= 83 ps
2624 s: E1= 82 ps	2624 s: E5= 103 ps
1312 s: E1= 102 ps	1312 s: E5= 120 ps
656 s: E1= 132 ps	656 s: E5= 148 ps
328 s: E1= 174 ps	328 s: E5= 175 ps
164 s: E1= 292 ps	164 s: E5= 299 ps
82 s: E1= 416 ps	82 s: E5= 431 ps
41 s: E1= 586 ps	41 s: E5= 604 ps



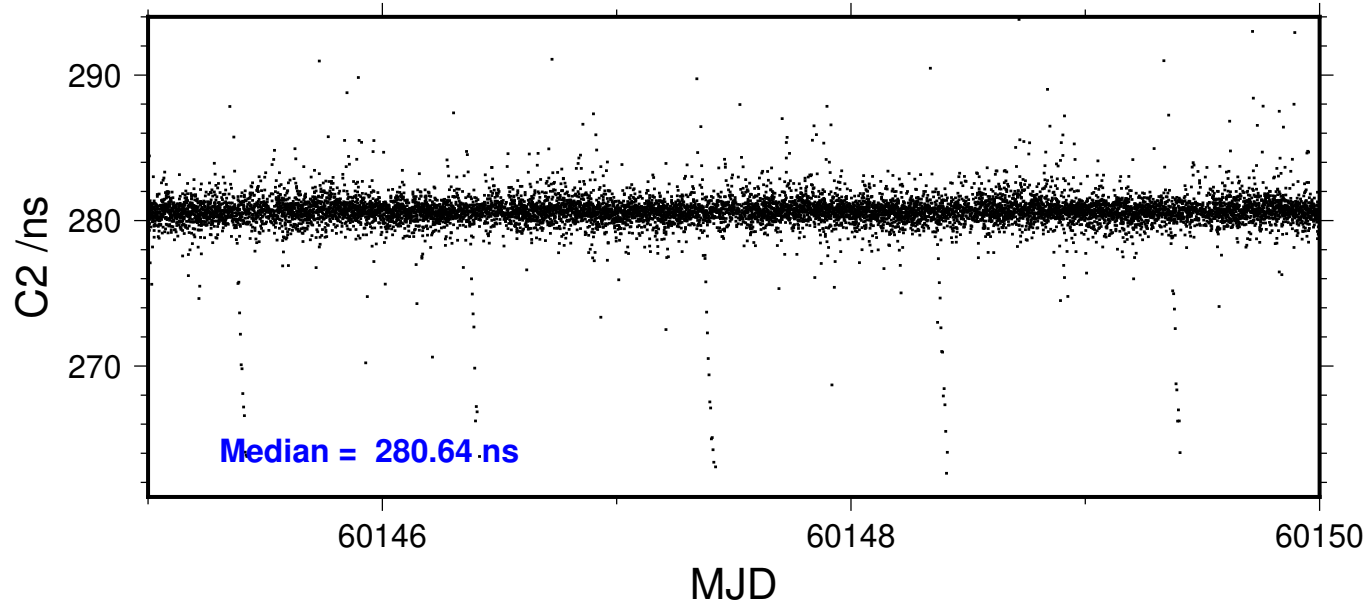
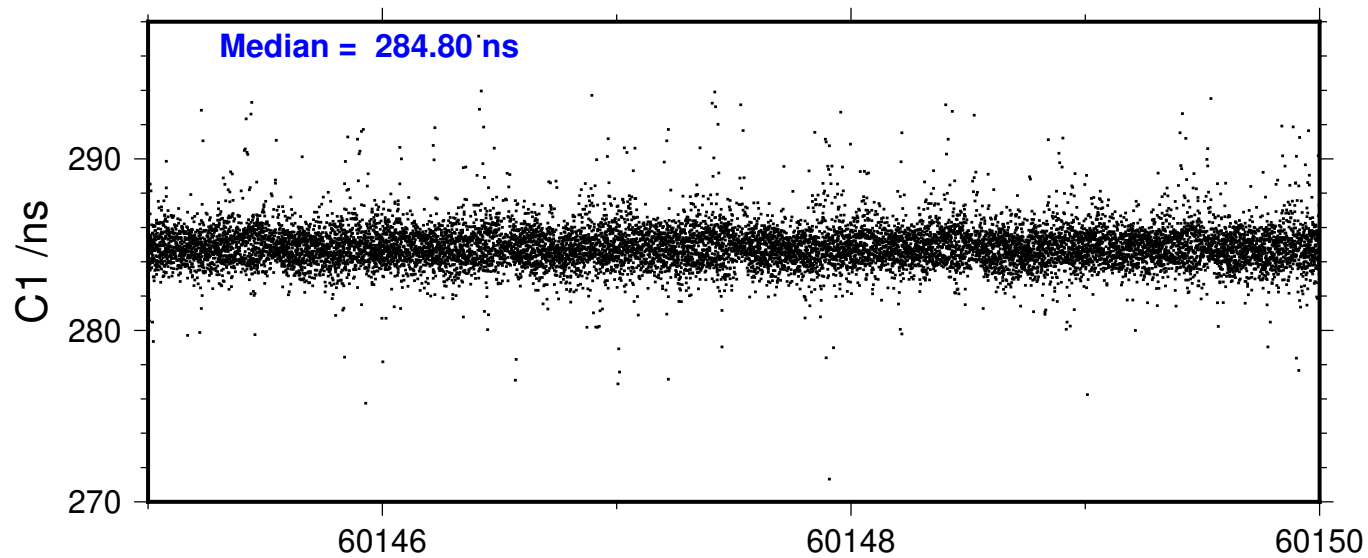
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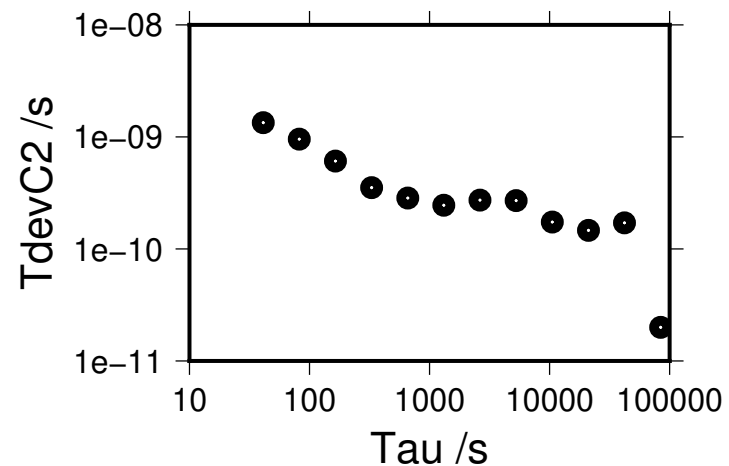
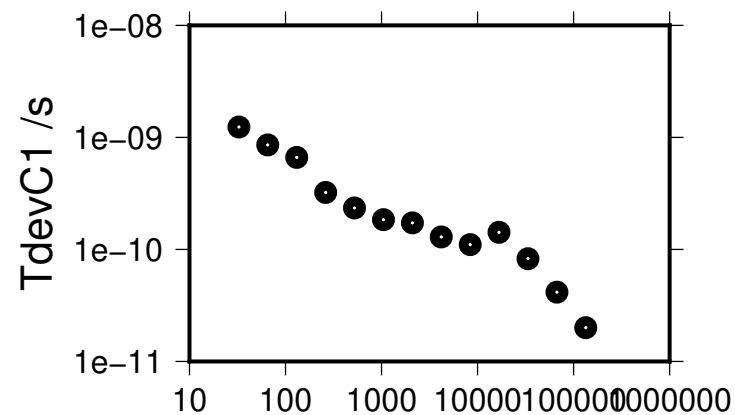
130075 s: P1= 14 ps	130075 s: P2= 17 ps
65038 s: P1= 10 ps	65038 s: P2= 20 ps
32519 s: P1= 43 ps	32519 s: P2= 73 ps
16259 s: P1= 37 ps	16259 s: P2= 45 ps
8130 s: P1= 49 ps	8130 s: P2= 87 ps
4065 s: P1= 80 ps	4065 s: P2= 93 ps
2032 s: P1= 87 ps	2032 s: P2= 140 ps
1016 s: P1= 122 ps	1016 s: P2= 189 ps
508 s: P1= 161 ps	508 s: P2= 251 ps
254 s: P1= 215 ps	254 s: P2= 346 ps
127 s: P1= 365 ps	127 s: P2= 523 ps
64 s: P1= 490 ps	64 s: P2= 716 ps
32 s: P1= 692 ps	32 s: P2= 997 ps



