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## GNSS CALIBRATION REPORT PT15 TRANSFER CALIBRATION

Prepared by: Florian Heimbach (PTB) Time Dissemination Working Group

Authorized by: BIPM

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#### REFERENCES

	REFERENCES
RD01	2022 Group 1 GNSS calibration trip (CAL_ID 1001-2022)
RD02	BIPM guidelines for GNSS calibration, V3.0, 02/04/2015
RD03	BIPM Procedure for computing raw difference of GNSS code measurements for geodetic receivers, dclrinex software version 3.1, April 2021
RD04	J. Kouba, P. Heroux, 2002, "Precise Point Positioning Using IGS Orbit and Clock Products", GPS Solutions, Vol. 5, No. 2, 12-28
RD05	W. Lewandowski, C. Thomas, 1991, "GPS Time transfers," Proc. IEEE, Vol. 79, No. 7, 991-1000
RD06	P. Defraigne and G. Petit, "CGGTTS-Version 2E: an extended standard for GNSS time transfer", Metrologia 52 (2015) G1
RD07	D. A. Howe and N. Schlossberger, "Characterizing Frequency Stability Measurements Having Multiple Data Gaps", IEEE Transactions on Ultrasonics, Ferroelectrics, and Frequency Control, Vol. 69, No. 2 (2022)
RD08	BIPM Template for calibration report to the BIPM, V3.1, 29/08/2015



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### **ACRONYMS**

	ACRONYMS
BIPM	Bureau International des Poids et Mesures, Sèvres, France
CAB DLY	Antenna Cable Delay
CGGTTS	CCTF Generic GNSS Time Transfer Standard
DCLRINEX	Differential calibration software using the pseudoranges directly read from the
	RINEX files, software was provided by the BIPM
EURAMET	The European Association of National Metrology Institutes
IGS	International GNSS Service
INT DLY	Internal Signal Delay
GNSS	Global Navigation Satellite System
PPP	Precise Point Positioning
РТВ	Physikalisch-Technische Bundesanstalt, Braunschweig, Germany
REF DLY	Reference Delay
RINEX	Receiver Independent Exchange Format
R2CGGTTS	RINEX-to CGGTTS conversion software, provided by ORB / BIPM
TDEV	Time Deviation
тіс	Time Interval Counter



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#### RESULTS OF RAW DATA PROCESSING

#### 1.1. OVERVIEW

The raw code differences of the pairs of co-located receivers during the data acquisition period are generated using the DCLRINEX software. The stated raw calibration results are taken as the median of the raw differences. The associated uncertainties are derived from the TDEV at 50000 s. The default value of 0.1 ns is chosen if the measured TDEV is less than 0.1 ns.

Pair	Date	RAWDIF	Unc.	Code
PT15-PT13	60519 - 60528	48.97	0.1	P1
PT15-PT13	60519 - 60528	44.57	0.1	P2
PT15-PT13	60519 - 60528	49.99	0.1	C1
PT15-PT13	60519 - 60528	50.43	0.1	E1
PT15-PT13	60519 - 60528	43.56	0.1	E5a

#### Table 1-1 Summary information on the raw calibration results for GPS signals (all values in ns)



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#### 1.2. COMMON-CLOCK SET-UP IN PTB

For "CC1", PT15 was operated for 9 days at PTB. The installation of the receivers in PTB is depicted in Figure 1-1 for PPS signals and in Figure 1-2 for 5 MHz (and 10 MHz) signals.



#### Figure 1-1 UTC(PTB) reference point and 1 PPS signal distribution to PT13, PTBM, and other receivers; PD10 stands for pulse distributor, CSDA stands for clock signal distribution amplifier

A clarification may be helpful regarding the 1 PPS REF point. When measuring with a TIC the time difference between Port A = UTC(PTB), and Port B = 1 PPS REF, then the result is +2.7 ns. Figure 1-3 illustrates the installation of GNSS antennas on the roof of the PTB time laboratory (clock hall) during CC1.



Figure 1-2 UTC(PTB) signal distribution (5 MHz, 10 MHz) to PT13, PTBM, and other receivers HPDA stands for High-precision distribution amplifier (for rf frequencies)



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Figure 1-3 Installation of GNSS antennas at PTB, PT15 antenna is highlighted by the blue arrow

The period 60306 to 60528 (9 days) was chosen to determine the initial PT15 INT DLY values. The results of the comparison with PT13 as the reference are shown in Figure B-1. The figures show the raw code differences and the corresponding TDEVs. The numerical results are given in Table 1-1.



