

FREQUENCY COMPARISON (H_MASER 140 0809) - (LNE-SYRTE-FO2Rb) For the period MJD 59029 to MJD 59059

The secondary frequency standard LNE-SYRTE-FO2Rb has been compared to the hydrogen Maser 140 0809 of the laboratory, during a measurement campaign between MJD 59029 and 59059 (29^{th} June 2020 – 29^{th} July 2020). The fountain operation covered 95.1 % of the period.

The mean frequency difference at the middle date of the period is given in the following table:

59029 - 59059 59044 -366.1 2.0 2.5 0.6 0.0 6	Period (MJD)	Date of the estimation	y(HMaser140 0809 – FO2Rb)	UA	uB	u _{A/lab}	u _{B/lab}	USecRep
	59029 - 59059	59044	-366.1	2.0	2.5	0.6	0.0	6

Table 1: Results of the comparison in 1×10^{-16} .

The calibration is made using the recommended value for the ⁸⁷Rb secondary representation: 6 834 682 610.904 312 6 Hz (21st CCTF in 2017).

u_B is the ⁸⁷Rb fountain type B uncertainty.

u_{SecRep} is the recommended uncertainty of the secondary representation (21st CCTF in 2017).

During the period, the interrogating signal of the FO2-Rb fountain was based on the multiplication of a 1 GHz signal provided by a cryogenic oscillator phase locked to the maser 140 0809. A synthesizer is used to lock the microwave signal to the atomic resonance. The frequency difference between this maser and the fountain is deduced from the average correction applied to the synthesizer.

Average value and statistical uncertainty

The frequency data are averaged over 0.2 day intervals. We then perform a linear unweighted fit to the average data points to determine the average frequency at the middle date of the period, as given in Table 1. The statistical uncertainty u_A is estimated using the Allan variance of the frequency residuals, after removing the drift. We estimate a conservative statistical uncertainty u_A of 2.0×10^{-16} .

We verified the result by applying a second method. We calculated the accumulated phase by integrating the data points, assuming a constant frequency during each segment, and during the dead times of the fountain operation. The average frequency is then obtained by dividing the total accumulated phase by the calibration period duration. The processing has been performed with segments of 0.01, 0.1 and 1 day duration. The results are in agreement with the values given in Table 1 within 0.5×10^{-16} , which is consistent with the estimation of the statistical uncertainty u_A and the uncertainty due to the link.

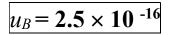
Accuracy

The frequency is corrected from the quadratic Zeeman, the black body radiation, the cold collision (+ cavity pulling), the distributed cavity phase shift and the microwave lensing shifts, and at last the redshift. The cold collision (+ cavity pulling) correction is based on alternating measurements at full density for 50 cycles and at half density for 100 cycles, by changing the state selection frequency and readjusting the microwave power to keep the selection transition probability at maximum. The uncertainty in this correction is mostly statistical. The following table summarizes the budget of the systematic corrections and their associated uncertainties. The accuracy is the quadratic sum of all the systematic uncertainties.

	Correction (10 ⁻¹⁶)	Uncertainty (10 ⁻¹⁶)
Quadratic Zeeman effect	-3503.57	0.70
Black body radiation	127.29	1.45
Cold collisions + cavity pulling	1.83	0.95
Distributed cavity phase shift	-0.35	1.00
Microwave lensing	-0.70	0.70
Microwave spectral purity&leakage	0	< 0.50
Ramsey & Rabi pulling	0	<0.10
Second order Doppler effect	0	< 0.10
Background gas collisions	0	<1.00
Total	-3375.50	2.50
Redshift	- 65.45	0.25
Total with redshift	-3440.95	2.51

 Table 2: Budget of systematic effects and uncertainties for SYRTE-FO2Rb fountain

 for the MJD 59029– 59059 period



Uncertainty of the link

The statistical uncertainty of the link $u_{A/lab}$ is the quadratic sum of 2 terms:

-A possible effect of phase fluctuations introduced by the cables that connect the frequency standard to the maser. A new characterization of the signal distribution leads to a still conservative value of 0.5×10^{-16} .

-The uncertainty due to the dead times of the frequency comparison.

We have updated the estimation of this contribution, applying the method described in *Metrologia*, vol. 44, pp 91-96, 2007, as we did for the initial calibration reports of the LNE-SYRTE Strontium SFS. The maser noise model includes a white frequency noise component of 5×10^{-16} at 1 d and a flicker frequency noise component of 5×10^{-16} at 1 d and a flicker frequency noise component of 5×10^{-16} at 1 d and a flicker frequency noise component of 5×10^{-16} at 1 d and a flicker frequency noise component of 5×10^{-16} at 1 d, which is pessimistic especially for short averaging periods. We applied the method to the dead times longer than 600 s and obtained a stability degradation of 0.3×10^{-16} .

In the signal distribution chain between the maser and the fountain, all the intermediate oscillators are phase locked using proportional/integrator phase lock loops. The comparison between the maser and UTC(OP) is performed using a time interval counter. Therefore, the systematic uncertainty of the link $u_{B/lab}$ is expected to be negligible.