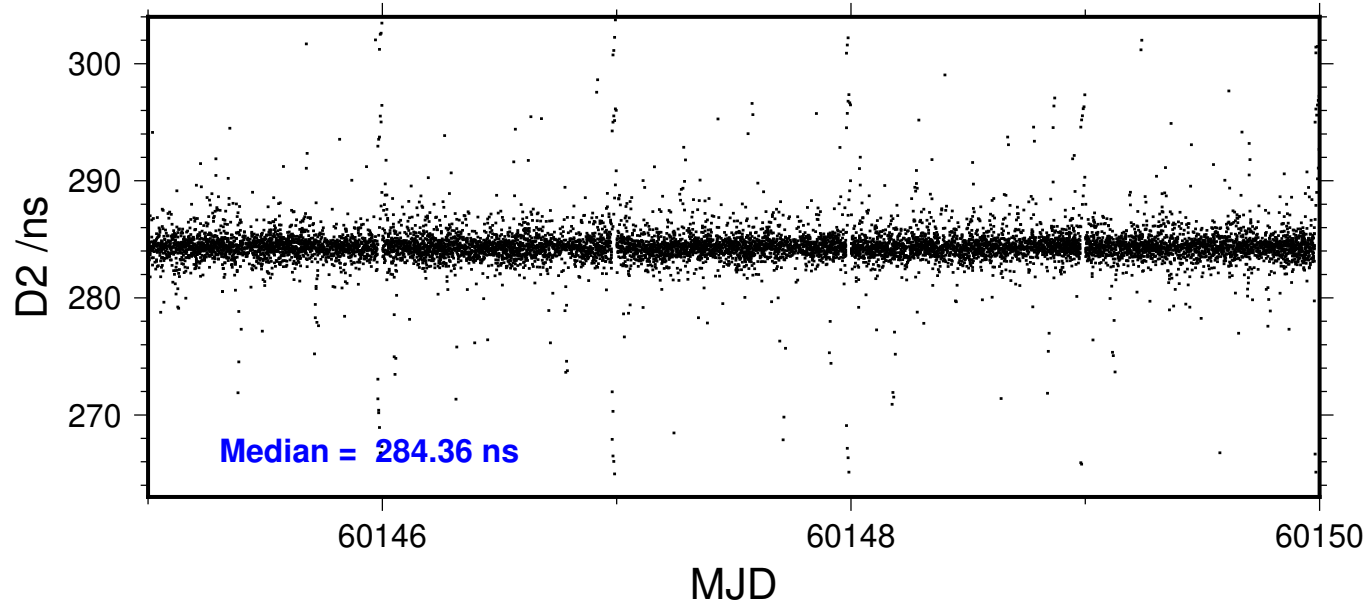
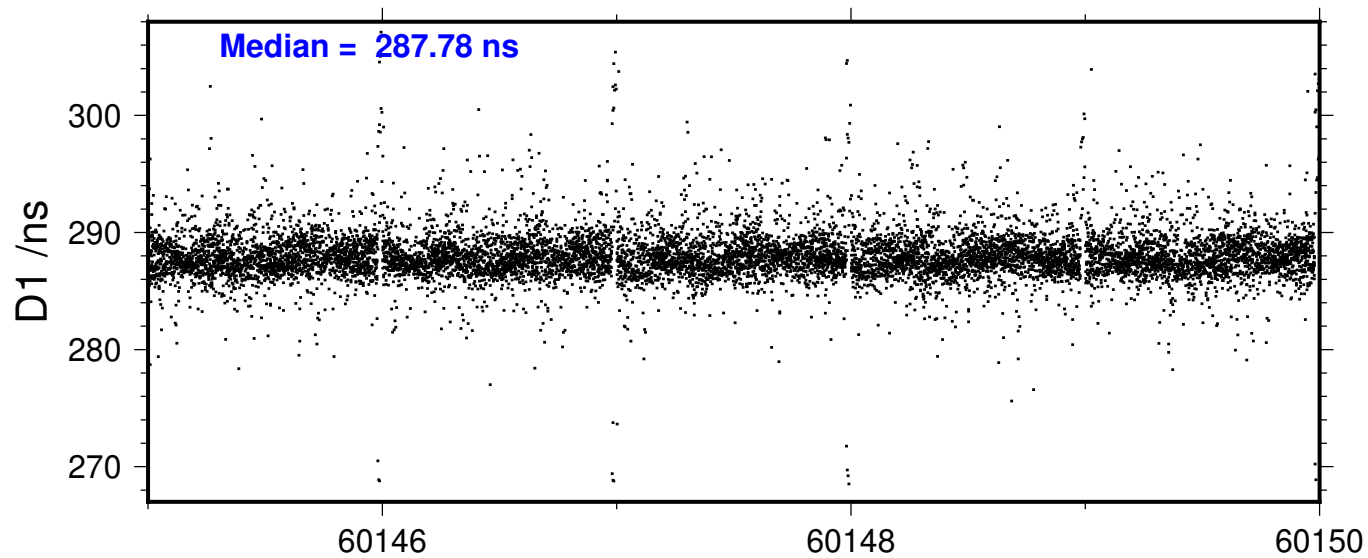
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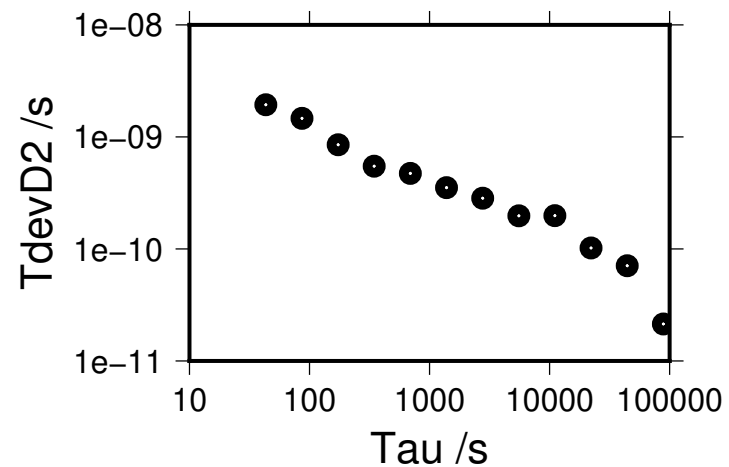
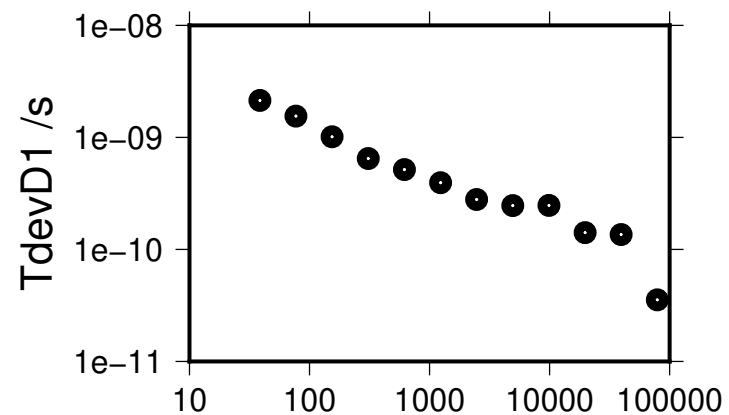
133978 s: C1= 20 ps	
66989 s: C1= 42 ps	84226 s: C2= 20 ps
33495 s: C1= 83 ps	42113 s: C2= 171 ps
16747 s: C1= 142 ps	21057 s: C2= 146 ps
8374 s: C1= 110 ps	10528 s: C2= 174 ps
4187 s: C1= 129 ps	5264 s: C2= 270 ps
2093 s: C1= 172 ps	2632 s: C2= 272 ps
1047 s: C1= 185 ps	1316 s: C2= 246 ps
523 s: C1= 234 ps	658 s: C2= 284 ps
262 s: C1= 323 ps	329 s: C2= 353 ps
131 s: C1= 664 ps	164 s: C2= 609 ps
65 s: C1= 856 ps	82 s: C2= 954 ps
33 s: C1= 1240 ps	41 s: C2= 1339 ps



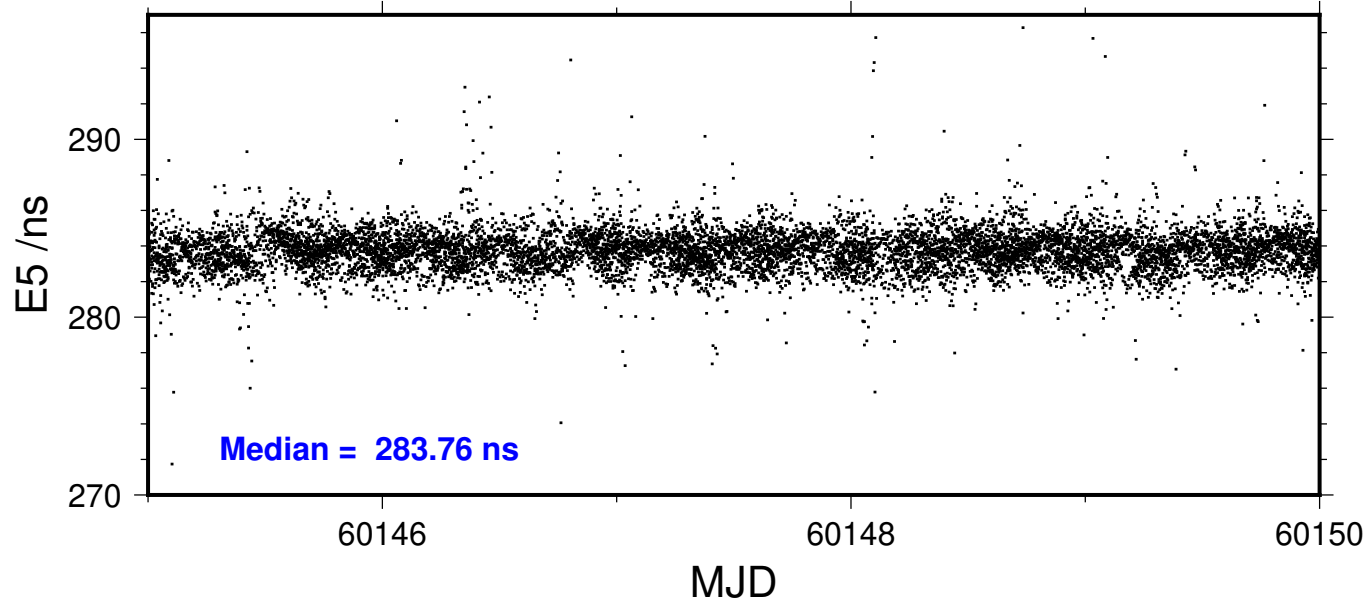
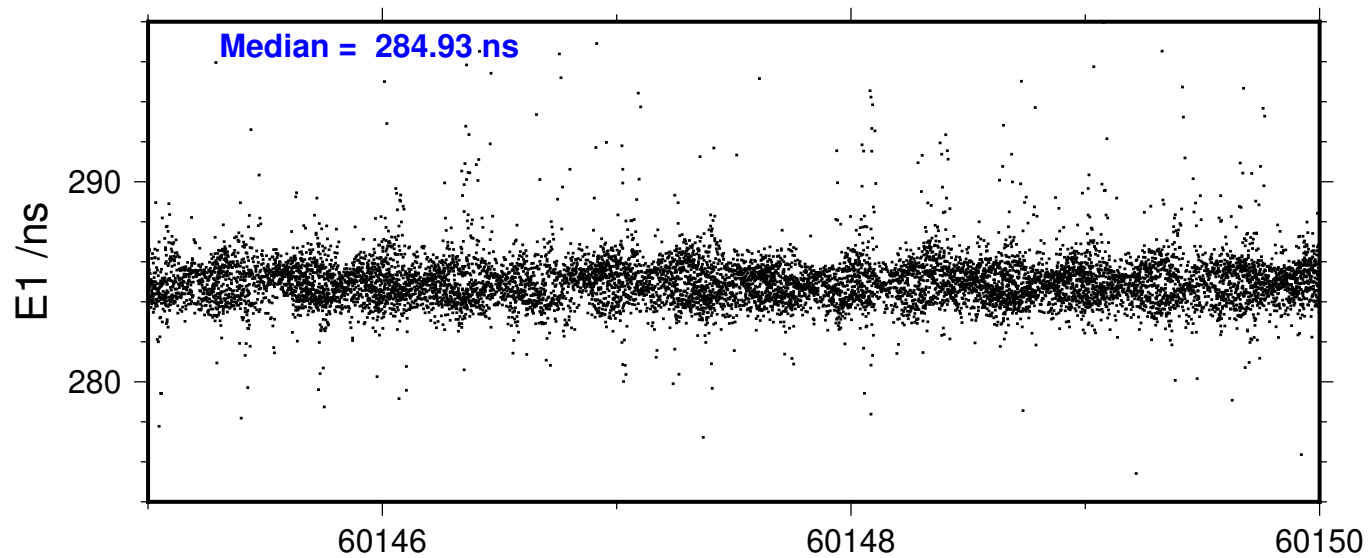
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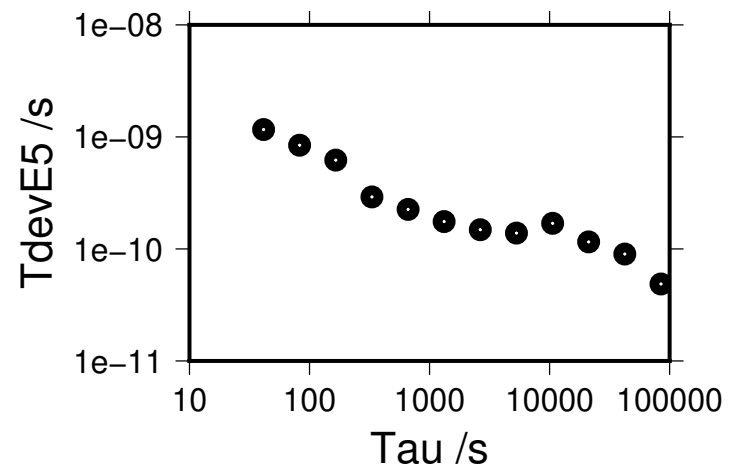
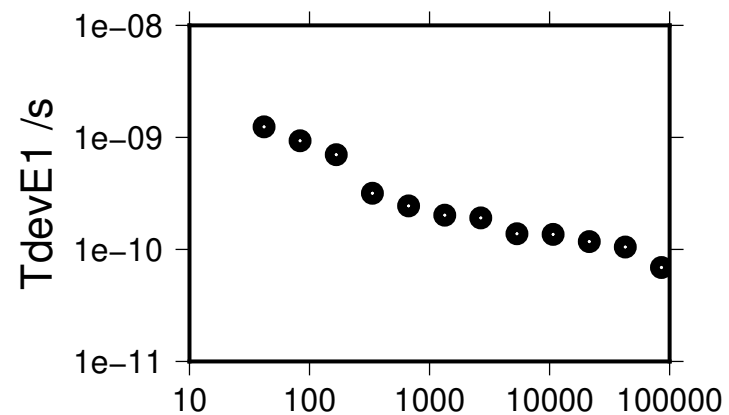
78996 s: D1= 35 ps	88616 s: D2= 21 ps
