Report for Calibration of G2 Laboratories MASM and NMC A*STAR by NIM

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The report is divided by seven parts. The first part introduces the calibration briefly. And the second and third parts describe separately the equipments and the operation methods, and the experiment setups during the calibration campaign. Part 4 introduce the data processing of the calibration. Then the fifth part describe the final results by processing. In part 6, it is shown how the calibration uncertainties are evaluated. Climate parameters during the calibration is involved in part 7.

1. Introduction

Time link calibration is the premise of time transfer. Since 2012, BIPM has started to draw up the new guideline for GNSS link calibration and assigned several NMIs including NIM as the group 1 laboratories to implement the possibility of calibration of group 2 laboratories in the local RMO (Regional Metrology Organization) that might give some assist to BIPM.

NIM Cal-002 has been installed and operated at MASM since the middle of November of 2018. NIM Cal-002 was sent to NMC A*STAR (abbreviated to NMC) from MASM and arrived at NMC in the end of December of 2018. Finally, it came back to NIM in early March.

2. Description of the equipments and the operation method

The NIM transportable calibrator NIM Cal-002 is pictured in figure 1 and depicted schematically in figure 2.



Figure 1. NIM calibrator(NIM Cal-002)

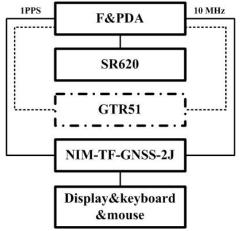


Figure 2. Schematic of NIM Cal-002

Referring to figure 2, the function of each part is as follows.

- 1. **NIM-TF-GNSS-2J**: GNSS time and frequency transfer travelling receiver developed by NIM
- 2. SR620:Time interval counter used to measure the reference delay
- 3. P&FDA: phase and frequency distribution amplifier
- 4. Display&keyboard&mouse (KVM): Interface between PC and the user, the interface for control of the receiver and logging of GNSS measurement data
- 5. GTR51: Dicom company product Physical Size: : 62cm(width)*78cm(height)*89cm(depth) (without the wheels) wheel height:12cm rough weight: 101 kg List of supplied items Receivers: IM20(site name for CGGTTS is IM20): NIM-TF-GNSS-2J(with antenna

AT1675 AT-200) IM12(site name for CGGTTS is IM12): GTR51(with antenna NOV703GGG) Others: KVM(ATEN) PDA and FDA(SDI) SR620(SRS) cables Connectors

All information about the equipments for the calibrator and the receivers to be calibrated are list in table 1.

Timing lab	Site name	BIPM code	Model	Role	Notes
NIM	IM06	IM06	Dicom GTR50	Reference receiver	Master
NIM	IM20	IM20	NIM-TF-GNSS-2J	Traveling receiver	Traveling
NIM	IM12	IM12	GTR51	Traveling receiver	Traveling
MASM	MN	MN	GTR51	Receiver to be	
				calibrated	
NMC	SG01	SG01	Septentrio	Receiver to be	
			PolaRx5TR	calibrated	
NMC	SG02	SG02	Septentrio	Receiver to be	
			PolaRx5TR	calibrated	
NMC	SG2P	SG2P	Septentrio	Receiver to be	
			PolaRx2eTR	calibrated	
NMC	SGBK	SGBK	Septentrio	Receiver to be	
			PolaRx2eTR	calibrated	

Table 1. Sites used for the calibration

The whole calibration tour includes start CCD before calibration, calibration on site and closure CCD as shown in table 2.

Time period	Location	Operation
MJD 58373-MJD 58379	NIM	Start CCD before calibration
MJD 58403-MJD 58409	MASM	Calibration on site
MJD 58481-MJD 58486	NMC	Calibration on site
MJD 58548 -MJD 58553	NIM	Closure CCD after calibration

The data from MJD 58403 to MJD 58409 and from MJD 58481 to MJD 58486 after the signal transmitting was closed which looks normal are finally used for computation.

The calibration method, the differential calibration with closure of GPS (Global Positioning System) time and frequency transfer receiver, is used. Its principle concept is addressed in [1].

3. Experiment setups

In the campaign, the receivers used were as follows in table 1. IMEJ (site name for CGGTTS is IM06) is the master GPS time and frequency transfer receiver of NIM for TAI contribution and the reference receiver. The calibrator at MASM and NMC was installed and the setups and the sub-delay information for start and closure experiments at NIM and calibration experiments on site at MASM and NMC were depicted in figure 4 and 5.

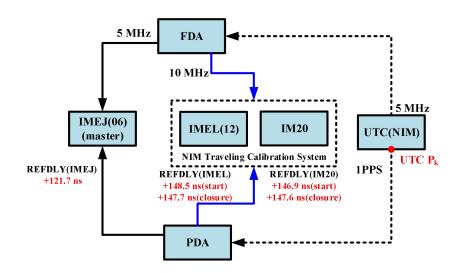


Figure 3. Experiment setup @NIM(for CCD experiments)

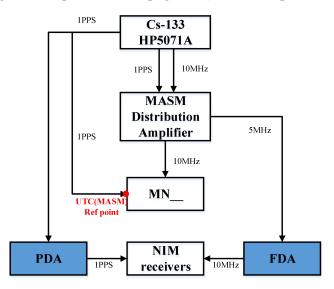


Figure 4. Experiment setup @MASM(for CCD experiments)

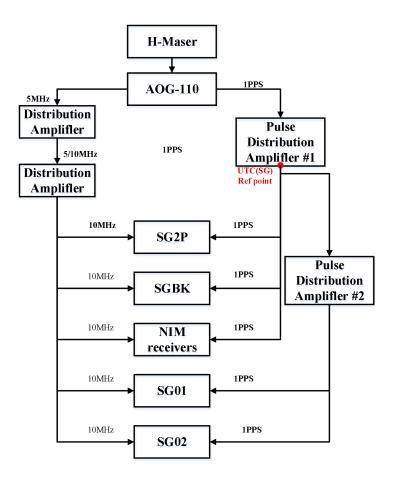


Figure 5. Experiment setup @NMC(for CCD experiments)

4. Data processing

The raw differences $RAWDIF(P1/P2)_{A-B}$ between two receivers such as A and B, in the CCD experiments during the calibration, are given by $RAWDIF(P1/P2)_{A-B} = \Delta CABDLY_{A-B} + \Delta INTDLY(P1/P2)_{A-B} - \Delta REFDLY_{A-B}$ (1)

where $RAWDIF(P1/P2)_{A-B}$ are the differences of code measurements from Rinex files without compensation of the antenna cable delay(CABDLY), the internal delay(INTDLY), and reference delay(REFDLY) from CGGTTS header. $\Delta CABDLY_{A-B}$, $\Delta REFDLY_{A-B}$ and $\Delta INTDLY_{A-B}$ are the differences of CABDLY, INTDLY, and REFDLY separately, given in table 3. P3 results are calculated by the formula P3=P1*2.54573-P2*1.54573.

Table 3. REFDLY and CABDLY differences between station and traveling receiversPairMJD $\triangle REFDLY(ns)$ $\triangle CABDLY(ns)$

IM12-IM06	58373-58379	26.8	-47.3
IM20-IM06	58373-58379	25.2	-43.6
MNIM12	58403-58409	-47.9	-70.0
MNIM20	58403-58409	-47.4	-73.7
SG01-IM12	58481-58486	1.1	9.5
SG01-IM20	58481-58486	1.1	34.2
SG02-IM12	58481-58486	1.2	-38.5
SG02-IM20	58481-58486	1.1	-13.8
SG2P-IM12	58481-58486	206.7	-94.5
SG2P-IM20	58481-58486	206.6	-69.8
SGBK-IM12	58481-58486	199.5	46.5
SGBK-IM20	58481-58486	199.4	71.2
IM12-IM06	58548-58553	26.0	-47.3
IM20-IM06	58548-58553	25.9	-43.6

5. Calibration computation and calibration values

Table 4 shows INTDLY for station IM06. Raw P1, P2, P3 and P1-P2 differences calculated between station and traveling receivers are given in table 5. The values for Δ INTDLY between a given pair of receivers are computed using Eq.(1) and given in table 6. Closure values(the difference between the mean values before calibration and after calibration) are given in table 7. The values of INTDLY for receiver MN_, SG01, SG02, SG2P and SGBK are computed using Δ INTDLY between receivers to be calibrated and the traveling receivers and Δ INTDLY between the traveling receivers and IM06 (values from 1001-2018). The values of INTDLY are given in table 8.

[Rcvr	P1(ns)	P2(ns)	P3(ns)
	IM06	-31.8	-18.4	-52.5

 Table 4. INTDLY for station IM06 from 1001-2018

5.1. Raw differences

Table 5. Raw differences between station and traveling receivers

Pair	MJD	$\triangle P1(ns)$	\triangle P2(ns)	\triangle P3(ns)
IM12-IM06	58373-58379	-82.0	-94.8	-62.1
IM20-IM06	58373-58379	-59.1	-54.1	-67.0
MNIM12	58403-58409	-4.4	-4.7	-4.1
MNIM20	58403-58409	-28.0	-45.8	-0.6
SG01-IM12	58481-58486	108.9	105.1	114.9
SG01-IM20	58481-58486	116.9	94.7	151.2
SG02-IM12	58481-58486	68.2	63.6	75.4
SG02-IM20	58481-58486	76.2	53.2	111.7
SG2P-IM12	58481-58486	-40.6	-41.4	-39.3

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SG2P-IM20	58481-58486	-32.6	-51.8	-2.9
SGBK-IM12	58481-58486	105.3	102.2	110.2
SGBK-IM20	58481-58486	113.3	91.7	146.5
IM12-IM06	58548-58553	-82.2	-95.2	-62.1
IM20-IM06	58548-58553	-59.1	-54.3	-66.6

5.2. \triangle **INTDLY** for recivers

Table 6. INTDLY differences between stations and traveling receivers

Pair	\triangle INTDLY(P1)(ns)	\triangle INTDLY(P2)(ns)	\triangle INTDLY(P3)(ns)
IM12-IM06 before	-7.9	-20.7	12.0
IM20-IM06 before	9.7	14.7	1.8
MNIM12	17.7	17.4	18.0
MNIM20	-1.7	-19.5	25.7
SG01-IM12	100.5	96.7	106.5
SG01-IM20	83.8	61.6	118.1
SG02-IM12	107.9	103.3	115.1
SG02-IM20	91.1	68.1	126.6
SG2P-IM12	260.6	259.8	261.9
SG2P-IM20	243.8	224.6	273.5
SGBK-IM12	258.3	255.2	263.2
SGBK-IM20	241.5	219.9	274.7
IM12-IM06 after	-8.9	-21.9	11.2
IM20-IM06 after	10.4	15.2	2.9

5.3. Closure values

Table 7.	Closure	values
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Pair	$\triangle P1(ns)$	\triangle P2(ns)	\triangle P3(ns)
IM12-IM06	1.0	1.2	0.7
IM20-IM06	-0.7	-0.5	-1.0

5.4. Calibration values

Table 8. INTDLY for stations MN_, SG01, SG02, SG2P and SGBK

Rcvr	P1(ns)	P2(ns)	P3(ns)
MN_IM12	-22.1	-21.7	-22.6
MNIM20	-23.9	-23.1	-25.3
SG01 _{IM12}	60.8	57.6	65.9
SG01 IM20	61.6	57.8	67.3
SG02 _{IM12}	68.2	64.2	74.5
SG02 IM20	69.0	64.4	75.9

SG2P IM12	220.9	220.7	221.4
SG2P IM20	221.7	220.9	222.8
SGBK IM12	218.6	216.0	222.6
SGBK IM20	219.3	216.3	224.0
MN	-23.0	-22.4	-24.0
SG01	61.2	57.7	66.6
SG02	68.6	64.3	75.2
SG2P	221.3	220.8	222.1
SGBK	219.0	216.2	223.3

6. Uncertainty Evaluation

Here we evaluated the uncertainty from the sources as follows and got the combined uncertainty as 1.8 ns conservatively for P codes. All the measurements related to the cable and reference delays were done with SR620 on the trigger level 1.0 V. And the uncertainties from position references and multipaths are just referenced to the description of the guideline. The u_a values are from TDEV of the corresponding CCD results shown in the figures in Annex 6. For NMC A*STAR calibration, the original antenna cables were not used. So the additional uncertainties for measurements of the original cable and the really used cable should be taken into account, which are both estimated as 0.5 ns (ub,43). So uCAL of P1 and P2 calibration values for NMC A*STAR should be calculated as 1.9 ns and 2.0 ns.