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## 2. CALIBRATION RESULTS

#### 2.1. PT15 WITH RESPECT TO THE REFERENCE SYSTEM

Pair	Date	$\text{REF}~\text{DLY}_{\text{V}}$	REF DLY <sub>G</sub>	RAW DIF	$\Delta SYS DLY_{V-G}$	Code
PT15-PT13	60519 - 60528	10.98	56.2	48.97	3.75	P1
PT15-PT13	60519 - 60528	10.98	56.2	44.57	-0.65	P2
PT15-PT13	60519 - 60528	10.98	56.2	49.99	4.77	C1
PT15-PT13	60519 - 60528	10.98	56.2	50.43	5.21	P1
PT15-PT13	60519 - 60528	10.98	56.2	43.56	-1.66	P2

Table 2-1 Calibration results T vs. G (all values in ns)



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#### 2.2. INT DLY UNCERTAINTY EVALUATION

#### Table 2-2 Uncertainty contributions for the calibration of receiver delays (GPS), all values in ns

	Uncertainty	Value f1	Value f2	Value f1-f2	Value f3	Description			
1	u <sub>a</sub> (PTB)	0.1	0.1	0.14		CC measurement uncertainty at PTB, TDEV max.			
2	u <sub>a</sub> (GPS)	0.1	0.1	0.14	0.24				
Systematic components due to antenna installation									
3	U <sub>b,11</sub>	0.2	0.2	0	0.20	Multipath at PTB			
4	U <sub>b,12</sub>	0.1	0.1	0.14	0.28	Position error at PTB			
		Inst	allation o	of PTBM and	d visited	receivers			
5	U <sub>b,21</sub>	0.2	0.2	0	0.20	Connection of PT15 to UTC(PTB) (REF DLY)			
6	U <sub>b,24</sub>	0.1	0.1	0	0.10	TIC nonlinearities at PTB			
			Ar	ntenna cabl	e delay				
7	u <sub>b,31</sub> (PTB)	0.5	0.5	0	0.50	Uncertainty estimation for the PTBM CAB DLY when installed at PTB			
	Total								
8	u <sub>b,INT</sub> (GPS)	0.77	0.77	0.32	0.91				
9	u <sub>CAL,0</sub> (GPS)				0.95				

#### Table 2-3 Uncertainty contributions for the calibration of receiver delays (Galileo), all values in ns

	Uncertainty	Value f1	Value f2	Value f1-f2	Value f3	Description			
1	u <sub>a</sub> (PTB)	0.1	0.1	0.14		CC measurement uncertainty at PTB, TDEV max.			
2	ua (Galileo)	0.1	0.1	0.14	0.24				
	Systematic components due to antenna installation								
3	U <sub>b,11</sub>	0.2	0.2	0	0.20	Multipath at PTB			
4	U <sub>b,12</sub>	0.1	0.1	0.14	0.28				
		Inst	allation o	of PTBM and	d visited	receivers			
5	U <sub>b,21</sub>	0.2	0.2	0	0.20	Connection of PT15 to UTC(PTB) (REF DLY)			
6	U <sub>b,24</sub>	0.1	0.1	0	0.10	TIC nonlinearities at PTB			
		-	Ar	ntenna cabl	e delay	-			
7	u <sub>b,31</sub> (PTB)	0.5	0.5	0	0.50	Uncertainty estimation for the PTBM CAB DLY when installed at PTB			
	Total								
8	u <sub>b,INT</sub> (Galileo)	0.78	0.78	0.35	0.89				
9	u <sub>CAL,0</sub> (Galileo)				0.92				



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#### **3. FINAL RESULTS FOR PT15**

The results of the calibration are summarized in Table 3-1. INT DLY values for the golden reference receiver PT13 were determined in 2021 [RD01]. The uncertainty values are taken from Table 2-2. The final INT DLY values are listed in Table 2-1.

Reference system	Cal_Id	Date		INT DLY	Code
PT13	1001-2022	60054		30.96	P1
PT13	1001-2022	60054		28.50	P2
PT13	1001-2022	60054		33.60	C1
PT13	1001-2022	60054		33.19	E1
PT13	1001-2022	60054		33.05	E5a
Visited system	Cal_Id	Date	u <sub>CAL</sub> (P3)	INT DLY	Code
PT15	1001-2022	60529	0.9	34.9	P1
PT15	1001-2022	60529	0.9	28.1	P2
PT15	1001-2022	60529	0.9	38.6	C1
PT15	1001-2022	60529	0.9	38.6	E1
PT15	1001-2022	60529	0.9	31.6	E5a

Table 3	3-1	Summarv	of final	results	for GPS	links, a	II values	in ns
i ubic i	-	Samary	or mua	i courto	101 01 0		iii values	