39498 s: D1= 136 ps	44308 s: D2= 71 ps
19749 s: D1= 141 ps	22154 s: D2= 102 ps
9874 s: D1= 247 ps	11077 s: D2= 198 ps
4937 s: D1= 246 ps	5538 s: D2= 197 ps
2469 s: D1= 279 ps	2769 s: D2= 283 ps
1234 s: D1= 395 ps	1385 s: D2= 352 ps
617 s: D1= 516 ps	692 s: D2= 472 ps
309 s: D1= 648 ps	346 s: D2= 548 ps
154 s: D1= 1013 ps	173 s: D2= 850 ps
77 s: D1= 1549 ps	87 s: D2= 1464 ps
39 s: D1= 2140 ps	43 s: D2= 1938 ps



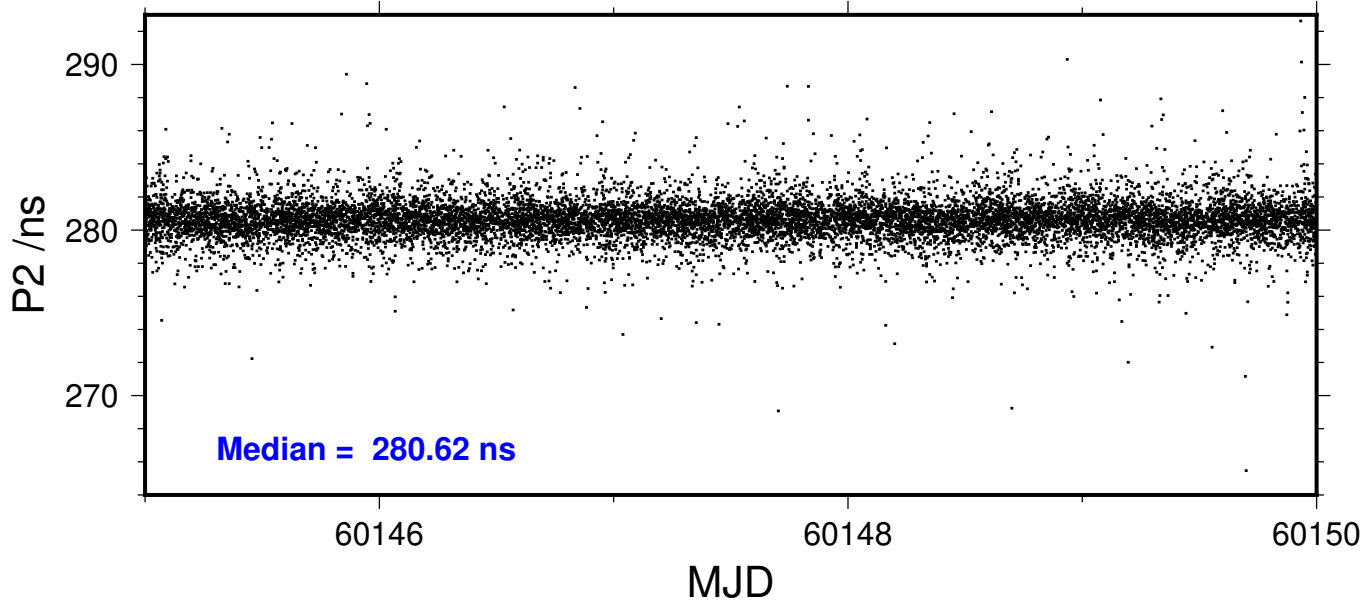
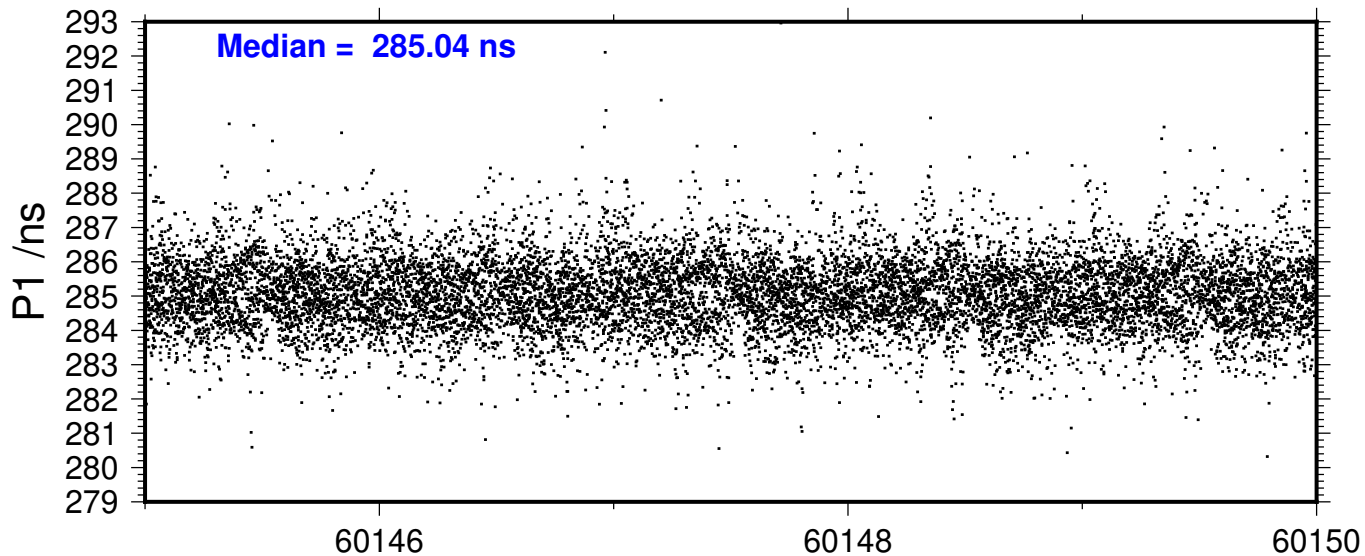
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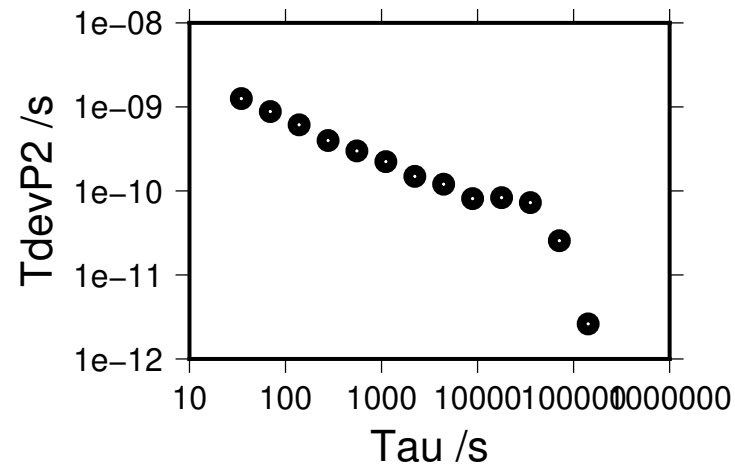
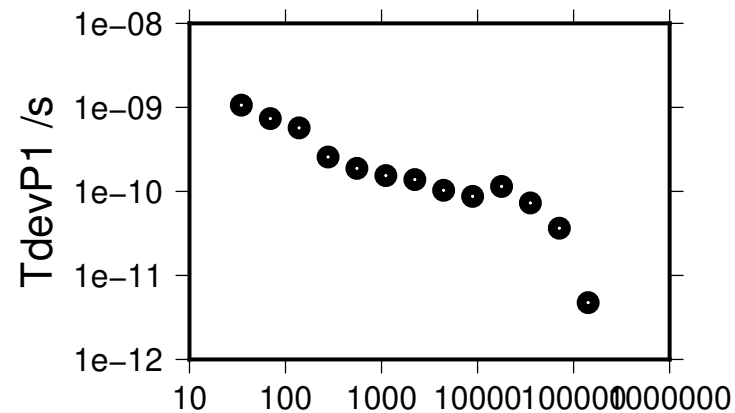
85546 s: E1= 69 ps	84727 s: E5= 49 ps
42773 s: E1= 105 ps	42363 s: E5= 90 ps
21387 s: E1= 118 ps	21182 s: E5= 116 ps
10693 s: E1= 136 ps	10591 s: E5= 169 ps
5347 s: E1= 138 ps	5295 s: E5= 139 ps
2673 s: E1= 191 ps	2648 s: E5= 149 ps
1337 s: E1= 202 ps	1324 s: E5= 175 ps
668 s: E1= 245 ps	662 s: E5= 226 ps