Unc.	P1 (ns)	P2 (ns)	P3 (ns)	Description			
u _a (T-V)	0.2	0.2	0.3	RAWDIF (traveling-visited)			
u _a (T-R)	0.2	0.2	0.3	RAWDIF (traveling-reference)			
ua	0.3	0.3	0.4				
Misclosure							
ub,1	1.0	1.2	1.0	observed mis-closure			
Systematic components related to RAWDIF							
ub,11	0.05	0.05	0.05	Position error at reference			
ub,12	0.05	0.05	0.05	Position error at visited			
ub,13	0.3	0.3	0.3	Multipaths at reference			
ub,14	0.3	0.3	0.3	Multipaths at visited			
Link of the Traveling system to the local $UTC(k)$							
ub,21	0.5	0.5	0.5	REFDLY _T (at ref lab)			
ub,22	0.5	0.5	0.5	REFDLY _T (at visited lab)			
ub,TOT	1.4	1.5	1.4				
Link of the Reference system to its local UTC(k)							
ub,31	0.5	0.5	0.5	REFDLY _R (at ref lab)			
Link of the Visited system to its local $UTC(k)$							
ub,32	0.5	0.5	0.5	REFDLYV (at visited lab)			
ub,SYS	1.6	1.7	1.6	Components of equation (2)			

Table 9. Uncertainty contributions

Supported by NIM

uCAL	1.7	1.8	1.7	Composed of ua and ub,SYS			
Antenna cable delays							
ub,41	0.5	0.5	0.5	CABDLYR			
ub,42	0.5	0.5	0.5	CABDLYV			
Combined Uncertainty: 1.8 ns							

7. Climate parameters

7.1. Temperature and humidity

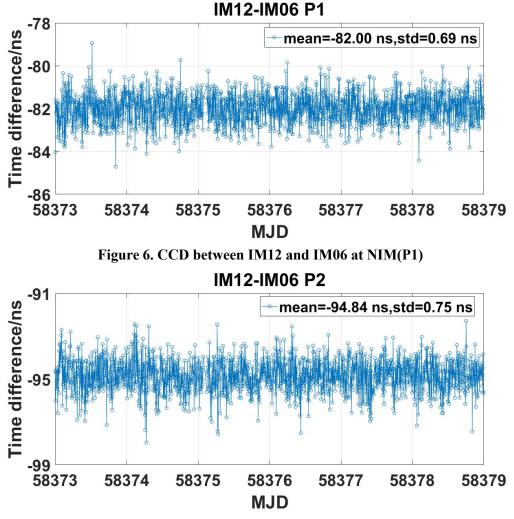
23.3°C~24.3°C ±0.5°C 32.1%~42.3% ±3%

7.2. Reference signal

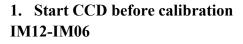
Rise time of the local UTC pulse: 2 ns

References:

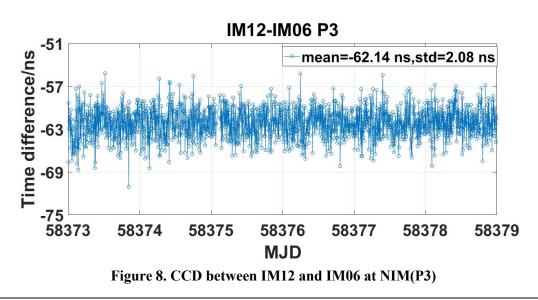
[1] BIPM. BIPM guidelines for GNSS calibration(V3.2). 05, 02, 2016.



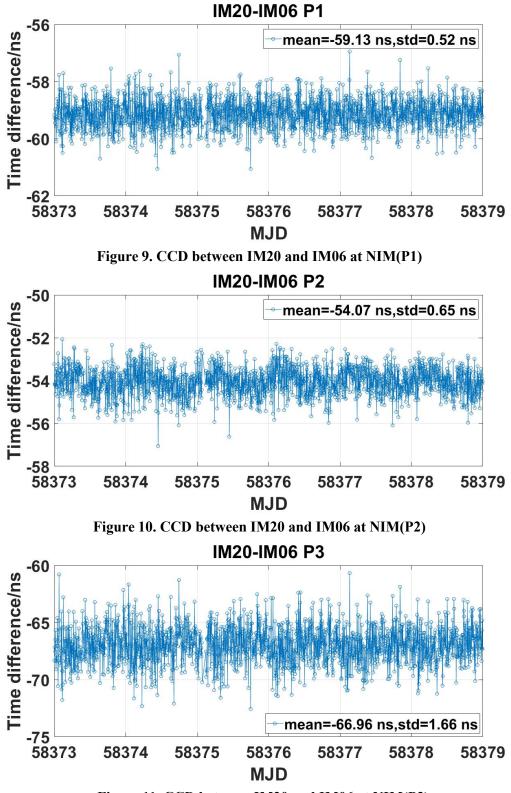
Annex 1. CCD results for MASM





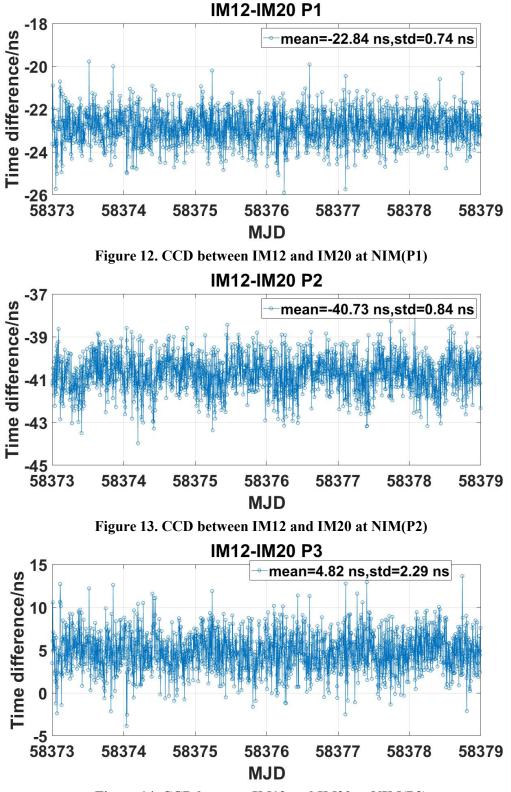


IM20-IM06



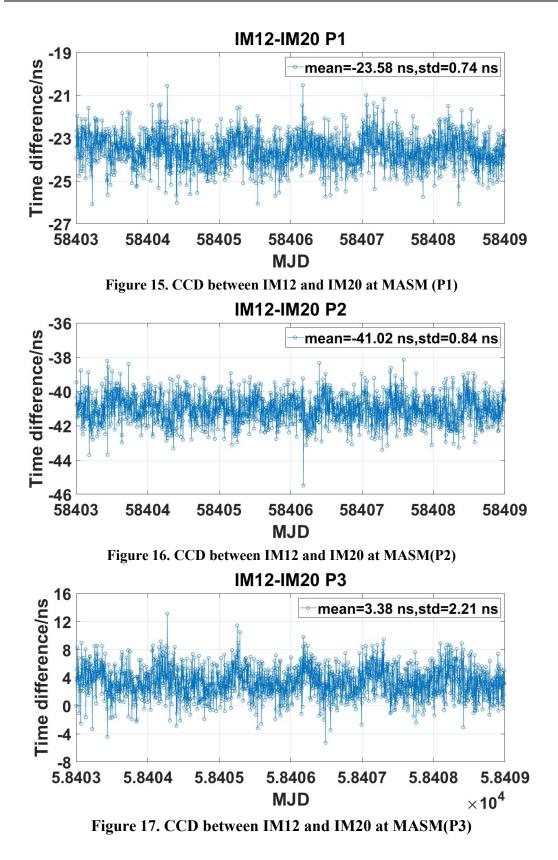


IM12-IM20





2. Calibration on site IM12 – IM20



IM12 – MN_

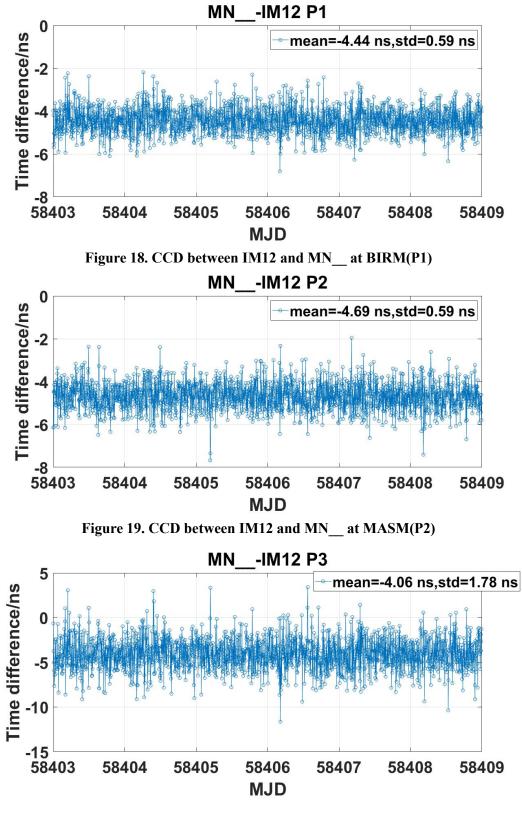
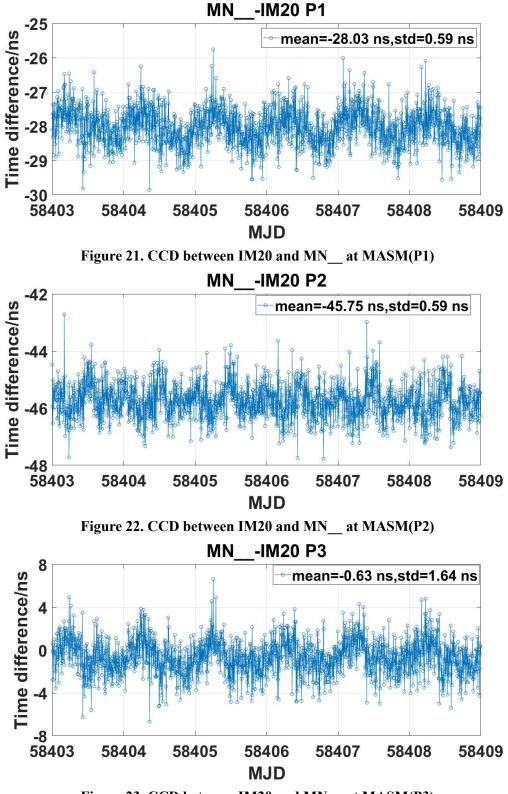
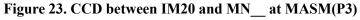
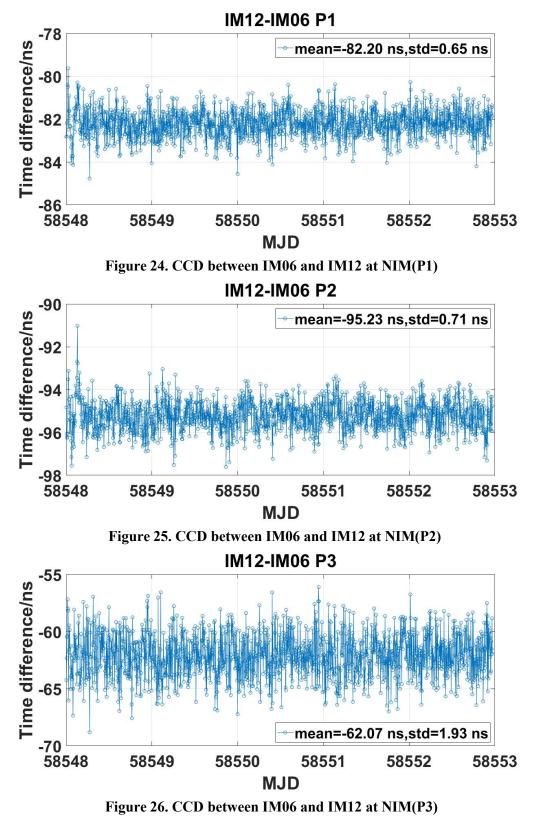