#### **ANNEXES**

ANNEX A: BIPM CALIBRATIOIN INFORMATION SHEETS ANNEX B: PLOTS OF RAW DATA AND TDEV ANALYSIS



## . ANNEX A: BIPM CALIBRATION INFORMATION SHEETS

## **Common clock measurement at PTB**

Laboratory:	РТВ					
Date and hour of the beginning of	2022-03-19 0:00 UTC (MJD 59657)					
Date and hour of the end of		2022-03-24 24:00 UTC (MJD 59662)				
Information on the system						
	Refer	ence:	DU	DUT:		
4-character BIPM code	PT13		PT1	15		
Receiver maker and type:	PolaR>	(5TR (5.2.0)	GTF	₹55		
Receiver serial number:	S/N 47	70 1292	231	.2001		
1 PPS trigger level /V:	1		1			
Antenna cable maker and type: Phase stabilised cable (Y/N):	ECOFL	EX 15plus	LMF	२-400		
Length outside the building /m:	approx	<. 25	Арр	prox.25		
Antenna maker and type: Antenna serial number:	LEICA 72633	AR25 3, Calib Geo++ 18.08.20	NO 15 NM	V850 LK22480015P		
Temperature (if stabilised) /°C						
Measured delays /ns						
	Refer	ence:		DUT:		
Delay from local UTC to receiver 1 PPS-in (X <sub>P</sub> ) / ns	9.59 ±	± 0.1 (#)		10.98		
Delay from 1 PPS-in to internal Reference (if different): (X <sub>0</sub> ) / ns	46.63	± 0.1 (#)		NA		
Antenna cable delay: (X <sub>C</sub> ) / ns	205.7		205	205.5		
Splitter delay (if any):	N/A	NA		4		
Data used for the generation of <b>C</b>	GGTT	S files				
		Reference:		DUT		
$\Box$ INT DLY (or X <sub>R</sub> +X <sub>S</sub> ) (GPS) /ns:		30.96 (P1), 28.5 (P2), 33.6 (C1) (*)		0.0 for all		
□ INT DLY (or X <sub>R</sub> +X <sub>S</sub> ) (GALILEO) /n	s:	33.19 (E1), 33.05 (E5a) (*)		0.0 (E1) 0.0 (E5a)		
$\Box$ INT DLY (or X <sub>R</sub> +X <sub>S</sub> ) (GLONASS) /r	าร:					
$\Box$ CAB DLY (or X <sub>c</sub> ) /ns:		205.7		208.7		
$\Box$ REF DLY (or X <sub>P</sub> +X <sub>0</sub> ) /ns:		56.2		44.3		
Coordinates reference frame:		ITRF (*)		ITRF		
X /m:		+3844059.86 (***)		+ 3844063.42 (**)		
Y /m:		+709661.56 (***)	Mast P10	+ 709658.80 (**)		
Z /m	+5023129.87 (***)	. 10	+ 5023127.41 (**)			
General information						
□ Rise time of the local UTC pulse:		3 ns				
☐ Is the laboratory air conditioned:	Yes					



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Set temperature value and uncertainty: 23.0 °C, peakt-to-peak variations 0.3° C

Notes:

(#) Local measurements repeated on occasion of campaign 1001-2020.

(\*) values based on G1 calib 1001-2022 [RD01]

(\*\*) APC determined using NRCan PPP free software [RD03]

(\*\*\*) values provided by BIPM via Mail 2019-08-07



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#### ANNEX B: PLOTS OF RAW DATA AND TDEV ANALYSIS



Figure B-1 Left: Raw code differences between V and G for GPS signals during CC1,  $\Delta$ P1 (blue) and  $\Delta$ P2 (red) Right: TDEV of the raw code differences.



Figure B-2 Left: Left: Raw code differences between V and G for GPS signals,  $\Delta$ C1 (blue) and  $\Delta$ PC (red) Right: TDEV of the raw code differences.



Figure B-3 Left: Left: Raw code differences between V and G for Galileo signals,  $\Delta$ E1 (green) and  $\Delta$ E5 (orange) Right: TDEV of the raw code differences.



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Figure B-4 Left: Left: Raw code differences between V and G for GLONASS signals,  $\Delta D1/C1$  (green) and  $\Delta D2/C2$  (purple) Right: TDEV of the raw code differences.



Figure B-5 Left: Left: Raw code differences between V and G for GLONASS signals,  $\Delta R1/P1$  (blue) and  $\Delta R2/P2$  (red) Right: TDEV of the raw code differences.



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