334 s: E1= 317 ps	331 s: E5= 291 ps
167 s: E1= 702 ps	165 s: E5= 620 ps
84 s: E1= 932 ps	83 s: E5= 844 ps
42 s: E1= 1243 ps	41 s: E5= 1163 ps



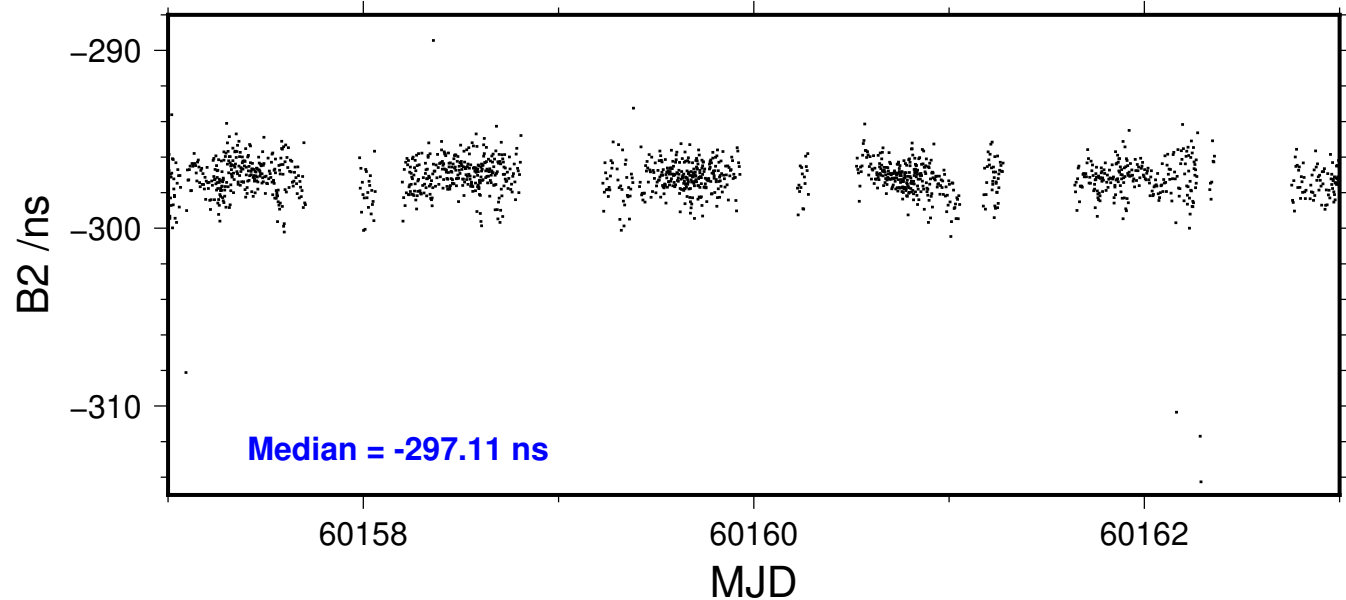
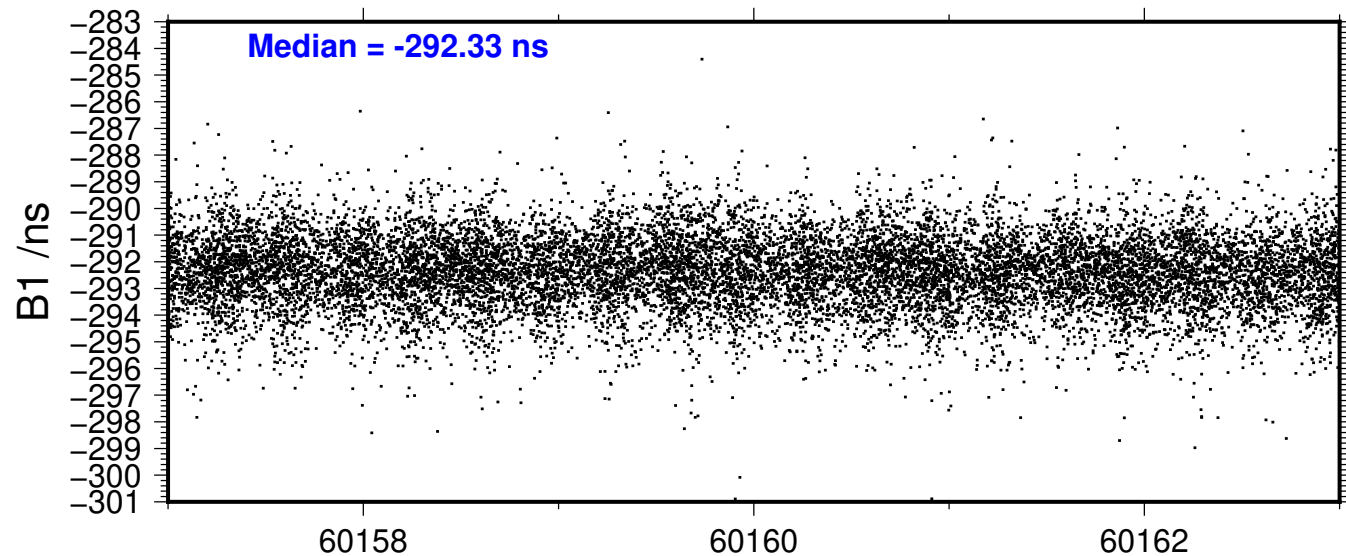
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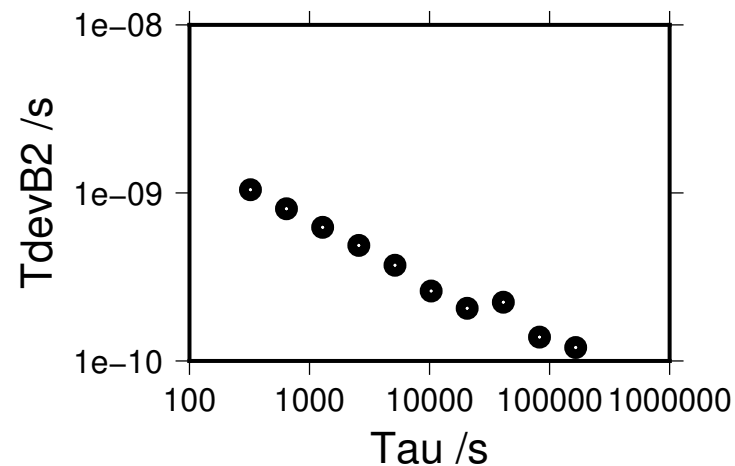
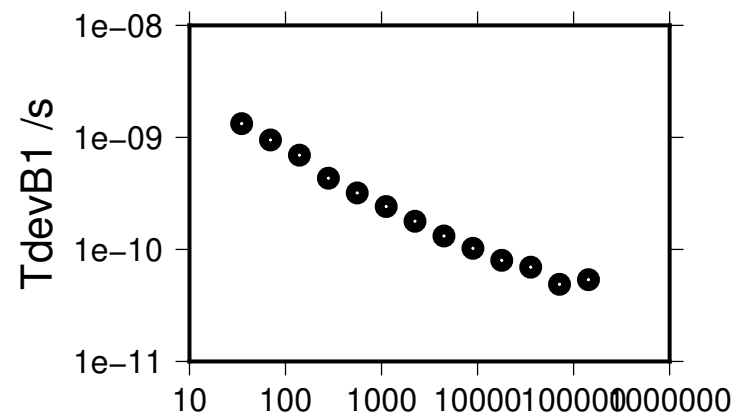
142005 s: P1= 5 ps	142005 s: P2= 3 ps
71002 s: P1= 37 ps	71002 s: P2= 26 ps
35501 s: P1= 73 ps	35501 s: P2= 73 ps
17751 s: P1= 115 ps	17751 s: P2= 83 ps
8875 s: P1= 87 ps	8875 s: P2= 81 ps
4438 s: P1= 103 ps	4438 s: P2= 120 ps
2219 s: P1= 139 ps	2219 s: P2= 149 ps
1109 s: P1= 155 ps	1109 s: P2= 223 ps
555 s: P1= 188 ps	555 s: P2= 299 ps
277 s: P1= 256 ps	277 s: P2= 398 ps
139 s: P1= 571 ps	139 s: P2= 613 ps
69 s: P1= 737 ps	69 s: P2= 882 ps
35 s: P1= 1062 ps	35 s: P2= 1255 ps



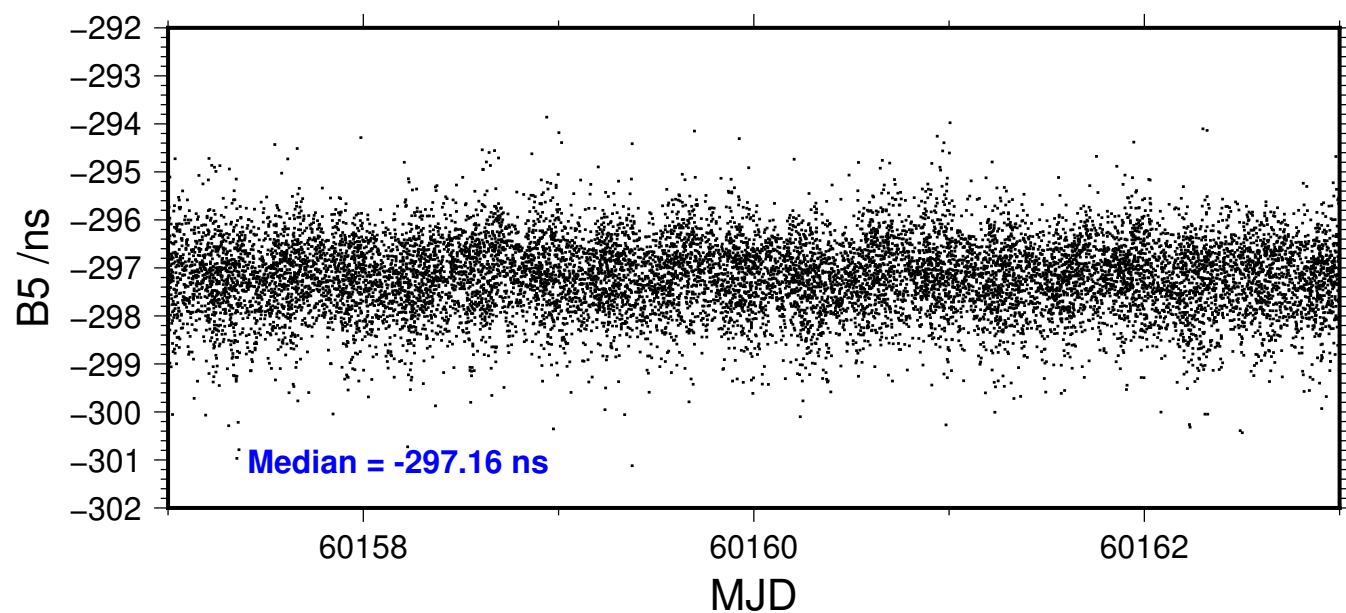
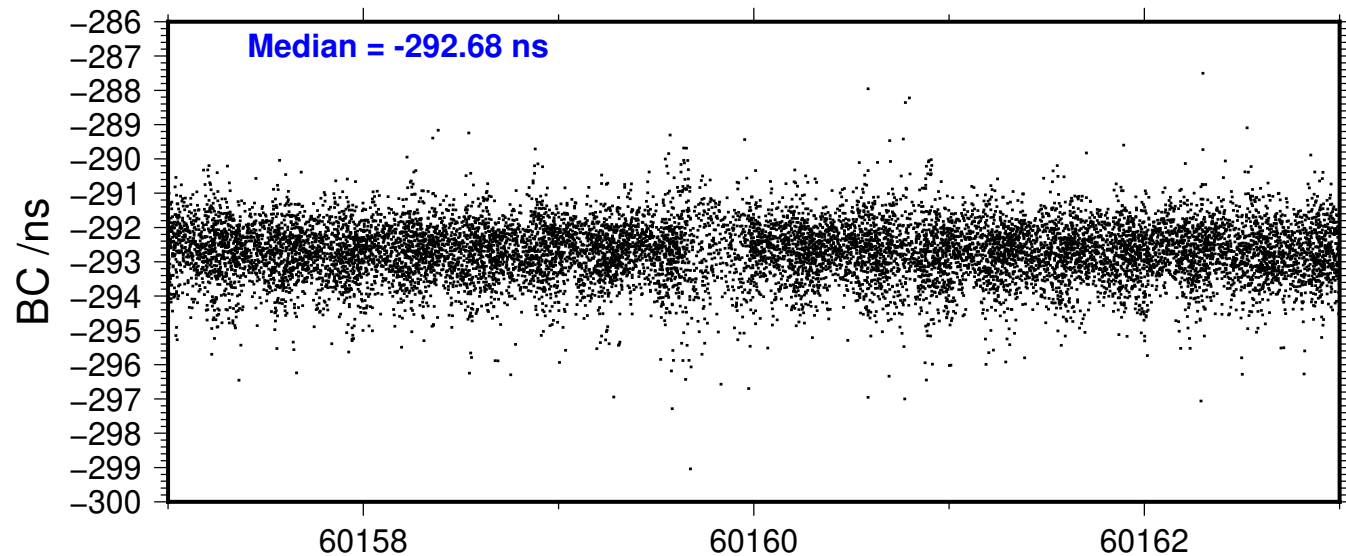