Figure 20. CCD between IM12 and MN_ at MASM(P3) IM20 – MN

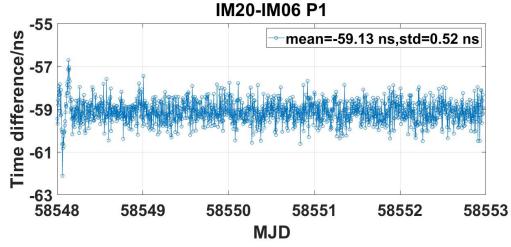




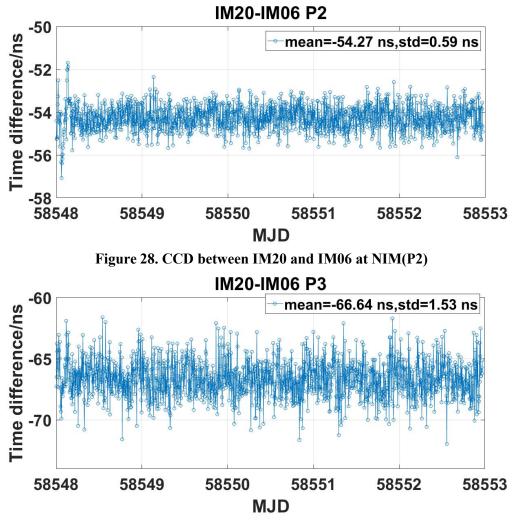
3. Closure CCD after calibration IM06-IM12



IM20-IM06









IM20-IM12

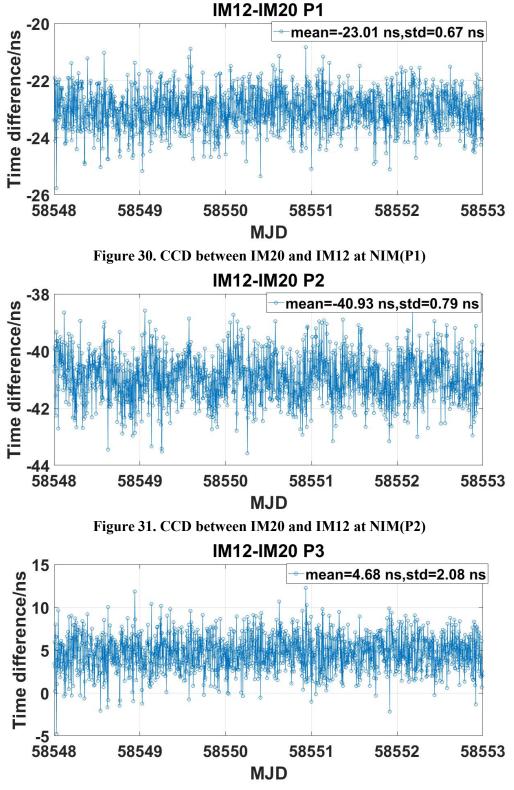
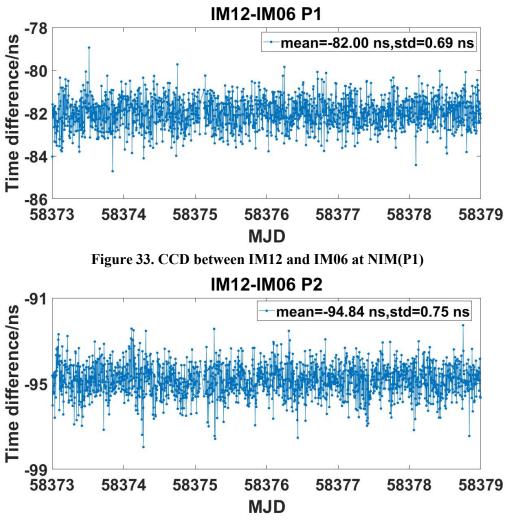


Figure 32. CCD between IM20 and IM12 at NIM(P3)

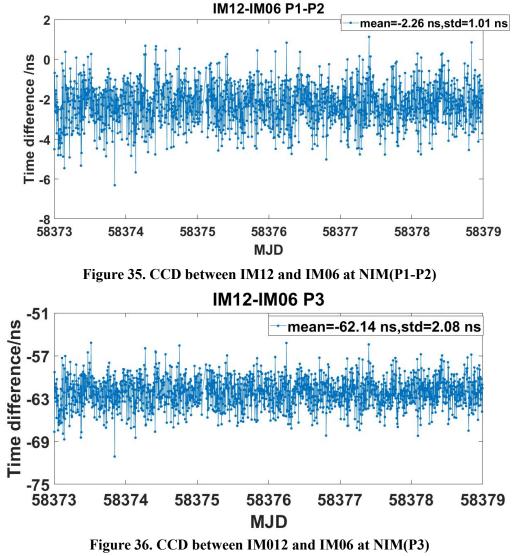
IM12-IM06

1. Start CCD before calibration



Annex 2. CCD results for NMC

Figure 34. CCD between IM12 and IM06 at NIM(P2)



IM20-IM06

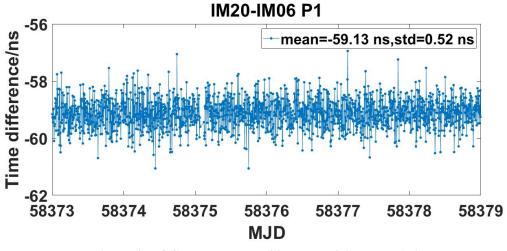
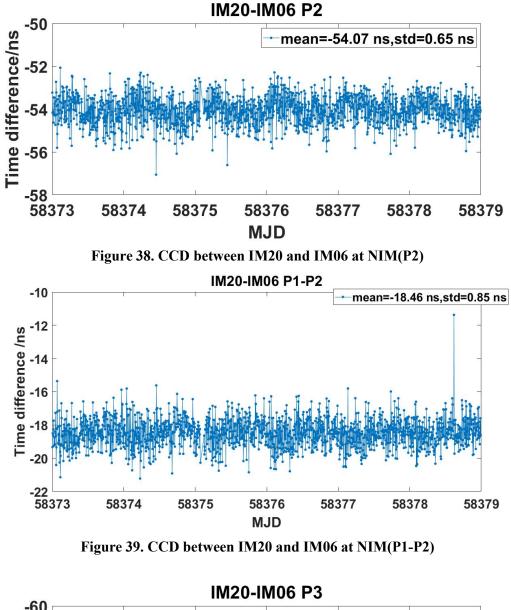
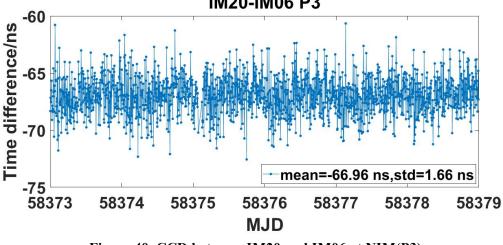


Figure 37. CCD between IM20 and IM06 at NIM(P1)







IM12-IM20

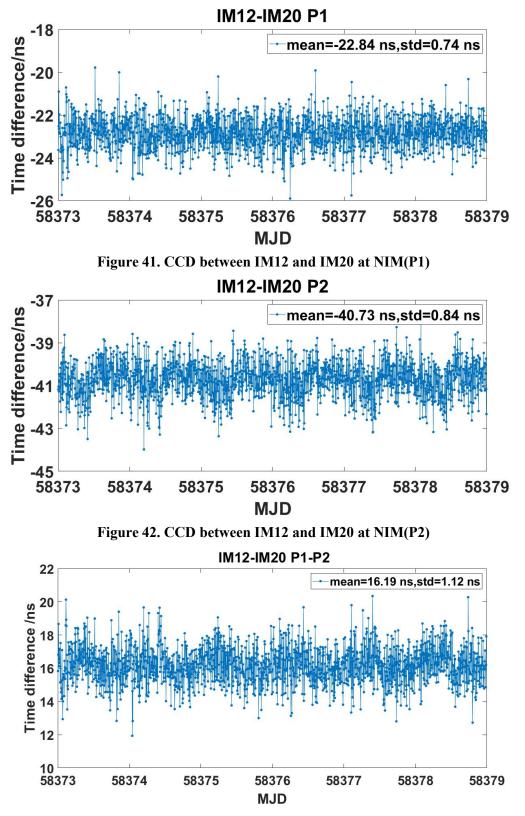


Figure 43. CCD between IM12 and IM20 at NIM(P1-P2)

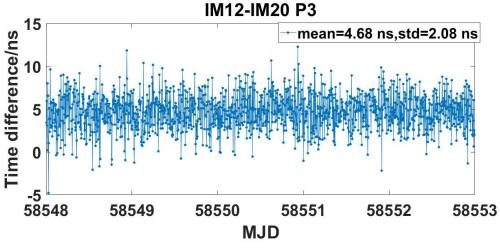
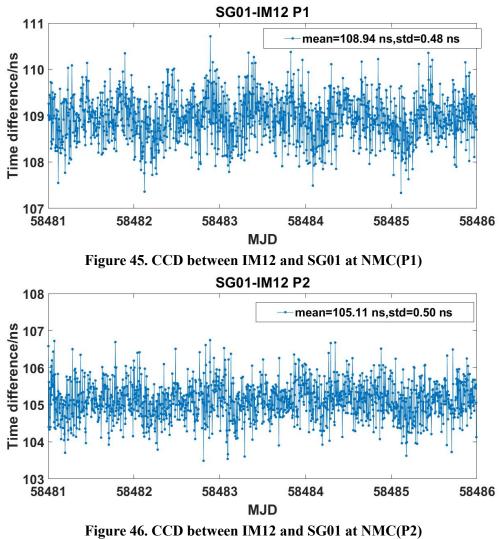
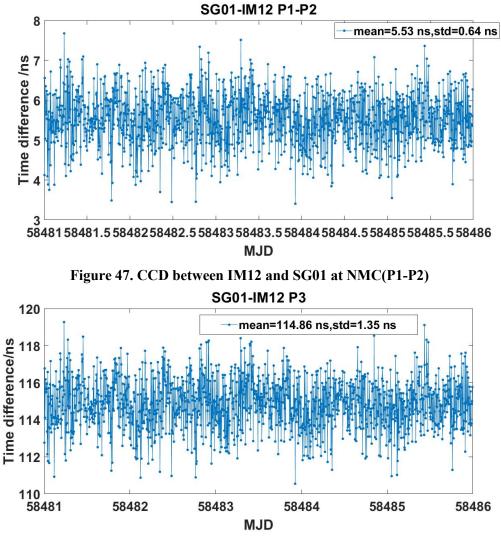