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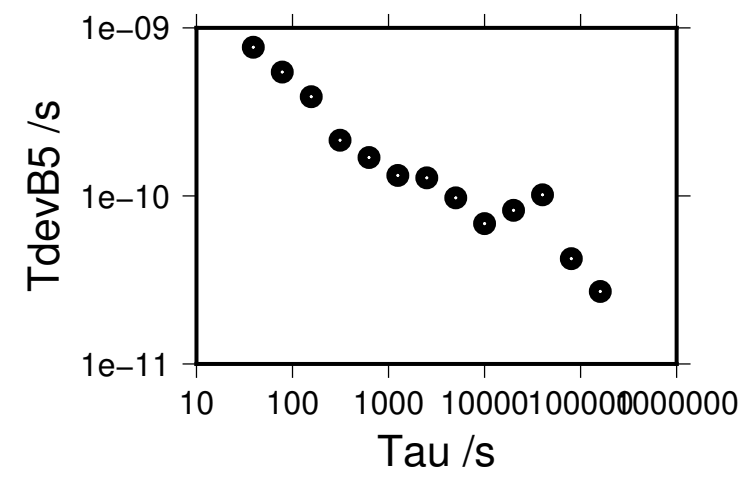
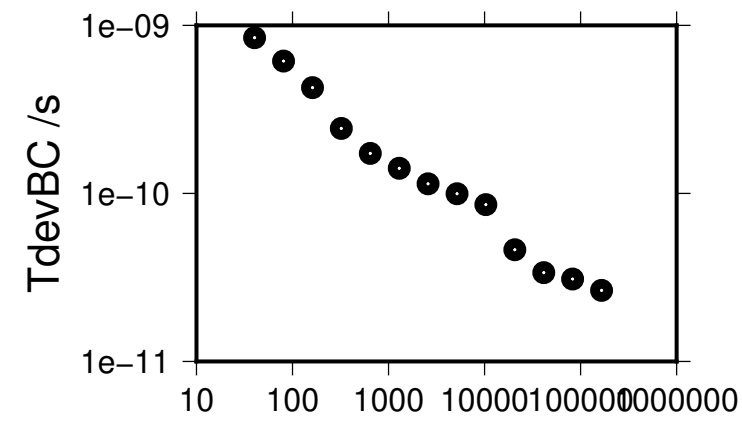
142943 s: B1=	54 ps	164762 s: B2=	120 ps
71472 s: B1=	49 ps	82381 s: B2=	139 ps
35736 s: B1=	69 ps	41191 s: B2=	224 ps
17868 s: B1=	80 ps	20595 s: B2=	206 ps
8934 s: B1=	102 ps	10298 s: B2=	261 ps
4467 s: B1=	132 ps	5149 s: B2=	371 ps
2233 s: B1=	178 ps	2574 s: B2=	487 ps
1117 s: B1=	241 ps	1287 s: B2=	624 ps
558 s: B1=	319 ps	644 s: B2=	804 ps
279 s: B1=	432 ps	322 s: B2=	1045 ps
140 s: B1=	694 ps		
70 s: B1=	950 ps		
35 s: B1=	1326 ps		



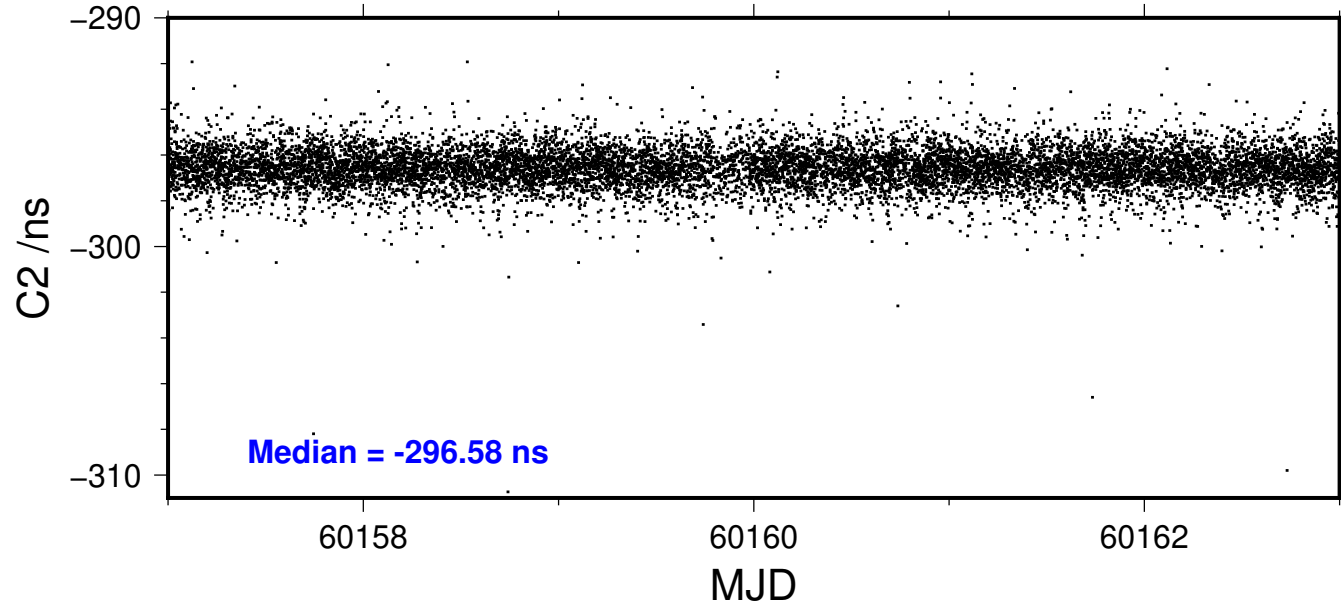
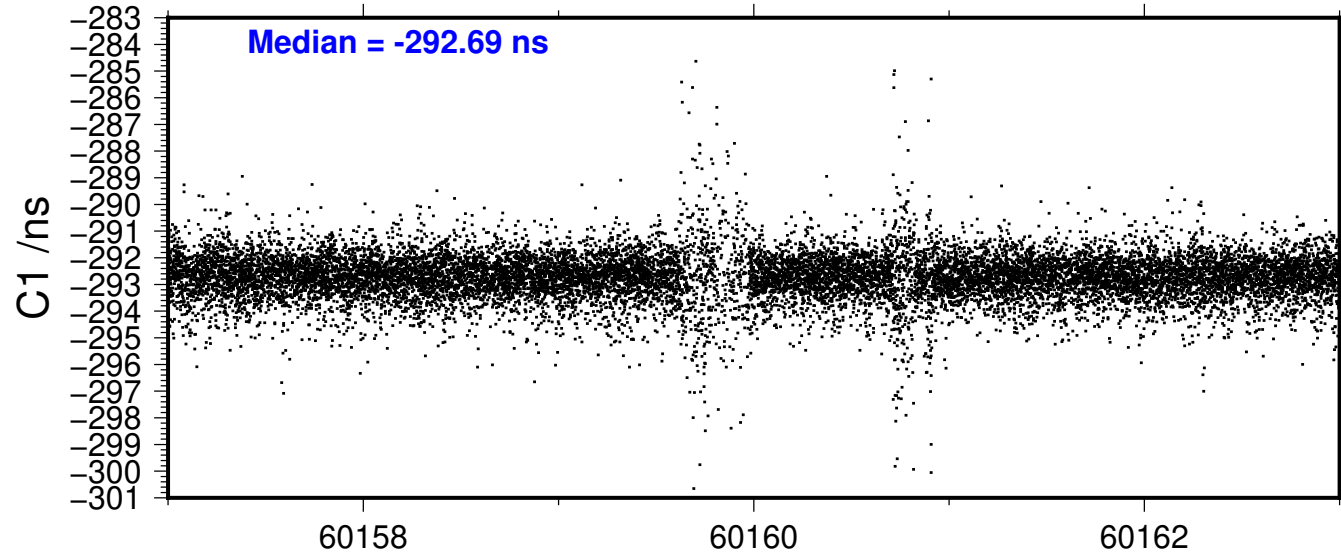
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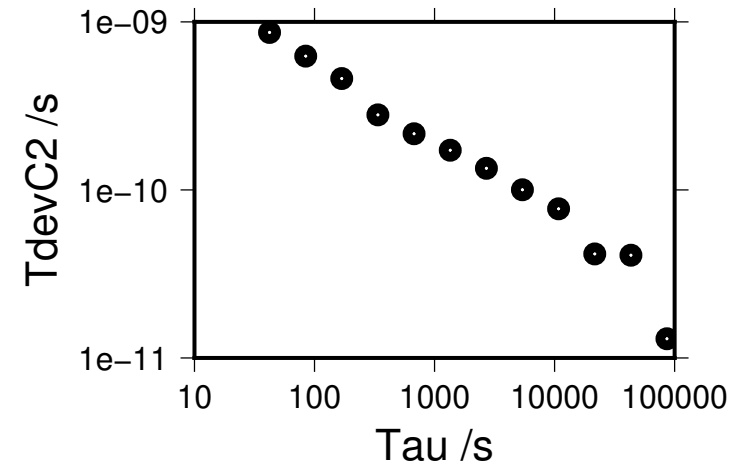
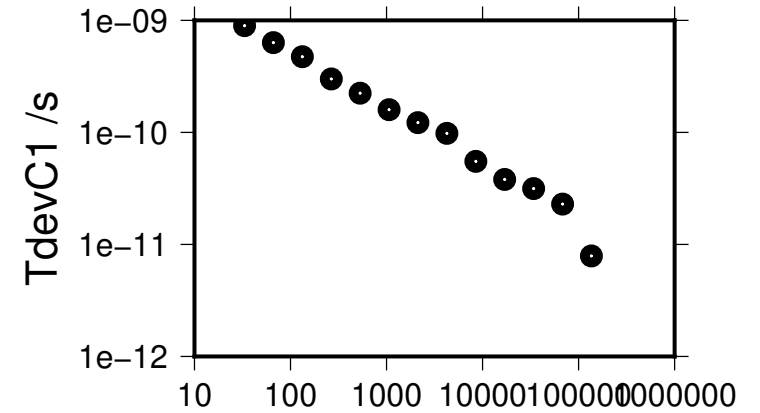
165237 s: BC= 26 ps	160210 s: B5= 27 ps
82618 s: BC= 31 ps	80105 s: B5= 42 ps
41309 s: BC= 34 ps	40052 s: B5= 102 ps
20655 s: BC= 46 ps	20026 s: B5= 82 ps