Figure 44. CCD between IM12 and IM20 at NIM(P3)

2. Calibration on site SG01-IM12







SG01-IM20

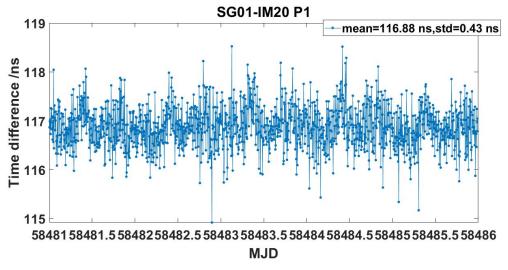
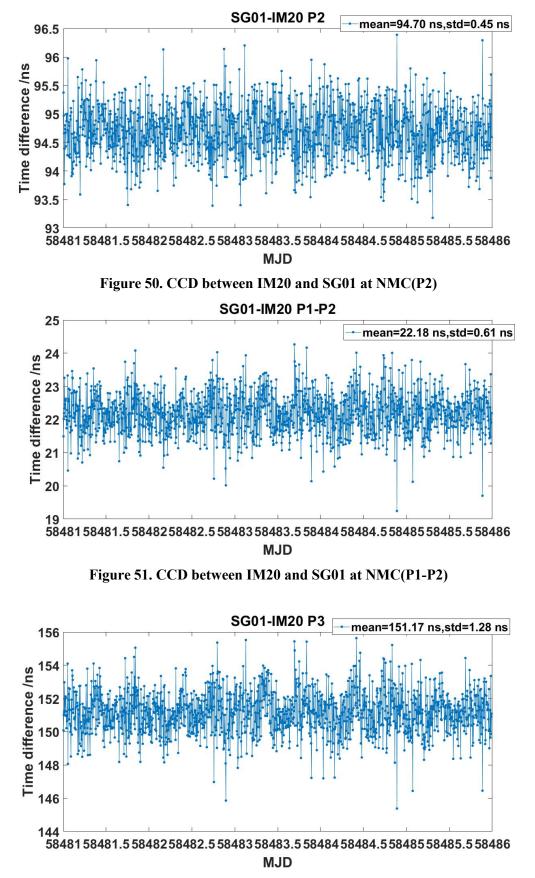


Figure 49. CCD between IM20 and SG01 at NMC(P1)





Supported by NIM



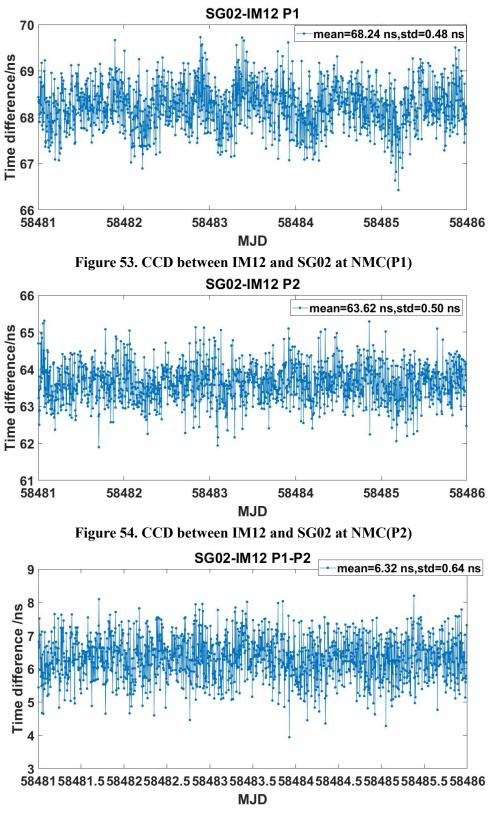


Figure 55. CCD between IM12 and SG02 at NMC(P1-P2)

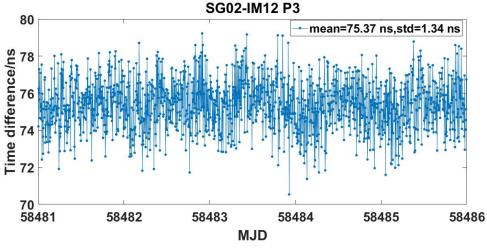
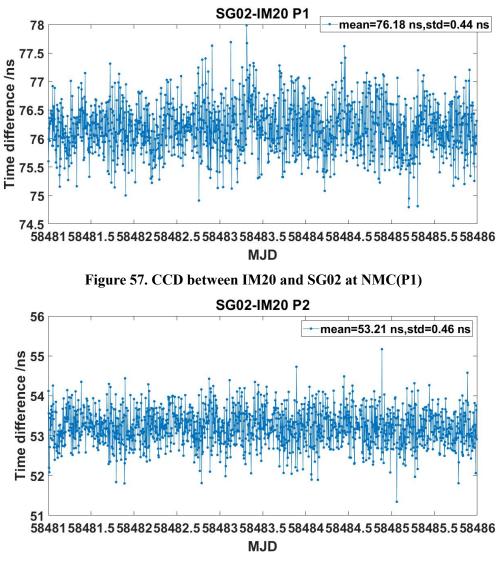
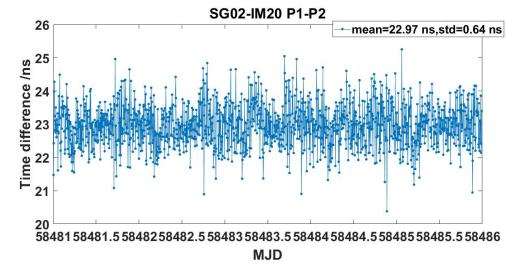


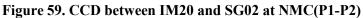
Figure 56. CCD between IM12 and SG02 at NMC(P3)

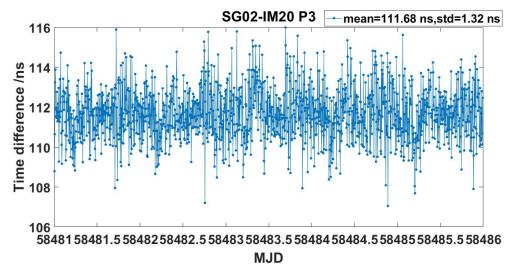






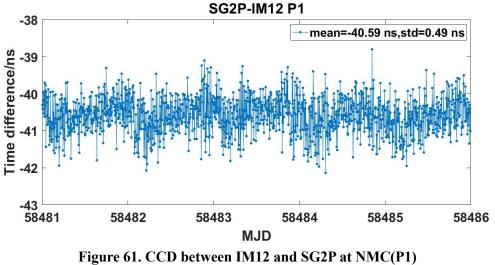


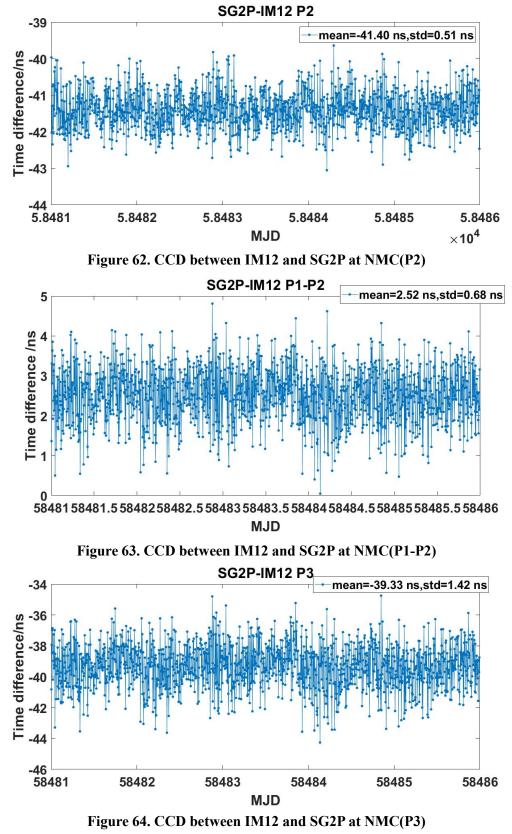






SG2P-IM12





SG2P-IM20

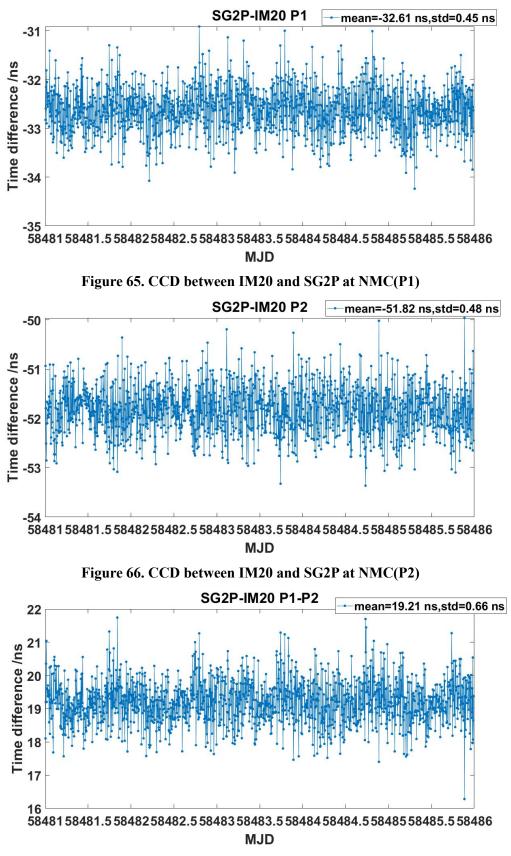
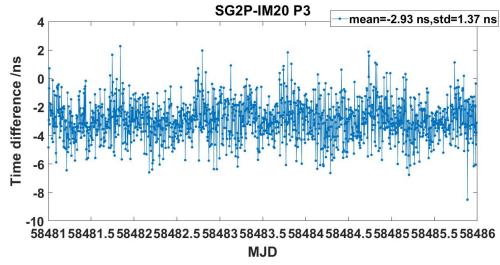


Figure 67. CCD between IM20 and SG2P at NMC(P1-P2)