10327 s: BC= 86 ps	10013 s: B5= 68 ps
5164 s: BC= 99 ps	5007 s: B5= 97 ps
2582 s: BC= 114 ps	2503 s: B5= 128 ps
1291 s: BC= 141 ps	1252 s: B5= 132 ps
645 s: BC= 173 ps	626 s: B5= 169 ps
323 s: BC= 244 ps	313 s: B5= 215 ps
161 s: BC= 426 ps	156 s: B5= 389 ps
81 s: BC= 613 ps	78 s: B5= 545 ps
40 s: BC= 845 ps	39 s: B5= 766 ps



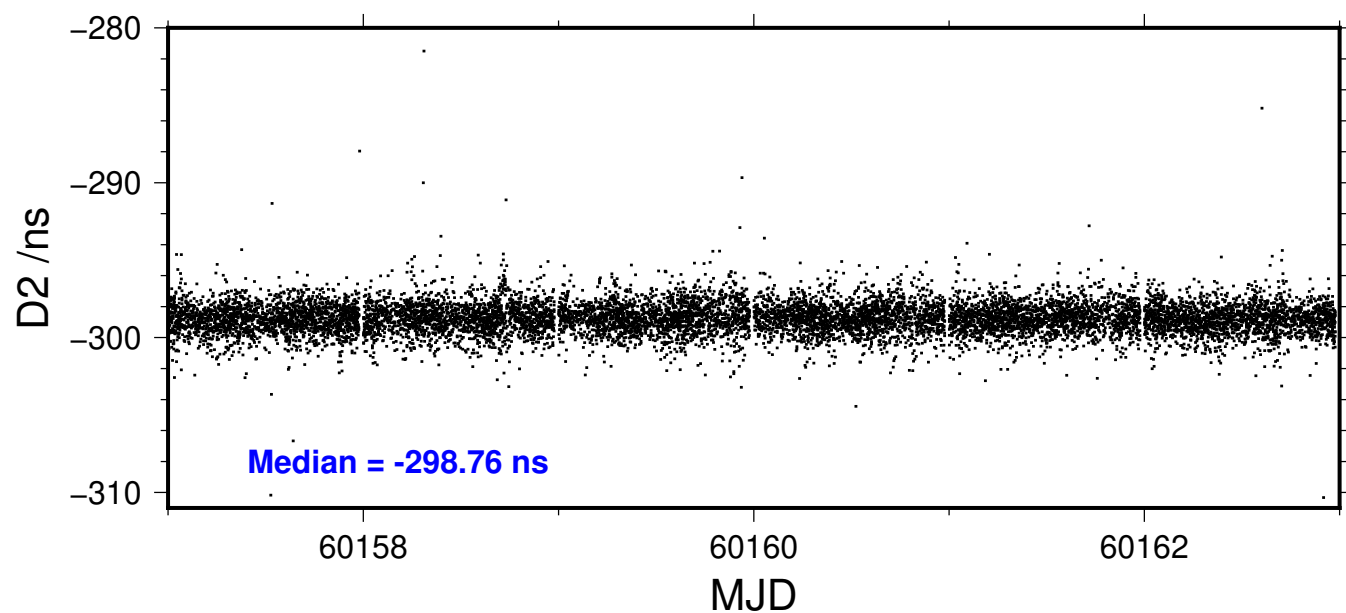
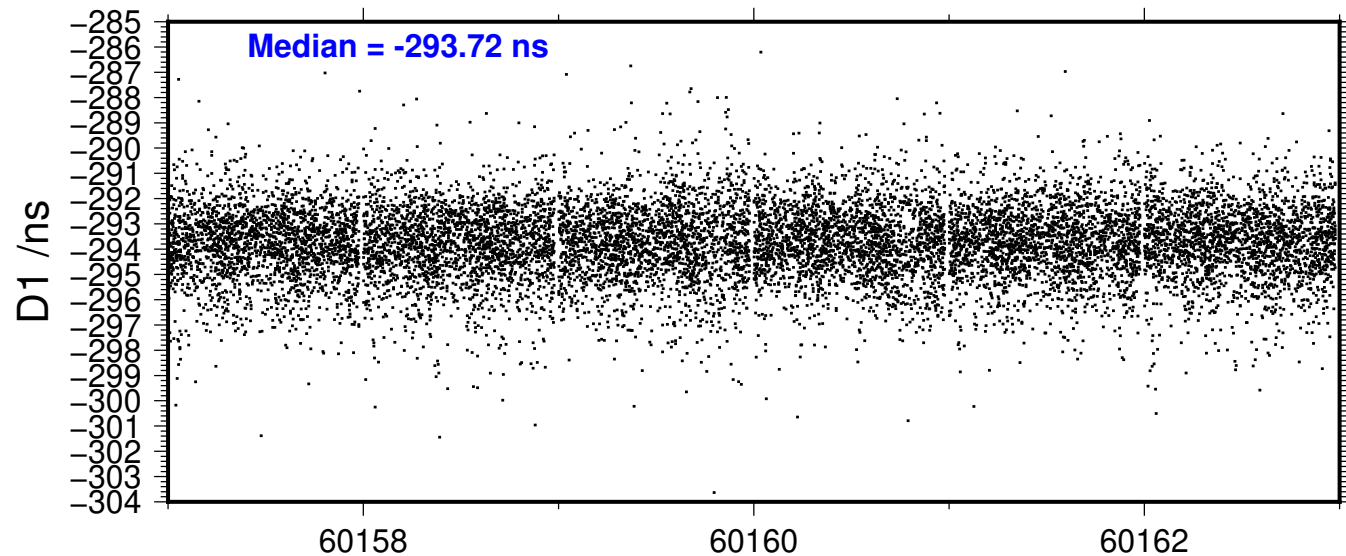
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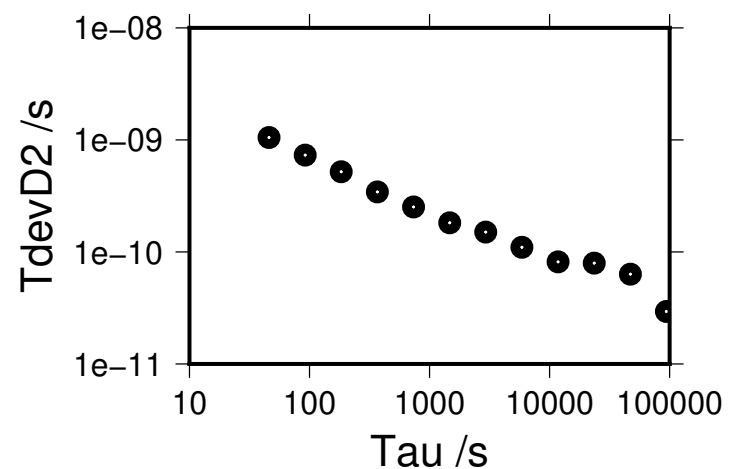
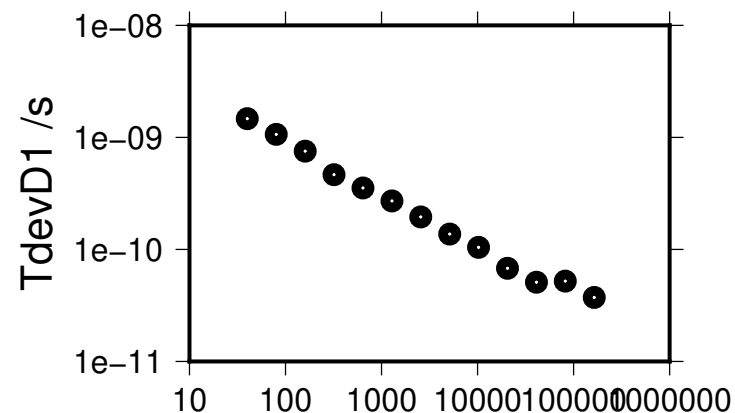
136043 s: C1=	8 ps	86399 s: C2=	13 ps
68022 s: C1=	23 ps	43200 s: C2=	41 ps
34011 s: C1=	32 ps	21600 s: C2=	42 ps
17005 s: C1=	38 ps	10800 s: C2=	77 ps
8503 s: C1=	55 ps	5400 s: C2=	100 ps
4251 s: C1=	98 ps	2700 s: C2=	134 ps
2126 s: C1=	122 ps	1350 s: C2=	172 ps
1063 s: C1=	160 ps	675 s: C2=	216 ps
531 s: C1=	224 ps	338 s: C2=	280 ps
266 s: C1=	300 ps	169 s: C2=	461 ps
133 s: C1=	473 ps	84 s: C2=	626 ps
66 s: C1=	634 ps	42 s: C2=	865 ps
33 s: C1=	899 ps		



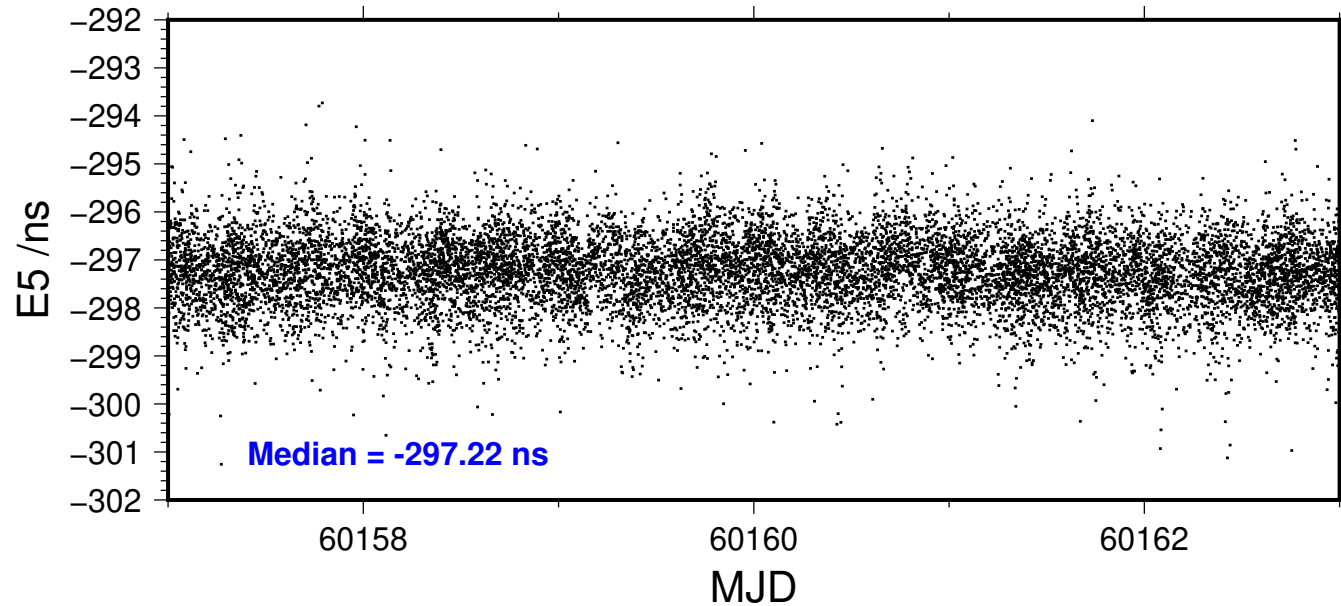
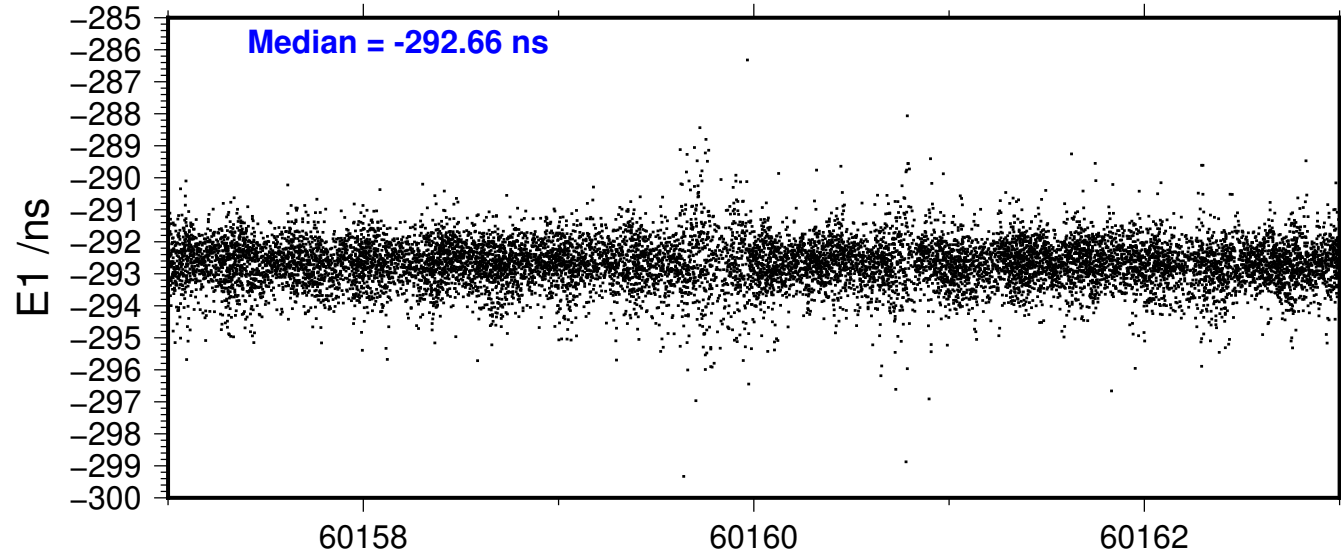
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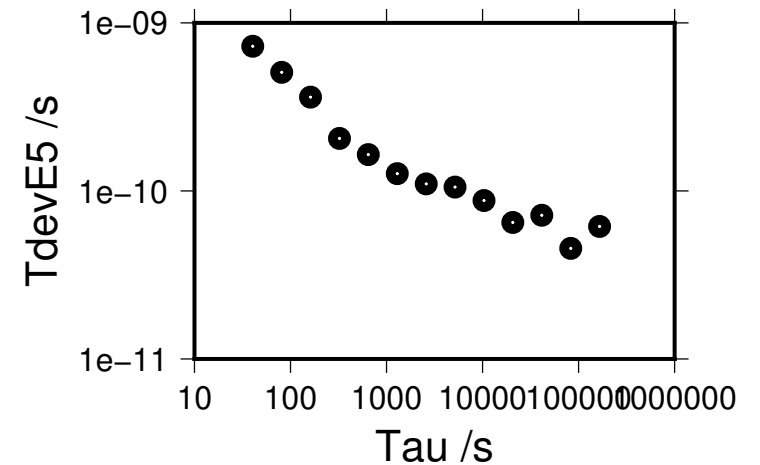
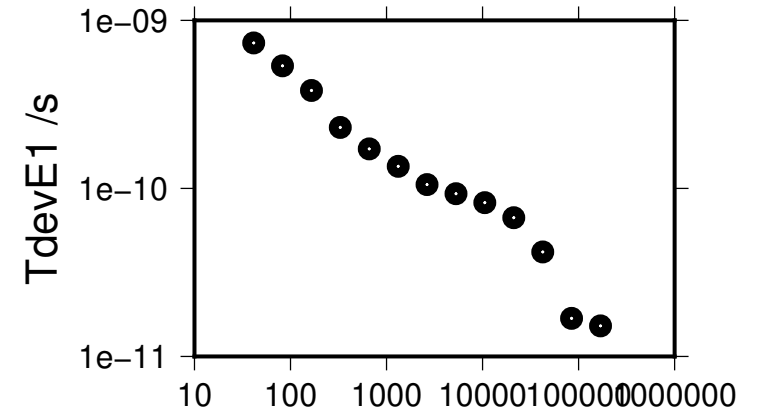
164024 s: D1= 37 ps	94133 s: D2= 29 ps
82012 s: D1= 52 ps	47067 s: D2= 63 ps
41006 s: D1= 51 ps	23533 s: D2= 79 ps
20503 s: D1= 68 ps	11767 s: D2= 81 ps
10251 s: D1= 104 ps	5883 s: D2= 110 ps
5126 s: D1= 137 ps	2942 s: D2= 150 ps
2563 s: D1= 195 ps	1471 s: D2= 182 ps
1281 s: D1= 271 ps	735 s: D2= 252 ps
641 s: D1= 353 ps	368 s: D2= 343 ps
320 s: D1= 465 ps	184 s: D2= 520 ps
160 s: D1= 755 ps	92 s: D2= 732 ps
80 s: D1= 1065 ps	46 s: D2= 1050 ps



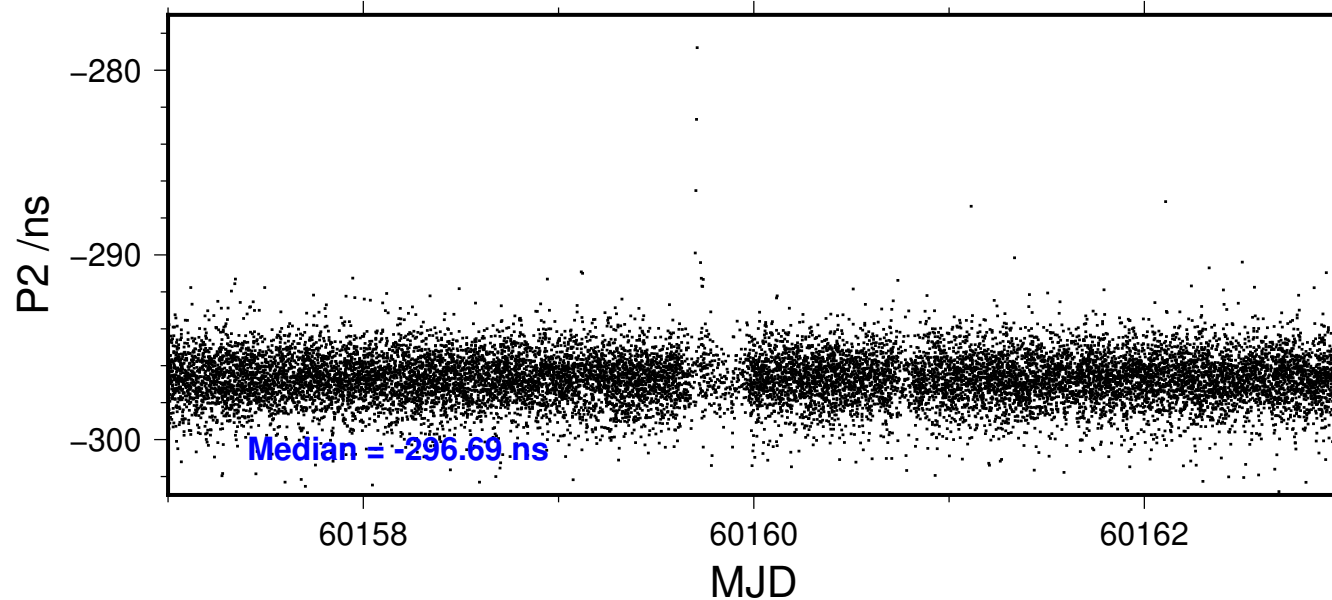
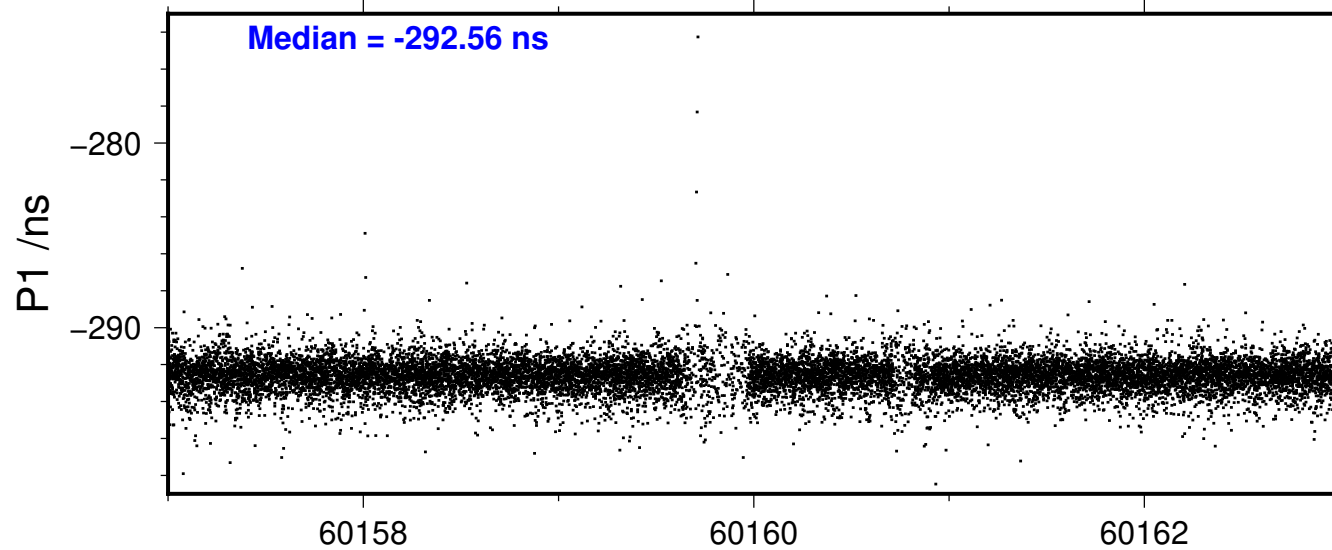
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169108 s: E1= 15 ps	165520 s: E5= 61 ps
84554 s: E1= 17 ps	82760 s: E5= 46 ps