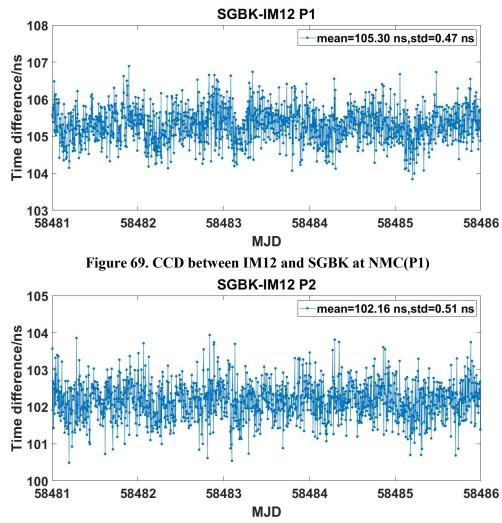
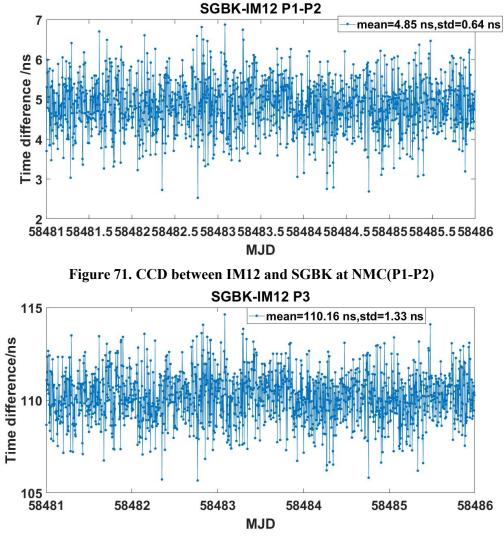


Figure 70. CCD between IM12 and SGBK at NMC(P2)





SGBK-IM20

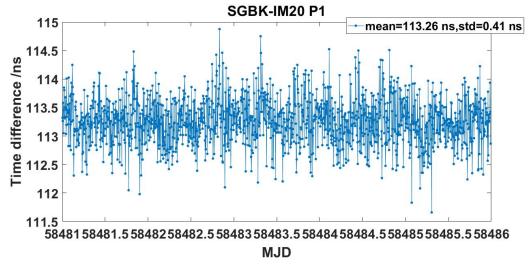
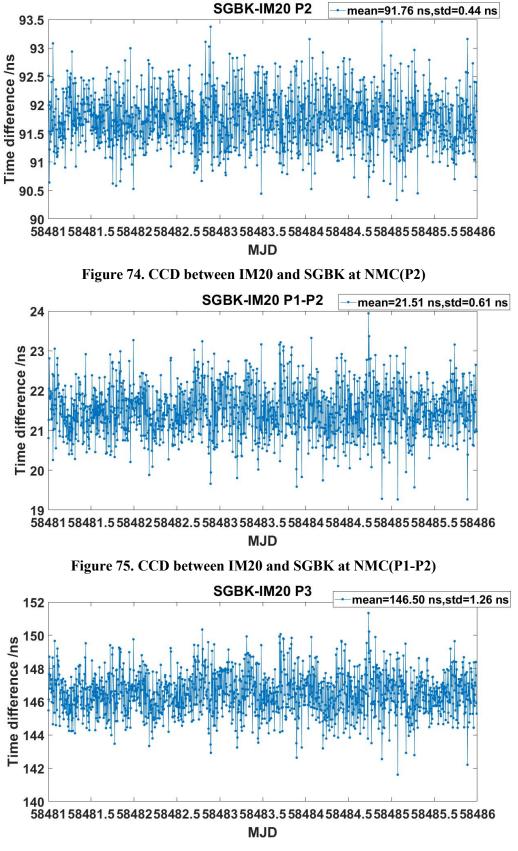


Figure 73. CCD between IM20 and SGBK at NMC(P1)





4. Closure CCD after calibration

IM06-IM12

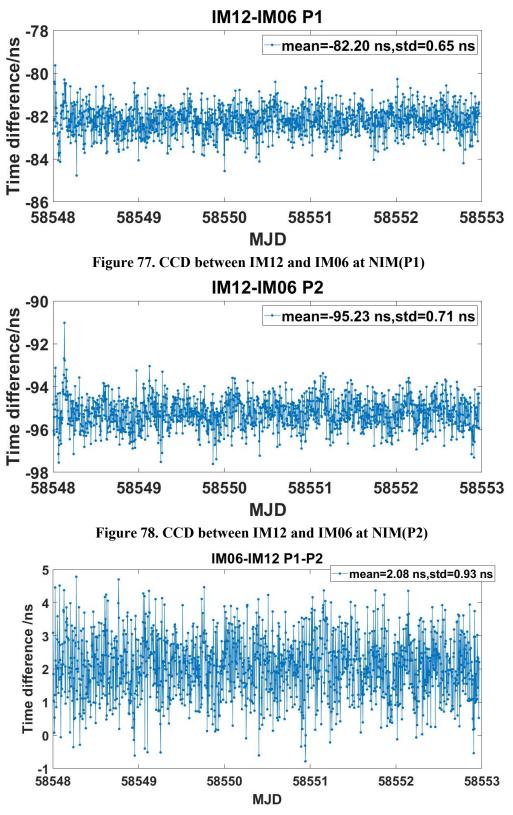
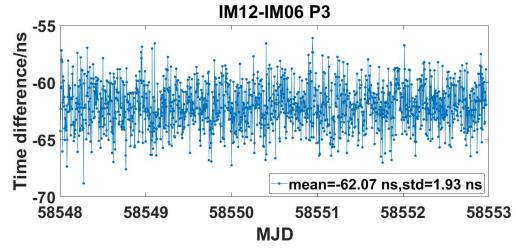


Figure 79. CCD between IM12 and IM06 at NIM(P1-P2)





IM20-IM06

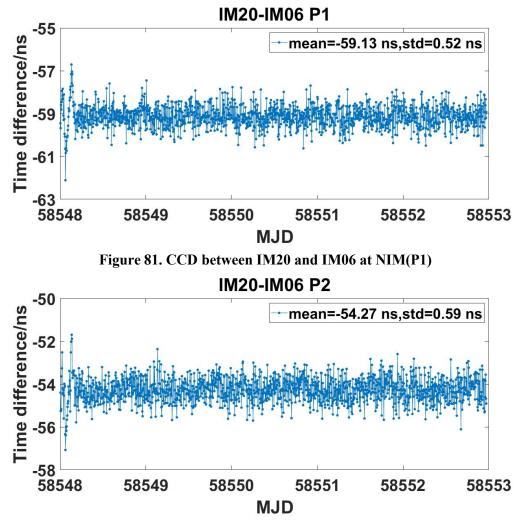
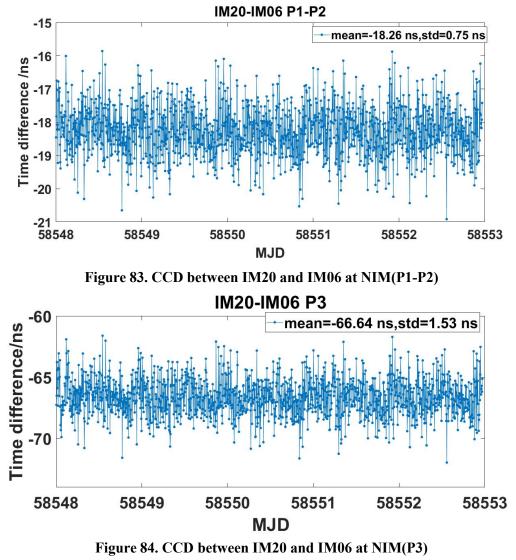


Figure 82. CCD between IM20 and IM06 at NIM(P2)



IM20-IM12

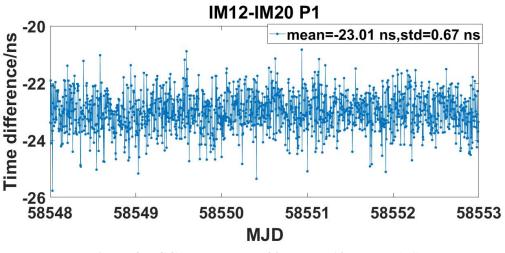


Figure 85. CCD between IM20 and IM12 at NIM(P1)

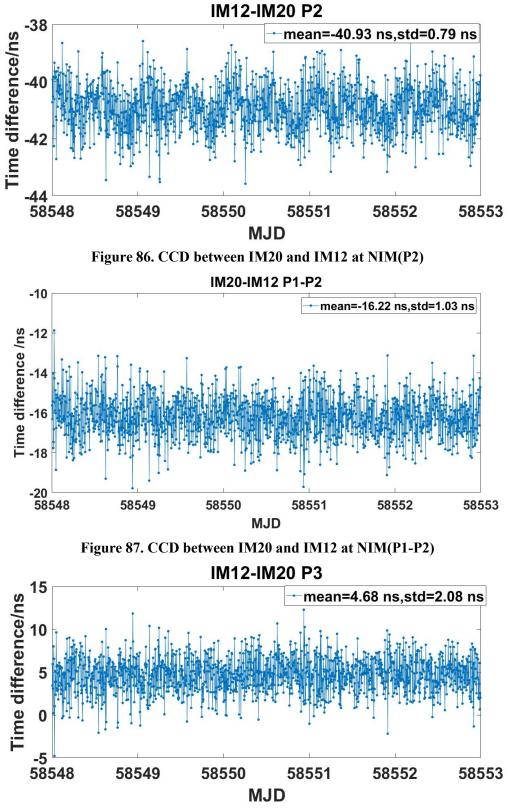


Figure 88. CCD between IM20 and IM12 at NIM(P3)

Annex 3 - Information Sheets

Information Sheet

Laboratory: Date and hour of the measurements:	beginning of	NIM UTC time 0:00 am Sep. 12,2018
Date and hour of the end of me	asurements:	UTC time 0:00 am Sep.19,2018
]	Information of	on the system
	Local:	Travelling:
4-character BIPM code	IM06	(1) IM12
		(2) IM20
Receiver maker and type:	maker:Dicom	(1)maker:Dicom
Receiver serial number:	type: GTR50	type: GTR51
	serial number:100	07011 serial number:11506132
		(2)maker:NIM
		type: NIM-TF-GNSS-2J
		serial number:2016005
1 PPS trigger level /V:	0~2	0~2
Antenna cable maker and	maker:	(1)NOV-703-GGG
type:	type:	P/N: 01018146
Phase stabilised cable (Y/N):	Phase stabilised c	able:N (2) NOV-702-GG
		P/N: 01017577
Length outside the building /m:	5.0	5.0
Antenna maker and type:	maker:Novatel	(1)NOV-703-GGG
Antenna serial number:	type: GPS-702-G	GG NEG15210020
	Serial number:	(2)NOV-702-GG
	NAE10220060	NAE 16270022
Temperature (if stabilised) /°C		

Measured delays /ns

	Local:	Travelling:
Delay from local UTC to	121.7	(1)148.5
receiver 1 PPS-in:		(2)146.9
Delay from 1 PPS-in to		
internal Reference (if		
different):		
Antenna cable delay:	248.7	(1)201.4
		(2)205.1

Splitter delay (if any):	
Additional cable delay (if any):	

Data used for the generation of CGGTTS files (IM06)

INT DLY (GPS) /ns:	-31.3 ns (GPS P1), -17.9 ns (GPS P2)
INT DLY (GLONASS) /ns:	0.0
CAB DLY /ns:	248.7
REF DLY /ns:	122.2
Coordinates reference frame:	ITRF
Latitude or X /m:	-2154288.06
Longitude or Y /m:	+4373440.56
Height or Z /m:	+4098884.94

Data used for the generation of CGGTTS files (IM12)

-27.4 ns (GPS C1), -33.5 ns (GPS P1), 0.	
ns (GPS C2), -35.2 ns (GPS P2), 0.0 ns	
(GPS L5)	
0	
201.4 ns	
148.5ns	
ITRF $Dx = 0.0 \text{ m}$, $Dy = 0.0 \text{ m}$, $Dz = 0.0 \text{ m}$, ds	
= 0.0, Rx = 0.0, Ry = 0.0, Rz = 0.000000	
-2154283.45	
+4373442.66	
+4098885.13	

Data used for the generation of CGGTTS files (IM20)

L1C/A : 0.0 ns L1P: 0.0 ns L2P: 0.0 ns L1C/A : 0.0 ns L1P: 0.0 ns L2P: 0.0 ns 205.1 ns
205.1 ns
146.9 ns
ITRF $Dx = 0.0 \text{ m}$, $Dy = 0.0 \text{ m}$, $Dz = 0.0 \text{ m}$, ds
= 0.0, Rx = 0.0, Ry = 0.0, Rz = 0.000000
-2154283.452
+4373442.660
+4098885.129
 = -

General information

Rise time of the local UTC pulse	unknown
Is the laboratory air conditioned	No
Set temperature value and uncertainty:	26.0°C ±0.2 °C
Set humidity value and uncertainty:	21% ± 1%

Diagram of the experiment set-up

Please see the report.

Log of Events / Additional Information

	(to be repeated for each calibrated system)						
Laboratory: MASM – TF- Lab				MN			
Date and hour of the beginning of				beginning	of	MJD 58401	UTC 04:24:51
measurements:							
Date and hour of the end of measurements:			MJD 58410	UTC 07:02:10			

Information on the system				
	Local:	Travelling:		
4-character BIPM code	(1) MN_	(1)IM20		
		(2)IM12		
Receiver maker and type:	(1) Dicom ,GTR51	(1) NIM ,NIM-TF-GNSS-2J;		
Receiver serial number:	SN:1311002	SN:2016005		
		(2) Dicom ,GTR51;		
		SN:1506132		
1 PPS trigger level /V:	1	1		
Antenna cable maker and	(1)NOV-703-GGG	(1) NOV702GG		
type:	NEG 13360009	P/N: 01017577		
Phase stabilised cable (Y/N):		(2) NOV-703-GGG		
		P/N: 01018146		
Length outside the building	(1) 37 m	(1) 37 m		
/m:		(2) 37 m		
Antenna maker and type:	(1) NOV-703-GGG	(1) NOV702GG		
Antenna serial number:	NEG 13360009	NAE 16270022		
		(2) NOV-703-GGG		
		NEG15210020		
Temperature (if stabilised)				
/°C				

Measured delays /ns

	Local:	Travelling:
Delay from local UTC to	(1) 0.0 ns	1) 47.32129 ns / 47.4 ns
receiver 1 PPS-in:		2) 47.31039 ns / 47.9 ns
Delay from 1 PPS-in to	(1) 0.0 ns	
internal Reference (if		
different):		

Supported by NIM

Antenna cable delay:	(1) 131.4 ns	1) 201.4 ns 2) 205.1 ns
Splitter delay (if any):		2) 203.1 113
Additional cable delay (if any):		

Data used for the generation of CGGTTS files (MASM)

INT DLY (GPS) /ns:	L1C/A : 0.0 ns L1P: 0.0 ns L2C: 0.0 ns L2P:
	0.0 ns L5: 0.0 ns
INT DLY (GLONASS) /ns:	L1OF: 0.0 L1SF: 0.0 ns L2OF: 0.0 ns
	L2SF: 0.0 ns
CAB DLY /ns:	131.4 ns
REF DLY /ns:	0.0 ns
Coordinates reference frame:	FRAME
Latitude or X /m:	-1248821.2
Longitude or Y /m:	4097255.60
Height or Z /m:	4711728.68

Data used for the generation of CGGTTS files (IM12)

INT DLY (GPS) /ns:	L1C/A : -27.4 ns L1P: -33.5 ns L2C: 0.0 n		
	L2P: -35.2 ns L5: 0.0 ns		
INT DLY (GLONASS) /ns:	L1OF: 0.0 L1SF: 0.0 ns L2OF: 0.0 ns		
	L2SF: 0.0 ns		
CAB DLY /ns:	201.4 ns		
REF DLY /ns:	47.3 ns UTC(MASM)		
Coordinates reference frame:	ITRF Dx = 0.0 m, Dy = 0.0 m, Dz = 0.0 m, ds		
	= 0.0, Rx = 0.0, Ry = 0.0, Rz = 0.000000		
Latitude or X /m:	-1248821.121		
Longitude or Y /m:	+4097254.832		
Height or Z /m:	+4711728.385		

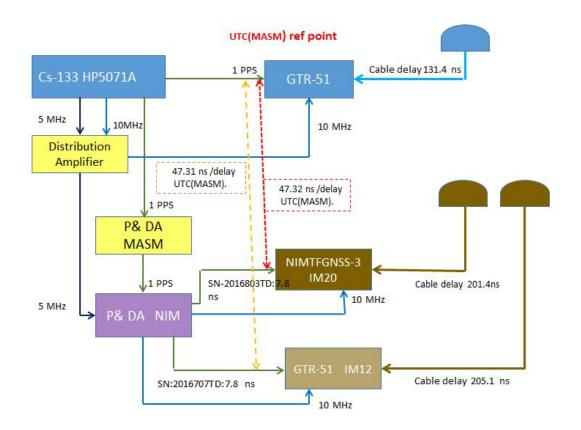
Data used for the generation of CGGTTS files (IM20)

INT DLY (GPS) /ns:	L1C/A : 0.0 ns L1P: 0.0 ns L2P: 0.0 ns		
INT DLY (GLONASS) /ns:	L1C/A : 0.0 ns L1P: 0.0 ns L2P: 0.0 ns		
CAB DLY /ns:	205.1 ns		
REF DLY /ns:	47.3 ns		
Coordinates reference frame:	ITRF $Dx = 0.0 \text{ m}$, $Dy = 0.0 \text{ m}$, $Dz = 0.0 \text{ m}$, ds		
	= 0.0, Rx = 0.0, Ry = 0.0, Rz = 0.000000		
Latitude or X /m:	-1248820.999		
Longitude or Y /m:	+4097255.264		
Height or Z /m:	+4711728.359		

General information

Rise time of the local UTC pulse	unknown
Is the laboratory air conditioned	No
Set temperature value and uncertainty:	26.0°C ±0.2 °C
Set humidity value and uncertainty:	$21\% \pm 1\%$
	21/0 - 1/0

Diagram of the experiment set-up



Log of Events / Additional Information

(to k	be re	peated	for	each	calibrated	system)
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Laboratory:			SG		
Date and hour of the	ne beginning	of	MJD 58479, 00:00:00		
measurements:					
Date and hour of the end of r	neasurements:				
Information on the system					
	Informatio	n or	the system		
	Informatio	n or	the system Travelling:		
4-character BIPM code		n or	•		

Receiver maker and type:	Septentrio PolaRx5TR	NIM-TF-GNSS-2J
Receiver serial number:	S/N: 4701189	GTR51
1 PPS trigger level /V:		
Antenna cable maker and type:	Huber+Suhner Sucofeed ¹ / ₂	HUBER+SUHNER
Phase stabilised cable (Y/N):	inch	SUCOFEED (for both)
		3/8 Inch
		1/2 Inch
Length outside the building	98 m	80 m
/m:		92 m
Antenna maker and type:	Leica AR25	NOV-GPS-702-GG
Antenna serial number:	S/N: 726808	NOV-GPS-703-GGG
Temperature (if stabilised)	-	-
/° C		

Measured delays /ns

	Local:	Travelling:
Delay from local UTC to	38.24 ns	37.16 ns
receiver 1 PPS-in:		37.10 ns
Delay from 1 PPS-in to internal	-	-
Reference (if different):		
Antenna cable delay:	376.0 ns	341.8 ns
		366.5 ns
Splitter delay (if any):	-	-
Additional cable delay (if any):	_	_

Data used for the generation of CGGTTS files

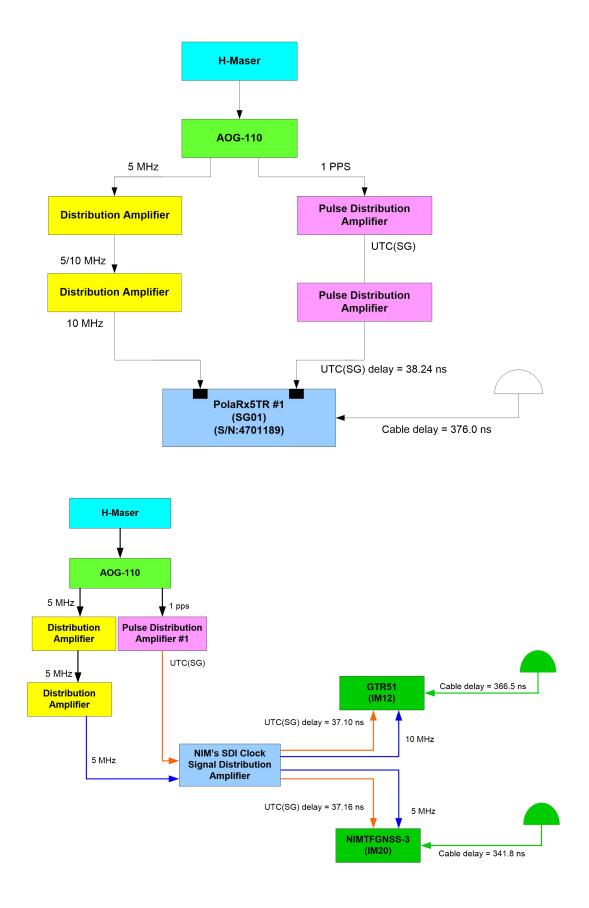
INT DLY (GPS) /ns:	_
INT DLY (GLONASS) /ns:	_
CAB DLY /ns:	376.0 ns
REF DLY /ns:	40.4 ns
Coordinates reference frame:	ITRF
Latitude or X /m:	-1519470.700 m
Longitude or Y /m:	+6192911.180 m
Height or Z /m:	+142840.120 m

General information

Rise time of the local UTC pulse	807.7 ps
Is the laboratory air conditioned	Yes
Set temperature value and uncertainty:	(23±2)0C
Set humidity value and uncertainty:	(55±10)% rh

(1) For a trip with closure, not needed if the traveling equipment is used in the same set-up throughout.