42277 s: E1= 42 ps	41380 s: E5= 72 ps
21139 s: E1= 67 ps	20690 s: E5= 65 ps
10569 s: E1= 82 ps	10345 s: E5= 88 ps
5285 s: E1= 93 ps	5173 s: E5= 105 ps
2642 s: E1= 105 ps	2586 s: E5= 110 ps
1321 s: E1= 135 ps	1293 s: E5= 127 ps
661 s: E1= 172 ps	647 s: E5= 165 ps
330 s: E1= 230 ps	323 s: E5= 205 ps
165 s: E1= 382 ps	162 s: E5= 361 ps
83 s: E1= 536 ps	81 s: E5= 508 ps
41 s: E1= 734 ps	40 s: E5= 726 ps



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139193 s: P1= 10 ps	139202 s: P2= 19 ps
69597 s: P1= 22 ps	69601 s: P2= 20 ps
34798 s: P1= 34 ps	34801 s: P2= 49 ps
17399 s: P1= 47 ps	17400 s: P2= 64 ps
8700 s: P1= 63 ps	8700 s: P2= 101 ps
4350 s: P1= 112 ps	4350 s: P2= 149 ps
2175 s: P1= 142 ps	2175 s: P2= 200 ps
1087 s: P1= 176 ps	1088 s: P2= 275 ps
544 s: P1= 229 ps	544 s: P2= 353 ps
272 s: P1= 279 ps	272 s: P2= 467 ps
136 s: P1= 480 ps	136 s: P2= 660 ps
68 s: P1= 641 ps	68 s: P2= 944 ps
34 s: P1= 909 ps	34 s: P2= 1363 ps