Diagram of the experiment set-up





Laboratory:		SG	
Date and hour of the	beginning of	MJD 58479,	00:00:00
measurements:			
Date and hour of the end of meas	surements:		
Inf	ormation on	the system	n
	Local:		Travelling:
4-character BIPM code	SG02		IM20
			IM12
Receiver maker and type:	Septentrio Pola	Rx5TR	NIM-TF-GNSS-2J
Receiver serial number:	S/N: 4701190		GTR51
1 PPS trigger level /V:			
Antenna cable maker and type:	Huber+Suhner S	Sucofeed 7/8	HUBER+SUHNER
Phase stabilised cable (Y/N):	Inch		SUCOFEED (for both)
			3/8 Inch
			1/2 Inch
Length outside the building	84 m		80 m
/m:			92 m
Antenna maker and type:	Leica AR25		NOV-GPS-702-GG
Antenna serial number:	S/N: 726809		NOV-GPS-703-GGG
Temperature (if stabilised) /° C	_		_

(40	la o	manaatad	for	oook	alibuated	arratana)
- 0.0	De	repeated	TOF	each	calibrated	systemp
1						~ _ ~ ~ ~ ~ /

Measured delays /ns

	Local:	Travelling:
Delay from local UTC to	38.25 ns	37.16 ns
receiver 1 PPS-in:		37.10 ns
Delay from 1 PPS-in to internal	0.0 ns	-
Reference (if different):		
Antenna cable delay:	328.0 ns	341.8 ns
		366.5 ns
Splitter delay (if any):	-	-
Additional cable delay (if any):	-	-

Data used for the generation of CGGTTS files

INT DLY (GPS) /ns:	-
INT DLY (GLONASS) /ns:	_
CAB DLY /ns:	328.0 ns
REF DLY /ns:	40.4 ns
Coordinates reference frame:	ITRF

Latitude or X /m:	-1519464.790 m
Longitude or Y /m:	+6192912.490 m
Height or Z /m:	+142845.940 m

General int	formation
Rise time of the local UTC pulse	807.7 ps
Is the laboratory air conditioned	Yes
Set temperature value and uncertainty:	(23±2)0C
Set humidity value and uncertainty:	(55±10)% rh

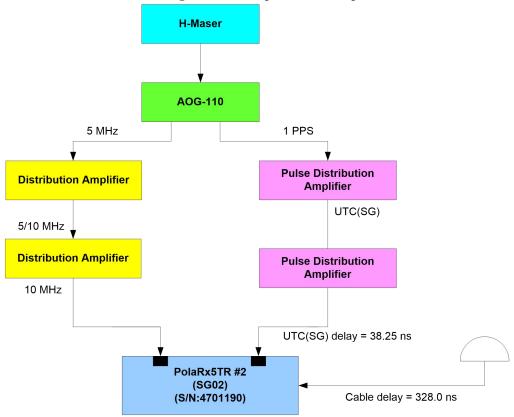


Diagram of the experiment set-up

Log of Events / Additional Information

1	(to	ho	ropostod	for	oooh	calibrated	exetom)
	UU	DC	repeated	101	caun	canor accu	system)

Laboratory:		SG
Date and hour of the	beginning of	MJD 58479, 00:00:00
measurements:		
Date and hour of the end of meas	surements:	
Inf	formation or	ı the system
	Local:	Travelling:

4-character BIPM code	SG2P	IM20
		IM12
Receiver maker and type:	Septentrio PolaRx2eTR	NIM-TF-GNSS-2J
Receiver serial number:	S/N: 3364	GTR51
1 PPS trigger level /V:		
Antenna cable maker and type:	Huber+Suhner Sucofeed ¹ / ₂	HUBER+SUHNER
Phase stabilised cable (Y/N):	inch	SUCOFEED (for both)
		3/8 Inch
		1/2 Inch
Length outside the building	70m	80 m
/m:		92 m
Antenna maker and type:	Novatel GNSS 750	NOV-GPS-702-GG
Antenna serial number:	S/N: 01018874	NOV-GPS-703-GGG
Temperature (if stabilised)	_	_
/° C		

Measured delays /ns

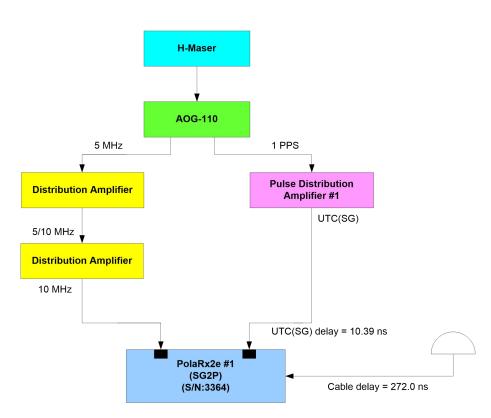
Local:	Travelling:
10.39 ns	37.16 ns
	37.10 ns
224.7 ns (using with 8.7 ns)	-
272.0 ns	341.8 ns
	366.5 ns
-	-
_	-
	10.39 ns 224.7 ns (using with 8.7 ns)

Data used for the generation of CGGTTS files

INT DLY (GPS) /ns:	224.6 ns (P1); 222.3 ns (P2)
INT DLY (GLONASS) /ns:	_
CAB DLY /ns:	272.0 ns
REF DLY /ns:	205.6 ns
Coordinates reference frame:	ITRF
Latitude or X /m:	-1519459.05 m
Longitude or Y /m:	+6192913.72 m
Height or Z /m:	+142851.46 m

General information

Rise time of the local UTC pulse	807.7 ps
Is the laboratory air conditioned	Yes
Set temperature value and uncertainty:	(23±2)0C
Set humidity value and uncertainty:	(55±10)% rh



Log of Events / Additional Information

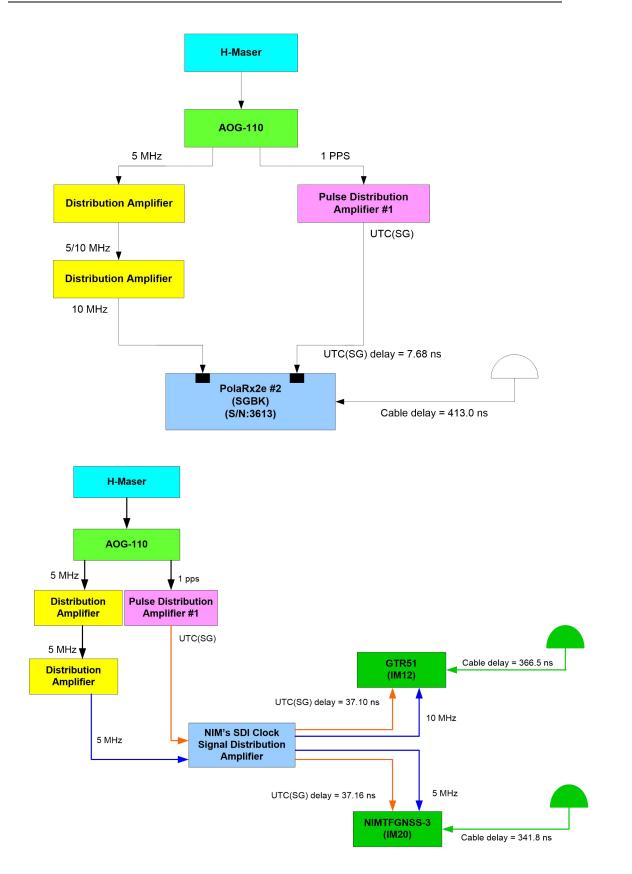
Laboratory:		SG	
Date and hour of the	beginning of	MJD 58479,	00:00:00
measurements:			
Date and hour of the end of meas	surements:		
Inf	formation or	n the system	n
	Local:		Travelling:
4-character BIPM code	SGBK		IM20
			IM12
Receiver maker and type:	Septentrio Pola	Rx2eTR	NIM-TF-GNSS-2J
Receiver serial number:	S/N: 3613		GTR51
1 PPS trigger level /V:			
Antenna cable maker and type:	Huber+Suhner	Sucofeed 1/2	HUBER+SUHNER
Phase stabilised cable (Y/N):	inch		SUCOFEED (for both)
			3/8 Inch
			1/2 Inch
Length outside the building	105 m		80 m
/m:			92 m

Antenna maker and type:	Leica AR25	NOV-GPS-702-GG
Antenna serial number:	S/N: 765733	NOV-GPS-703-GGG
Temperature (if stabilised)	_	_
/° C		
	Measured delays /ns	
	Local:	Travelling:
Delay from local UTC to	7.68 ns	37.16 ns
receiver 1 PPS-in:		37.10 ns
Delay from 1 PPS-in to internal	220.2 ns (using with 8.7 ns)	_
Reference (if different):		
Antenna cable delay:	413.0 ns	341.8 ns
		366.5 ns
Splitter delay (if any):	_	_
Additional cable delay (if any):	_	_
• • • •		
Data used fo	r the generation of C	GGTTS files
Data used fo	-	GGTTS files 1); 217.5 ns (P2)
	-	
INT DLY (GPS) /ns:	222.3 ns (P	
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns:	222.3 ns (P –	
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns:	222.3 ns (P - 413.0 ns	
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns:	222.3 ns (P - 413.0 ns 198.7 ns	1); 217.5 ns (P2)
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame:	222.3 ns (P - 413.0 ns 198.7 ns ITRF	1); 217.5 ns (P2)
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame: Latitude or X /m:	222.3 ns (P - 413.0 ns 198.7 ns ITRF -1519473.5	1); 217.5 ns (P2) 55m 47 m
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame: Latitude or X /m: Longitude or Y /m: Height or Z /m:	222.3 ns (P - 413.0 ns 198.7 ns ITRF -1519473.5 +6192910.	1); 217.5 ns (P2) 55m 47 m 4 m
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame: Latitude or X /m: Longitude or Y /m: Height or Z /m:	222.3 ns (P - 413.0 ns 198.7 ns ITRF -1519473.5 +6192910. +142837.2	1); 217.5 ns (P2) 55m 47 m 4 m
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame: Latitude or X /m: Longitude or Y /m: Height or Z /m:	222.3 ns (P – 413.0 ns 198.7 ns ITRF -1519473.5 +6192910. +142837.2 General information	1); 217.5 ns (P2) 55m 47 m 4 m
INT DLY (GPS) /ns: INT DLY (GLONASS) /ns: CAB DLY /ns: REF DLY /ns: Coordinates reference frame: Latitude or X /m: Longitude or Y /m: Height or Z /m: Rise time of the local UTC pulse	222.3 ns (P - 413.0 ns 198.7 ns ITRF -1519473.5 +6192910. +142837.2 General information 807.7 ps Yes	1); 217.5 ns (P2) 55m 47 m 4 m

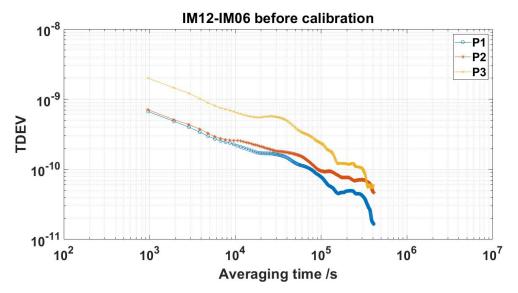
 $(55\pm10)\%$ rh

Diagram of the experiment set-up

Set humidity value and uncertainty:



Log of Events / Additional Information



Annex 4 – TDEV for CCD results at MASM

Figure 89. TDEV between IM12 and IM06 receivers at NIM before calibration

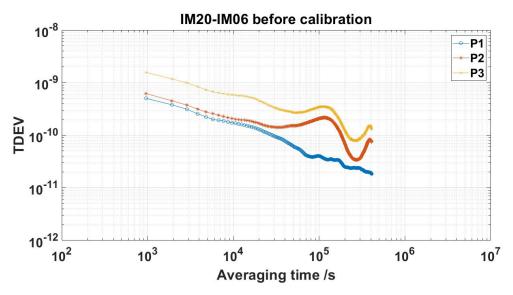


Figure 90. TDEV between IM20 and IM06 receivers at NIM before calibration

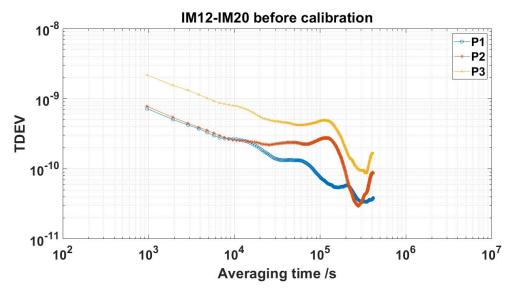


Figure 91. TDEV between IM12 and IM20 receivers at NIM before calibration

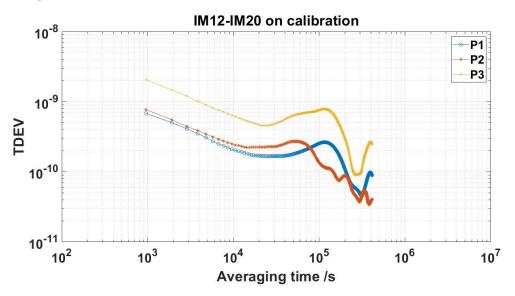
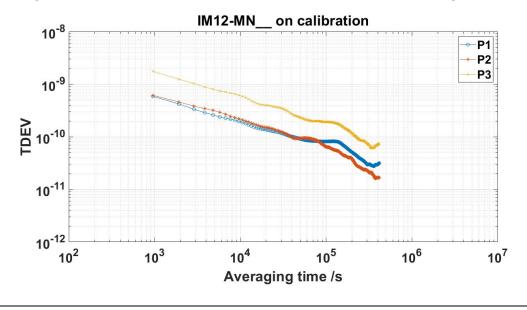


Figure 92. TDEV between IM12 and IM20 receivers at MASM during calibration



Supported by NIM

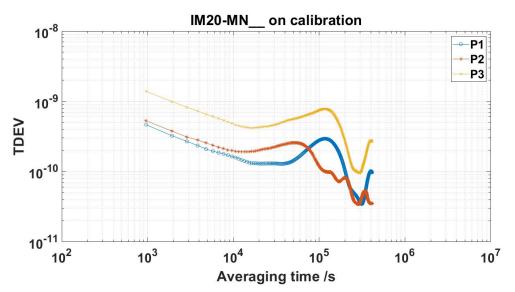


Figure 93. TDEV between IM12 and MN_ receivers at MASM during calibration



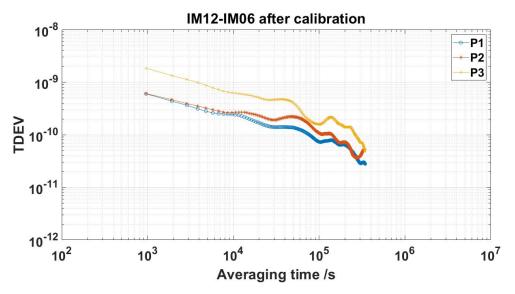


Figure 95. TDEV between IM12 and IM06 receivers at NIM after calibration

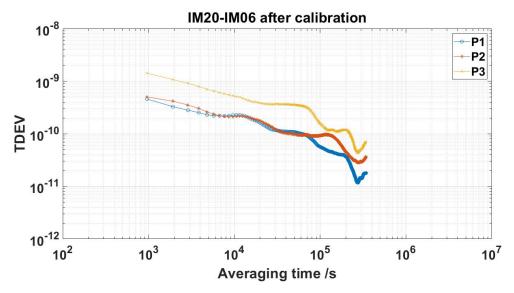


Figure 96. TDEV between IM20 and IM06 receivers at NIM after calibration

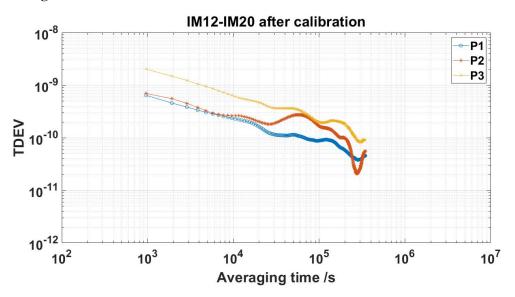
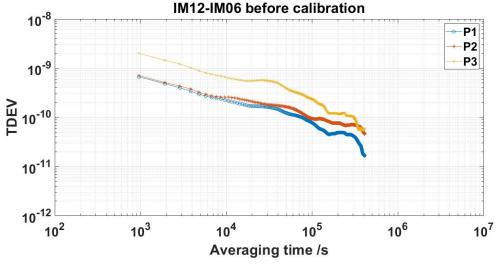


Figure 97. TDEV between IM12 and IM20 receivers at NIM after calibration



Annex 5 – TDEV for CCD results at NMC

Figure 98. TDEV between IM12 and IM06 receivers at NIM before calibration

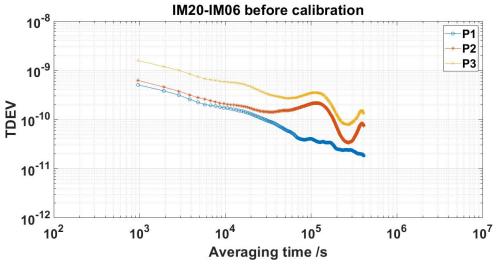


Figure 99. TDEV between IM20 and IM06 receivers at NIM before calibration

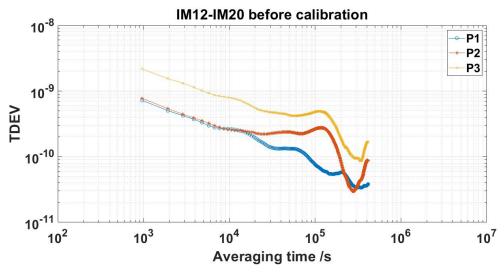


Figure 100. TDEV between IM12 and IM20 receivers at NIM before calibration

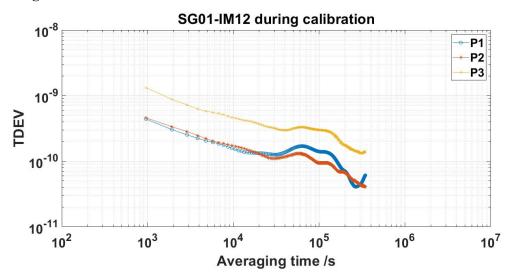


Figure 101. TDEV between SG01 and IM12 receivers at NMC on calibration

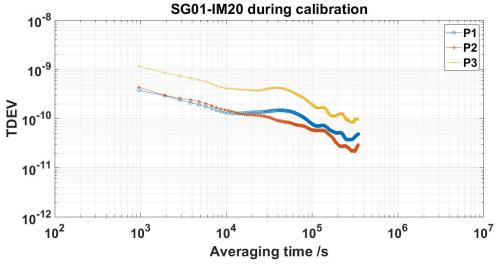


Figure 102. TDEV between SG01 and IM20 receivers at NMC on calibration

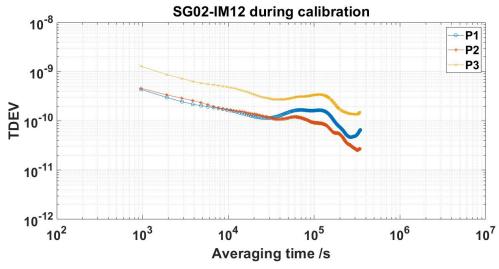


Figure 103. TDEV between SG02 and IM12 receivers at NMC on calibration

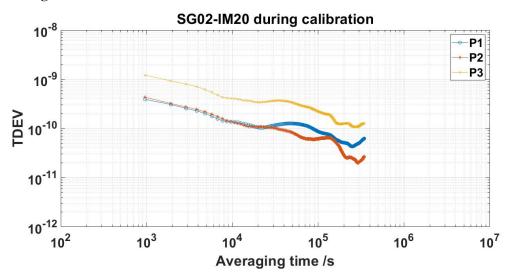


Figure 104. TDEV between SG02 and IM20 receivers at NMC on calibration

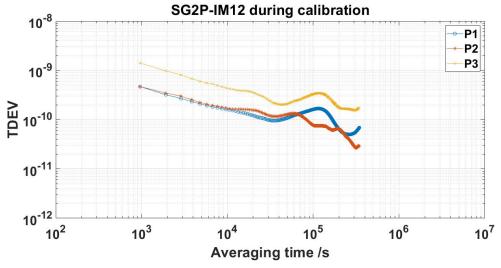


Figure 105. TDEV between SG2P and IM12 receivers at NMC on calibration

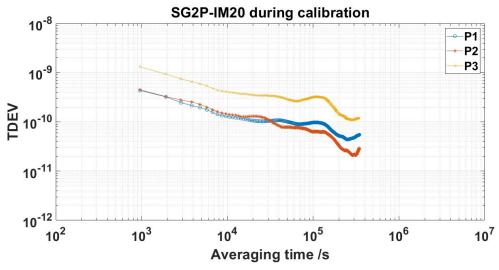


Figure 106. TDEV between SG2P and IM20 receivers at NMC on calibration

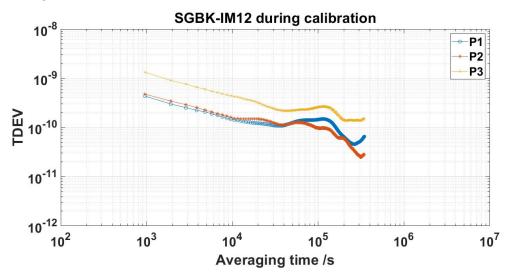


Figure 107. TDEV between SGBK and IM12 receivers at NMC on calibration

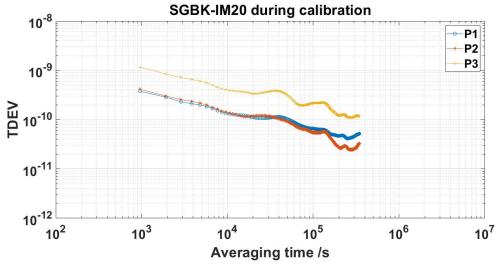


Figure 108. TDEV between SGBK and IM20 receivers at NMC on calibration

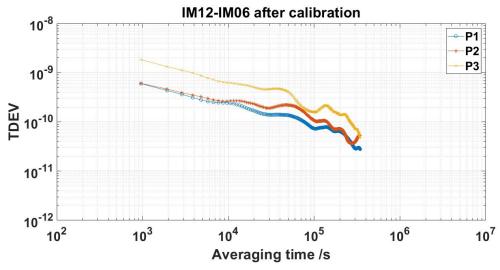


Figure 109. TDEV between IM12 and IM06 receivers at NIM after calibration

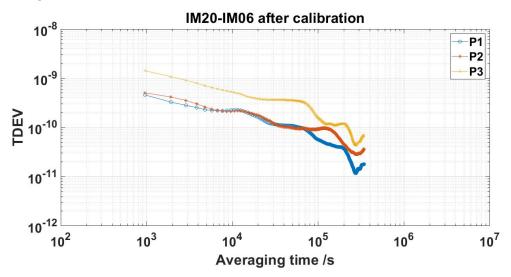


Figure 110. TDEV between IM20 and IM06 receivers at NIM after calibration

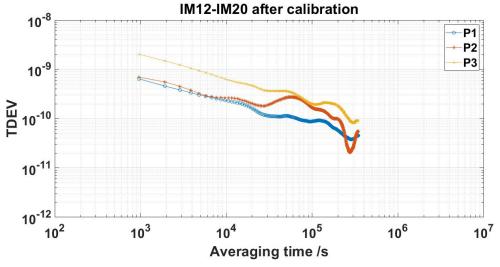


Figure 111. TDEV between IM12 and IM20 receivers at NIM after calibration